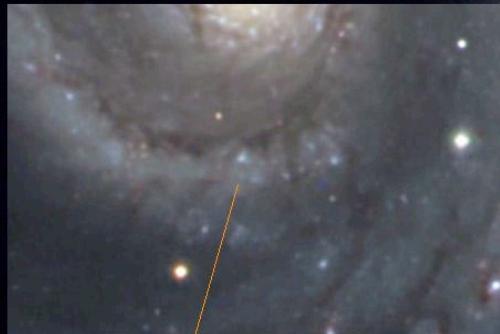


Supernovae Part 4

Numerical Modelling

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Physics Department
University of Basel



MAY 8th
2005

SN2005CS

- Discretisation of time evolution
- Diffusivity from discrete space
- Solving the Boltzmann equ.
- 3D MHD
- Approximations for v -transport

Computer Representation of Equations



Equation to be solved:

$$\frac{\partial y}{\partial t} = f(y)$$

Euler forward differencing:

$$\frac{y(t + \Delta t) - y(t)}{\Delta t} = f(y(t))$$

Euler backward differencing:

$$\frac{y(t + \Delta t) - y(t)}{\Delta t} = f(y(t + \Delta t))$$

Simple & fast!

Stable & expensive!

(--> implicit demo)

Finite differencing of time evolution



Forward differencing:
evaluate slope with
current state vector

Backw. differencing:
evaluate slope with
future state

Let's see...

Explicit finite differencing



Forward differencing:
evaluate slope with
current state vector

- simple
- accurate for small time steps
- limited by characteristic time scale

Go faster...

Explicit finite differencing



Forward differencing:
evaluate slope with
current state vector

- simple
- inaccurate for large time steps
- even catastrophic!

Think...

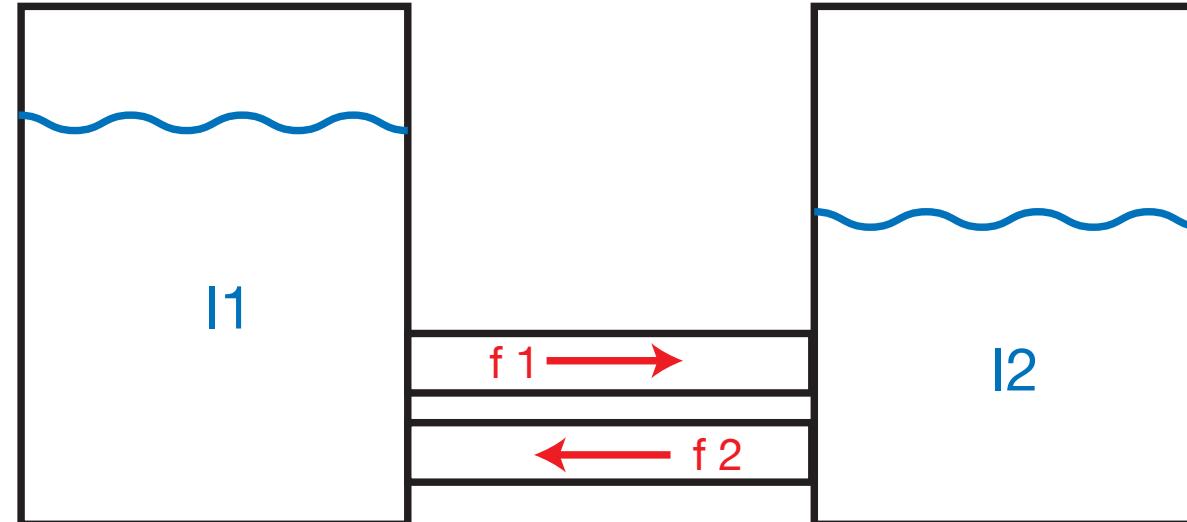
Implicit finite differencing



Backw. differencing:
evaluate slope with
future state vector

- Long time steps possible
- Follows ‘average’ evolution
- nonlinear system
- computationally expensive!

Finite Differencing in Time



Explicit finite differencing restricts time step to fastest process, $\Delta t < \tau$

Implicit FD is unconditionally stable

Analytical solution: x decays exponentially with time

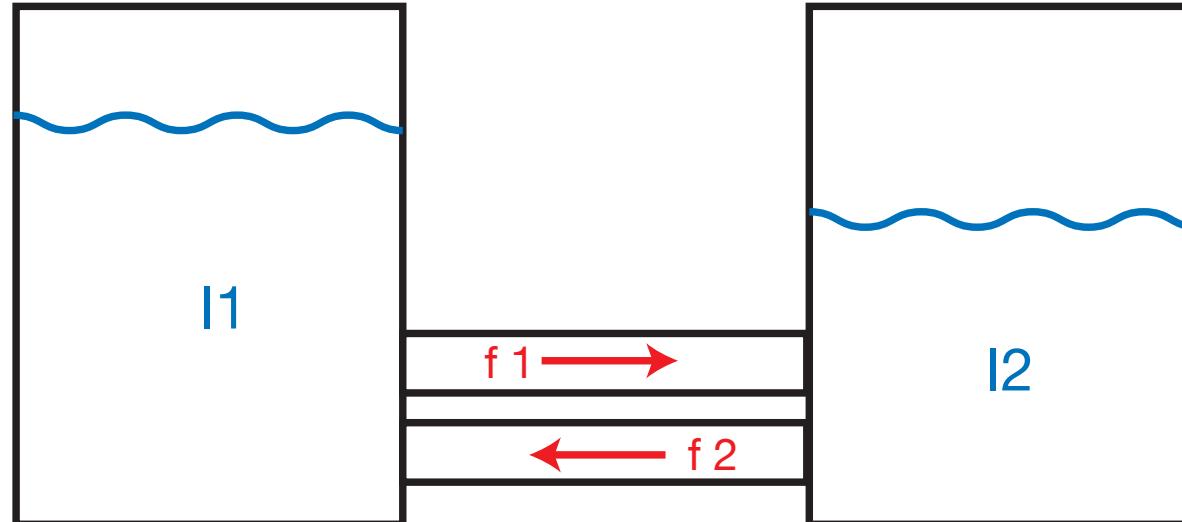
← explicit FD

← implicit FD

$$\frac{\partial \bar{I}_1}{\partial t} = - \frac{\bar{I}_1}{\tau} + \frac{\bar{I}_2}{\tau} = - \frac{\bar{I}_1 - \bar{I}_2}{\tau}$$

$$\frac{\partial \bar{I}_2}{\partial t} = + \frac{\bar{I}_1}{\tau} - \frac{\bar{I}_2}{\tau} = + \frac{\bar{I}_1 - \bar{I}_2}{\tau}$$

Finite Differencing in Time



Explicit finite differencing restricts time step to fastest process, $\Delta t < \tau$

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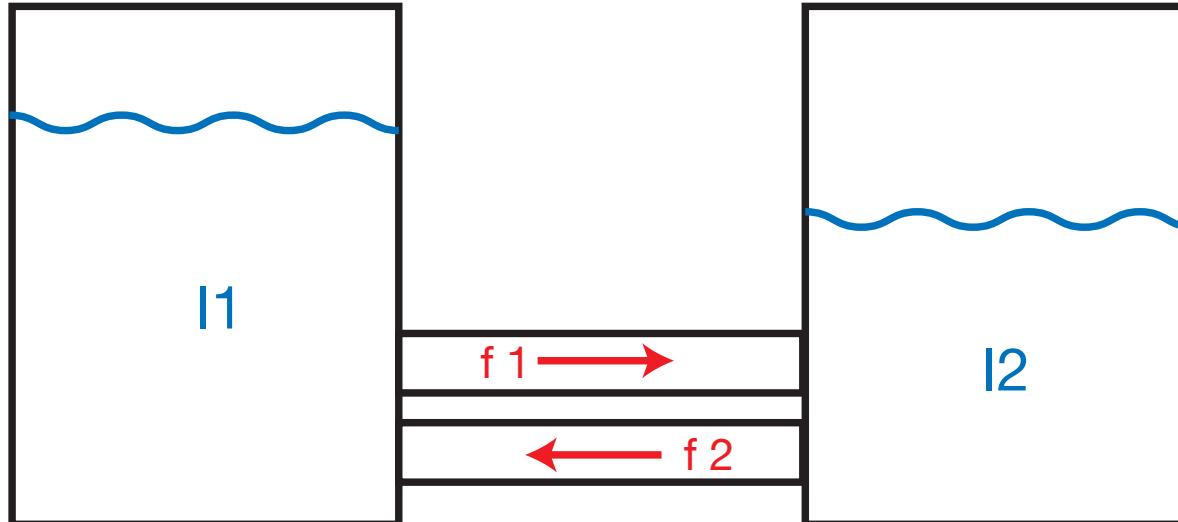
$$\left. \begin{aligned} \frac{\partial \bar{I}_1}{\partial t} &= - \frac{\bar{I}_1}{\tau} + \frac{\bar{I}_2}{\tau} = - \frac{\bar{I}_1 - \bar{I}_2}{\tau} \\ \frac{\partial \bar{I}_2}{\partial t} &= + \frac{\bar{I}_1}{\tau} - \frac{\bar{I}_2}{\tau} = + \frac{\bar{I}_1 - \bar{I}_2}{\tau} \end{aligned} \right\} \quad \begin{aligned} \frac{\partial}{\partial t} (\bar{I}_1 + \bar{I}_2) &= 0 \\ \frac{\partial}{\partial t} (\bar{I}_1 - \bar{I}_2) &= - \frac{2}{\tau} (\bar{I}_1 - \bar{I}_2) \end{aligned}$$

Analytical solution: x decays exponentially with time

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$$\left. \begin{aligned} \frac{\partial I_1}{\partial t} &= - \frac{I_1}{\tau} + \frac{I_2}{\tau} = - \frac{I_1 - I_2}{\tau} \\ \frac{\partial I_2}{\partial t} &= + \frac{I_1}{\tau} - \frac{I_2}{\tau} = + \frac{I_1 - I_2}{\tau} \end{aligned} \right\} \quad \begin{aligned} \frac{\partial}{\partial t} (I_1 + I_2) &= 0 \\ \frac{\partial}{\partial t} (I_1 - I_2) &= - \frac{2}{\tau} (I_1 - I_2) \end{aligned}$$

$$x := I_1 - I_2 \Rightarrow \frac{x^{n+1} - x^n}{\Delta t} = - \frac{2}{\tau} x^n \Rightarrow \left| \frac{x^{n+1}}{x^n} \right| > 1 \text{ if } \Delta t > \tau$$

$$\frac{x^{n+1} - x^n}{\Delta t} = - \frac{2}{\tau} x^{n+1} \Rightarrow \left| \frac{x^{n+1}}{x^n} \right| < 1 \quad \checkmark$$

Finite Differencing in Space

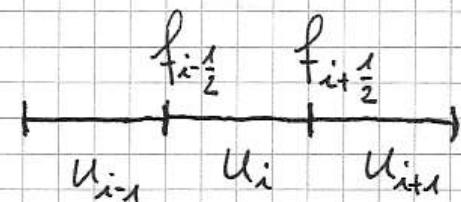
$u(t, x)$... function of time and space

$a = \text{const.}$... advection speed

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(au) = 0$$

Discretisation

$$(*) \quad \frac{u_i^{n+1} - u_i^n}{\Delta t} + \frac{f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}}}{\Delta x} = 0$$



Finite Differencing in Space

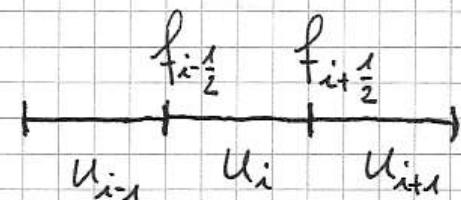
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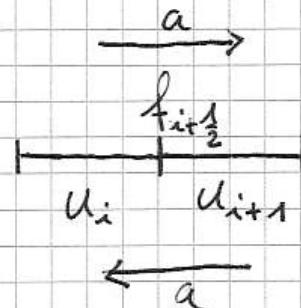
Naive choice of fluxe on cell-interfaces

$$f_{i+\frac{1}{2}} = a \frac{1}{2}(u_{i+1} + u_i)$$

accurate, but
not stable!

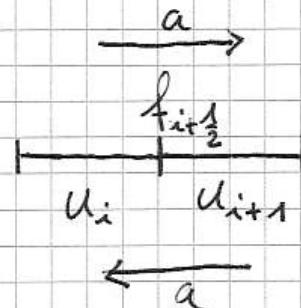
Upwind Differencing

$$f_{i+\frac{1}{2}} = \begin{cases} au_i & \text{if } a > 0 \\ au_{i+1} & \text{if } a \leq 0 \end{cases}$$



Upwind Differencing

$$f_{i+\frac{1}{2}} = \begin{cases} au_i & \text{if } a > 0 \\ a u_{i+1} & \text{if } a \leq 0 \end{cases}$$



Same f written differently:

$$f_{i+\frac{1}{2}} = a \frac{1}{2} (u_{i+1} + u_i) - |a| \frac{1}{2} (u_{i+1} - u_i)$$

accurate
choice

stabilising
correction

Artificial Diffusivity

Insert into equation (*)

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} + a \frac{\frac{1}{2}(u_{i+1}^n + u_i^n) - \frac{1}{2}(u_i^n + u_{i-1}^n)}{\Delta x} - |a| \frac{\frac{1}{2}(u_{i+1}^n - u_i^n) - \frac{1}{2}(u_i^n - u_{i-1}^n)}{\Delta x} = 0$$

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} + a \frac{u_{i+1}^n - u_{i-1}^n}{2 \Delta x} - \underbrace{|a| \Delta x}_{2} \cdot \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2} = 0$$

2nd order accurate

diffusivity depending on
advection speed and resolution

Important to compare numerical diffusivity with physical diffusivity!

Implement Conservation Laws!



If the resolution/
diffusivity cannot
meet the physical
requirements?

-> Conservation laws
make errors local
and set bounds to
their size.

-> Always guarantee
that finite differenced
equations guarantee
conservation laws!

Implement Conservation Laws!



Conservation laws:

- Baryon number
- Lepton number
- Energy
- Momentum
- Magnetic flux

Conditions:

- Nuclear statistical equilibrium (NSE)
- Charge neutrality
- Detailed balance
- $\text{div}(B) = 0$

Conservation laws are for computational physicists what ropes are for the rock climber: First you think you can survive by just being careful,...

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diffusivity cannot
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-> Always guarantee
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Implement Conservation Laws!



... but in astrophysics you always meet the situation where they are indispensable!

If the resolution/
diffusivity cannot
meet the physical
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-> Conservation laws
make errors local
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their size.

-> Always guarantee
that finite differenced
equations guarantee
conservation laws!

Physics <-> Model <-> Observation

Physics

Challenges

Reaction network

- uncertainties
- stiff partial diff'eqs.

Magneto-hydrodynamics

- resolution
- time scales

Gravity

- NR: elliptic equations
- GR: metric/horizons

Radiative transfer

- dimensionality
- non-locality

Astrophysical
modelling:

local

semi-local

non-local

Modeling: hydrodynamics

Metric in spherical symmetry:

$$ds^2 = -\alpha^2 dt^2 + \left(\frac{r'}{\Gamma}\right)^2 da^2 + r^2(d\vartheta^2 + \sin^2\vartheta d\varphi^2), \quad (1)$$

Stress-energy tensor:

$$T^{tt} = \rho(1 + e + J),$$

$$T^{ta} = T^{at} = \rho H,$$

$$T^{aa} = p + \rho K,$$

$$T^{\vartheta\vartheta} = T^{\varphi\varphi} = p + \frac{1}{2}\rho(J - K). \quad (2)$$

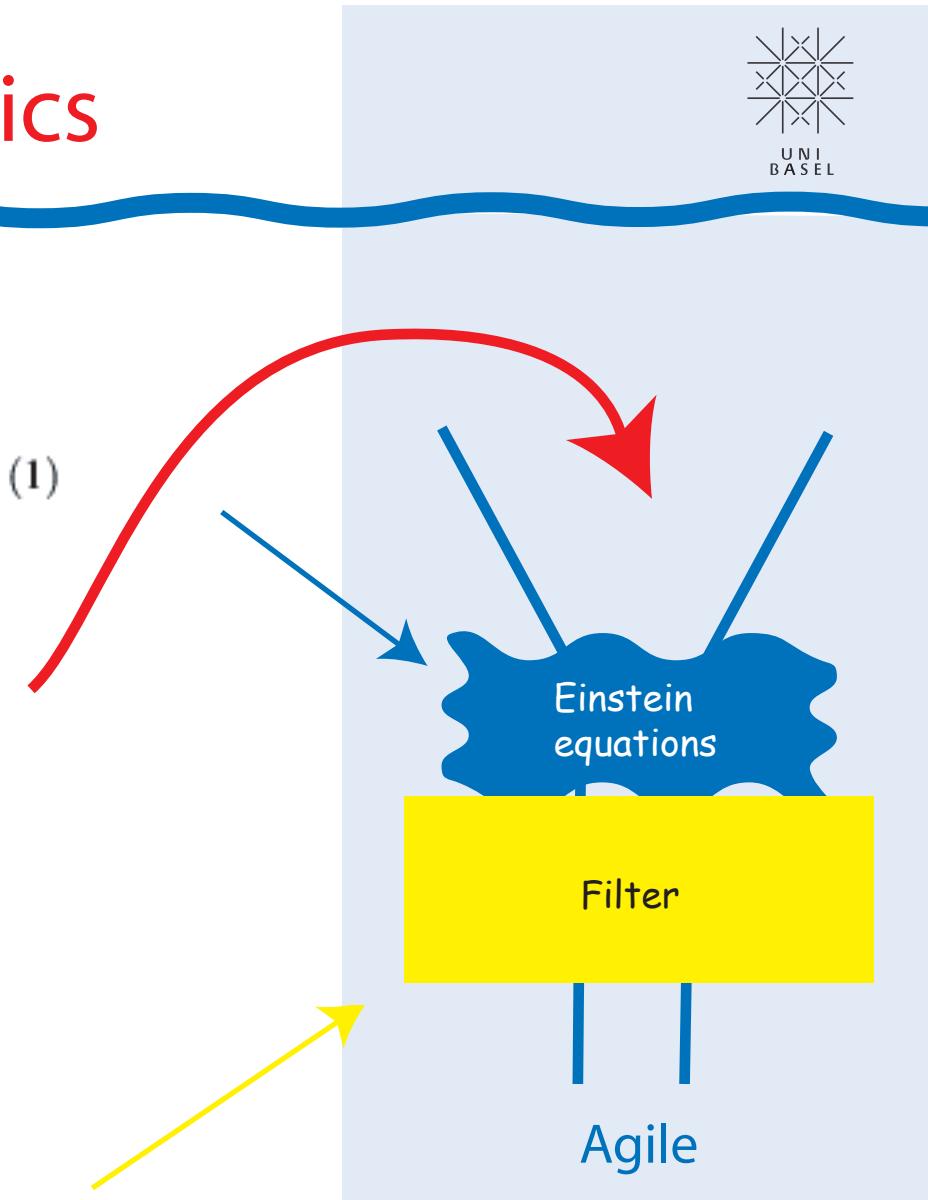
Conservation quantities:

$$\frac{1}{D} = \frac{\Gamma}{\rho}, \quad (3)$$

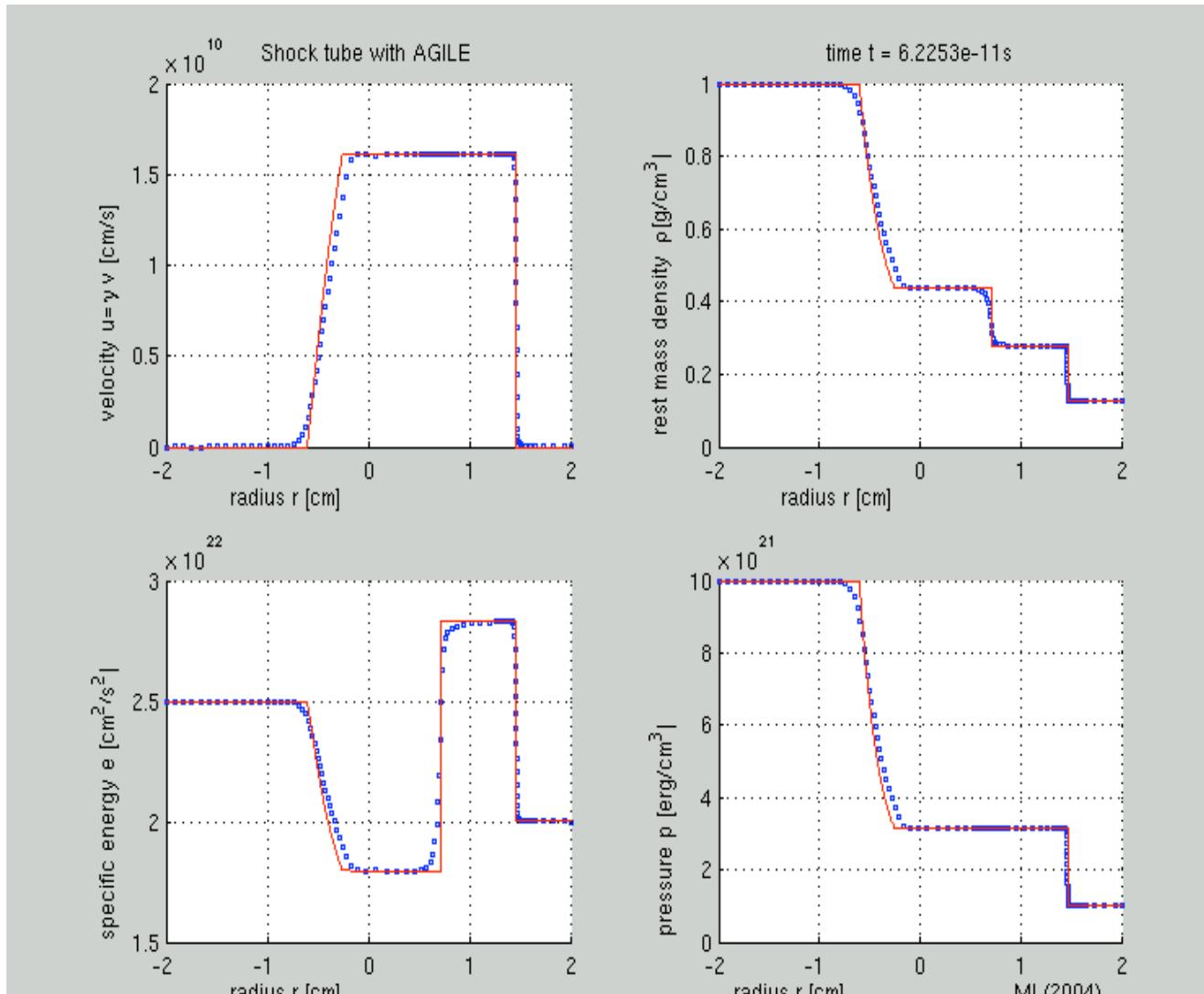
$$\tau = \Gamma(e + J) + \frac{2}{\Gamma + 1} \left(\frac{1}{2} u^2 - \frac{m}{r} \right) + uH, \quad (4)$$

$$\frac{\partial}{\partial t} \left(\frac{1}{D} \right) = \frac{\partial}{\partial a} (4\pi r^2 \alpha u), \quad (6)$$

$$\frac{\partial \tau}{\partial t} = -\frac{\partial}{\partial a} [4\pi r^2 \alpha (up + u\rho K + \Gamma \rho H)], \quad (7)$$



Hydrodynamics: Adaptive Mesh Refinement



AGILE:

- general relativistic hydrodynamics
- concentric shells
- adaptive mesh
- 2nd order TVD
- fully implicit

Methods of neutrino transport



Multi-Group Flux-Limited Diffusion (MGFLD)

- solution of one equation for $f(t,r,E)$
- flux limiter required
- flux factor by geometric estimate
- no characteristics

(Arnett 1966, Myra & Bludman 1989, Bruenn 1985/2001)

- + efficient
- + accurate @ opaque
- ad hoc @ transparent
- multi-D extension?

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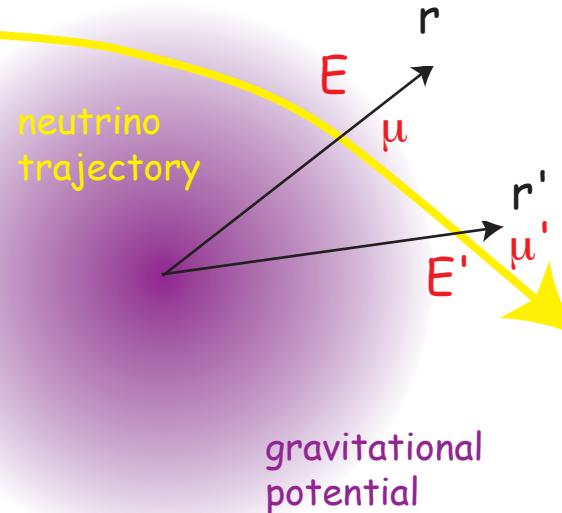
(Wilson 1971, Mezzacappa & Bruenn 1993,
Liebendörfer et al. 2001/2004, Sumiyoshi et al. 2005)

- + efficient
- + accurate @ opaque
- ad hoc @ transparent
- multi-D extension?

- + comprehensive
- + local (adaptive)
- expectation values
- angular resolution

Spherical Boltzmann transport

energy @ infinity
 ε
 b impact parameter



$$b = r \frac{\sqrt{1 - \mu^2}}{\Gamma + u\mu}$$

$$\varepsilon = (\Gamma + u\mu)E.$$

distribution function $f(t, r, \ell, \varepsilon)$

$$\frac{\partial f}{\partial t} + \mu \Gamma \frac{\partial f}{\partial r} \approx \Omega(f)$$

(comoving frame --> Lindquist, Ann. Phys. 1966)

Comoving metric:

$$ds^2 = -\alpha^2 dt^2 + \left(\frac{1}{\Gamma} \frac{\partial r}{\partial a} \right)^2 + r^2 (d\vartheta^2 + \sin^2 \vartheta d\varphi^2)$$

Stress-energy tensor:

$$\begin{aligned} T^{tt} &= \rho(1+e+J) \\ T^{ta} = T^{at} &= \rho H \\ T^{aa} &= p + \rho K \\ T^{\vartheta\vartheta} = T^{\varphi\varphi} &= p + \frac{1}{2}\rho(J-K) \end{aligned}$$

Radiation moments:

$$\begin{aligned} J &= \frac{4\pi}{(hc)^3} \int F d\mu E^2 dE \\ H &= \frac{4\pi}{(hc)^3} \int F \mu d\mu E^2 dE \\ K &= \frac{4\pi}{(hc)^3} \int F \mu^2 d\mu E^2 dE \end{aligned}$$

Solving the Boltzmann equation

$$\frac{\partial F}{\alpha c \partial t} + \frac{\partial (4\pi r^2 \alpha \rho \mu F)}{\alpha \partial m} .$$

$$= \frac{j}{\rho} - \tilde{\chi} F$$

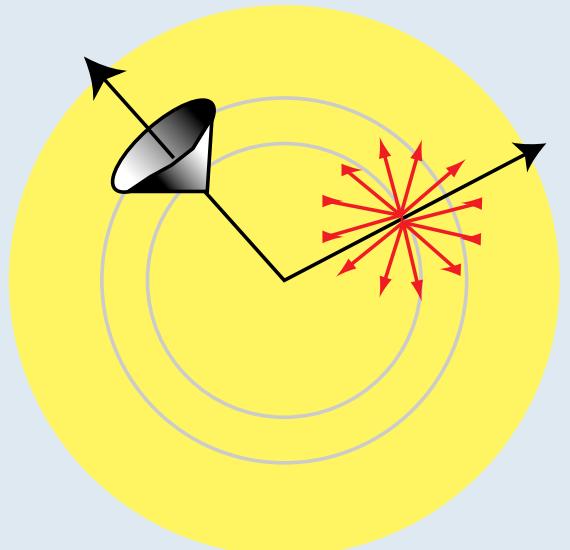
$$\frac{\partial Y_e}{\partial t} = -\frac{2\pi m_B}{h^3 c^2} \int E^2 dE d\mu \left(\frac{j}{\rho} - \tilde{\chi} F \right) \quad \frac{\partial e}{\partial t} = \dots \quad \frac{\partial u}{\partial t} = \dots$$

(Mezzacappa & Bruenn 1993, Liebendörfer 2000, Liebendörfer et al. 2004)

Evolution of specific neutrino distr. function:

$$F(t,m,\mu,E) = f(t,r,\mu,E)/\rho$$

=> 3D implicit problem



Solving the Boltzmann equation

$$\frac{\partial F}{\alpha c \partial t} + \frac{\partial (4\pi r^2 \alpha \rho \mu F)}{\alpha \partial m} .$$

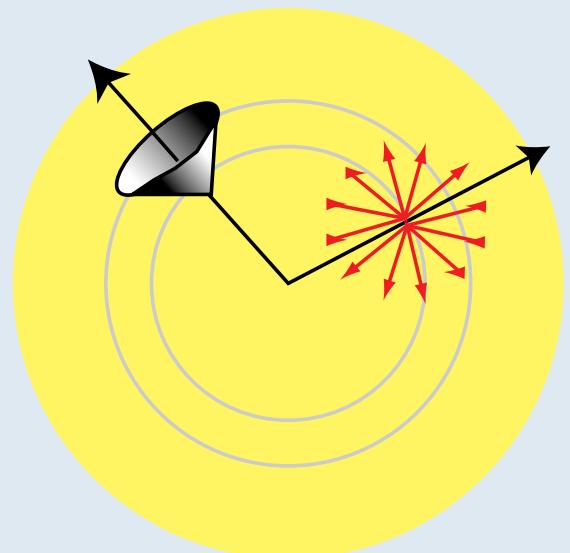
$$= \frac{j}{\rho} - \tilde{\chi}F + \frac{1}{h^3 c^4} E^2 \int d\mu' R_{is}(\mu, \mu', E) F(\mu', E) \\ - \frac{1}{h^3 c^4} E^2 F \int d\mu' R_{is}(\mu, \mu', E) \\ + \frac{1}{h^3 c^4} \left[\frac{1}{\rho} - F(\mu, E) \right] \int E'^2 dE' d\mu' \tilde{R}_{nes}^{in}(\mu, \mu', E, E') F(\mu', E) \\ - \frac{1}{h^3 c^4} F(\mu, E) \int E'^2 dE' d\mu' \tilde{R}_{nes}^{out}(\mu, \mu', E, E') \left[\frac{1}{\rho} - F(\mu', E') \right]$$

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(Mezzacappa & Bruenn 1993, Liebendörfer 2000, Liebendörfer et al. 2004)

Solving the Boltzmann equation

$$\frac{\partial F}{\alpha c \partial t} + \frac{\partial (4\pi r^2 \alpha \rho \mu F)}{\alpha \partial m} + \Gamma \left(\frac{1}{r} - \frac{\partial \alpha}{\alpha \partial r} \right) \frac{\partial [(1 - \mu^2) F]}{\partial \mu}$$

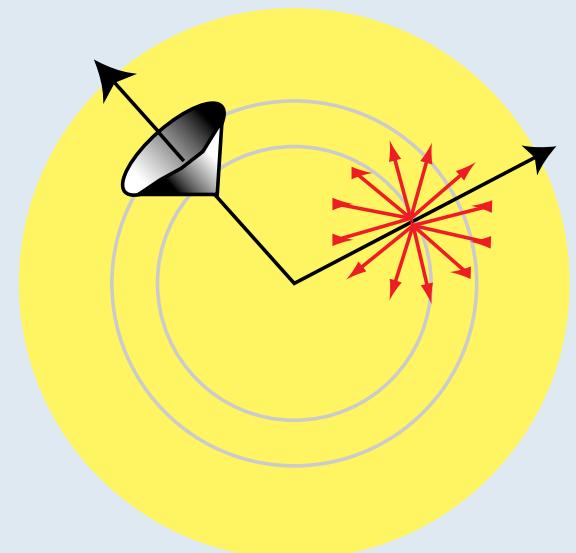
$$\begin{aligned}
 &+ \left[\dots - \mu \Gamma \frac{\partial \alpha}{\alpha \partial r} \right] \frac{1}{E^2} \frac{\partial (E^3 F)}{\partial E} \\
 &= \frac{j}{\rho} - \tilde{\chi} F + \frac{1}{h^3 c^4} E^2 \int d\mu' R_{is}(\mu, \mu', E) F(\mu', E) \\
 &- \frac{1}{h^3 c^4} E^2 F \int d\mu' R_{is}(\mu, \mu', E) \\
 &+ \frac{1}{h^3 c^4} \left[\frac{1}{\rho} - F(\mu, E) \right] \int E'^2 dE' d\mu' \tilde{R}_{nes}^{in}(\mu, \mu', E, E') F(\mu', E) \\
 &- \frac{1}{h^3 c^4} F(\mu, E) \int E'^2 dE' d\mu' \tilde{R}_{nes}^{out}(\mu, \mu', E, E') \left[\frac{1}{\rho} - F(\mu', E') \right]
 \end{aligned}$$

$$\frac{\partial Y_e}{\partial t} = -\frac{2\pi m_B}{h^3 c^2} \int E^2 dE d\mu \left(\frac{j}{\rho} - \tilde{\chi} F \right) \quad \frac{\partial e}{\partial t} = \dots \quad \frac{\partial u}{\partial t} = \dots$$

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(Mezzacappa & Bruenn 1993, Liebendörfer 2000, Liebendörfer et al. 2004)

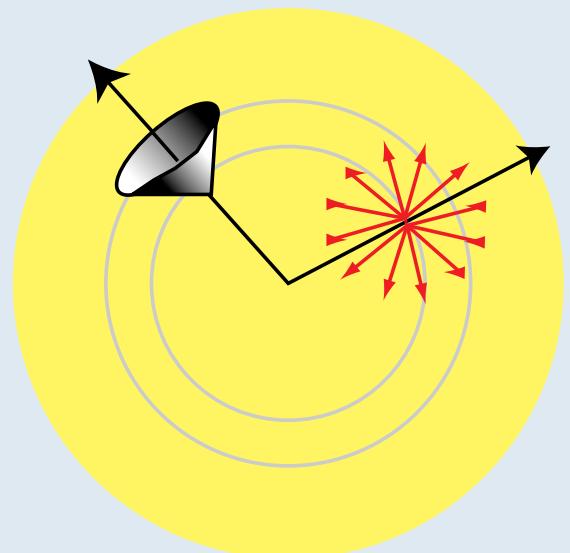
Solving the Boltzmann equation

$$\begin{aligned}
 & \frac{\partial F}{\alpha c \partial t} + \frac{\partial (4\pi r^2 \alpha \rho \mu F)}{\alpha \partial m} + \Gamma \left(\frac{1}{r} - \frac{\partial \alpha}{\alpha \partial r} \right) \frac{\partial [(1 - \mu^2) F]}{\partial \mu} \\
 & + \left(\frac{\partial \ln \rho}{\alpha c \partial t} + \frac{3u}{rc} \right) \frac{\partial [\mu (1 - \mu^2) F]}{\partial \mu} \\
 & + \left[\mu^2 \left(\frac{\partial \ln \rho}{\alpha c \partial t} + \frac{3u}{rc} \right) - \frac{1}{rc} u - \mu \Gamma \frac{\partial \alpha}{\alpha \partial r} \right] \frac{1}{E^2} \frac{\partial (E^3 F)}{\partial E} \\
 & = \frac{j}{\rho} - \tilde{\chi} F + \frac{1}{h^3 c^4} E^2 \int d\mu' R_{is}(\mu, \mu', E) F(\mu', E) \\
 & - \frac{1}{h^3 c^4} E^2 F \int d\mu' R_{is}(\mu, \mu', E) \\
 & + \frac{1}{h^3 c^4} \left[\frac{1}{\rho} - F(\mu, E) \right] \int E'^2 dE' d\mu' \tilde{R}_{nes}^{in}(\mu, \mu', E, E') F(\mu', E) \\
 & - \frac{1}{h^3 c^4} F(\mu, E) \int E'^2 dE' d\mu' \tilde{R}_{nes}^{out}(\mu, \mu', E, E') \left[\frac{1}{\rho} - F(\mu', E') \right] \\
 \frac{\partial Y_e}{\partial t} &= -\frac{2\pi m_B}{h^3 c^2} \int E^2 dE d\mu \left(\frac{j}{\rho} - \tilde{\chi} F \right) \quad \frac{\partial e}{\partial t} = \dots \quad \frac{\partial u}{\partial t} = \dots
 \end{aligned}$$

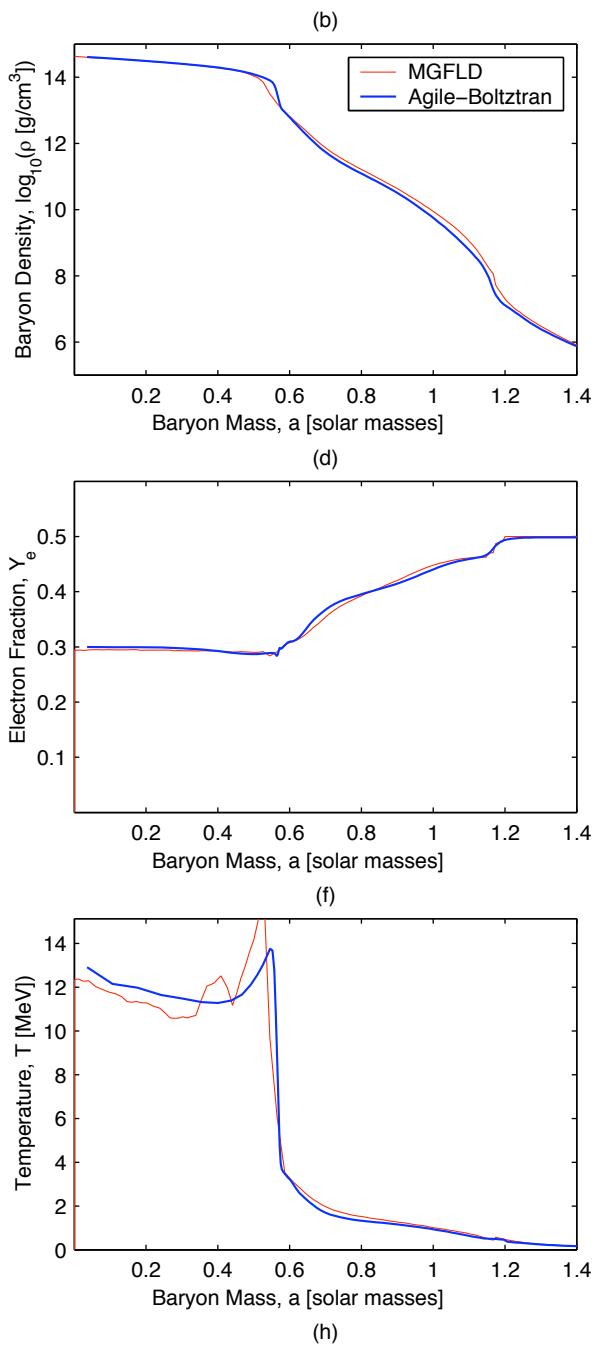
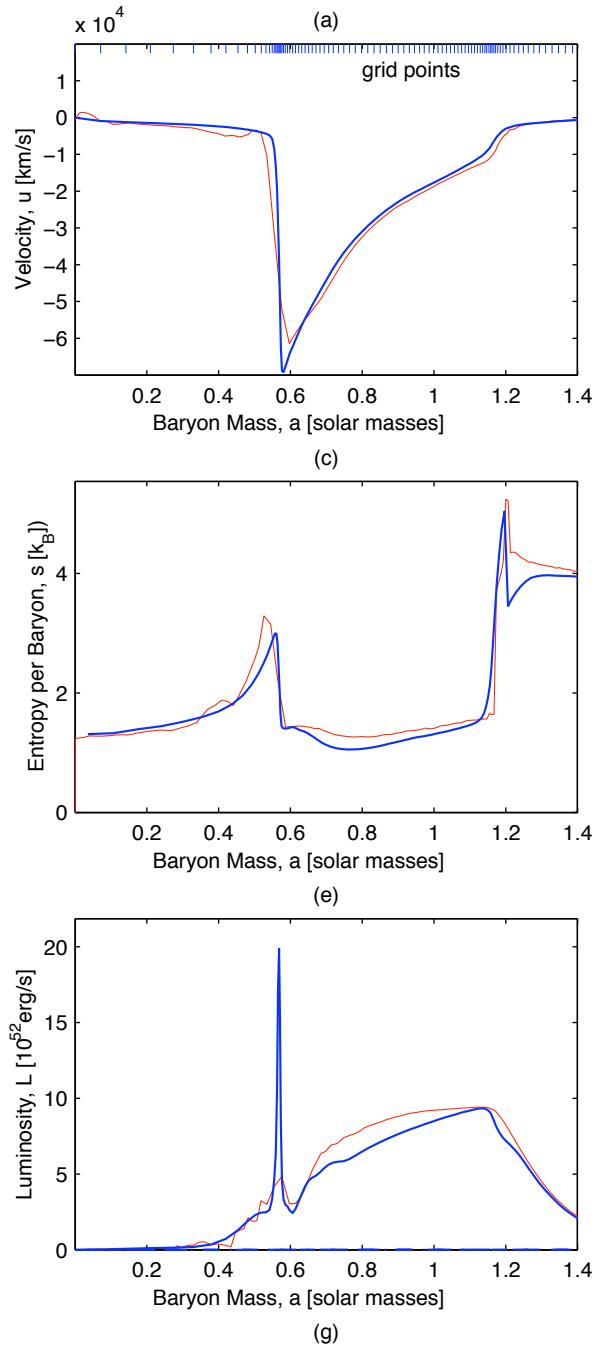
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- tuned for important expectation values
- short characteristics

(Wilson 1971, Mezzacappa & Bruenn 1993,
Liebendörfer et al. 2001/2004, Sumiyoshi et al. 2005)

- + comprehensive
- + local (adaptive)
- expectation values
- angular resolution

Variable Eddington Factor Method

- solution of moments equation
- separate calculation of Eddington factor
- long characteristics

(Burrows et al. 2000, Rampp & Janka 2000/2002, Thompson et al. 2003)

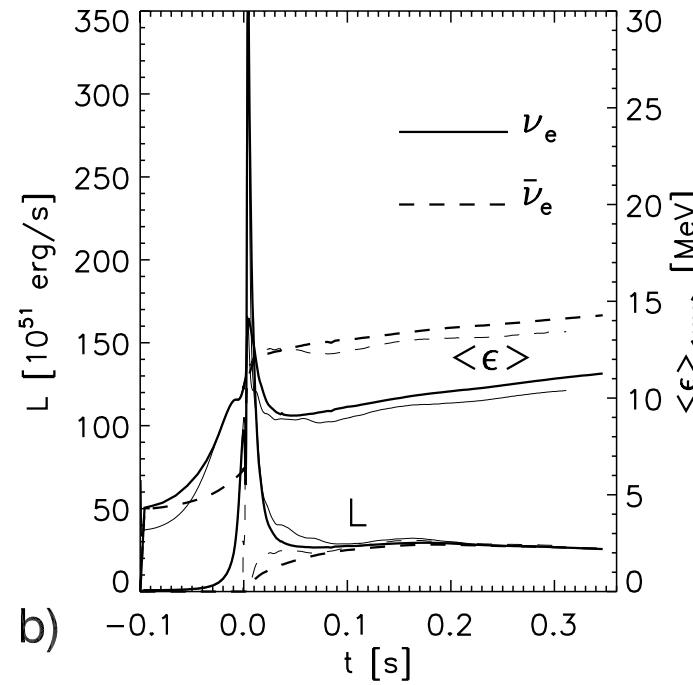
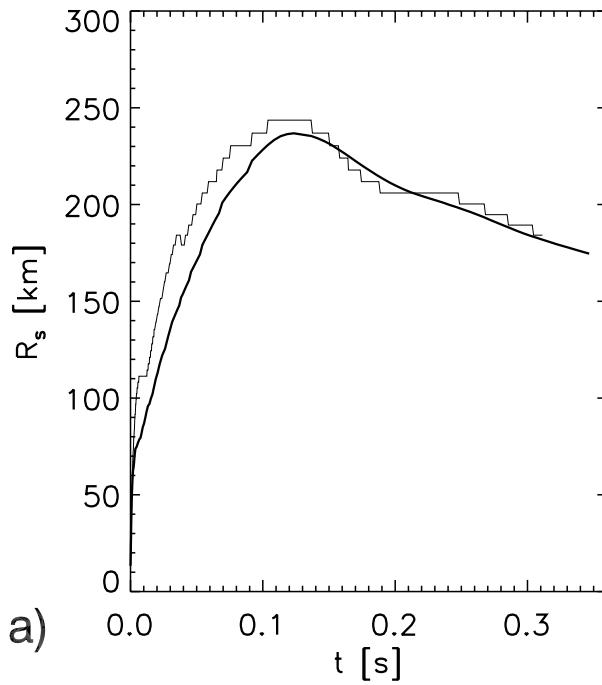
- + angular resolution
- + expectation values
- many equations
- global connection

Boltzmann transport comparison

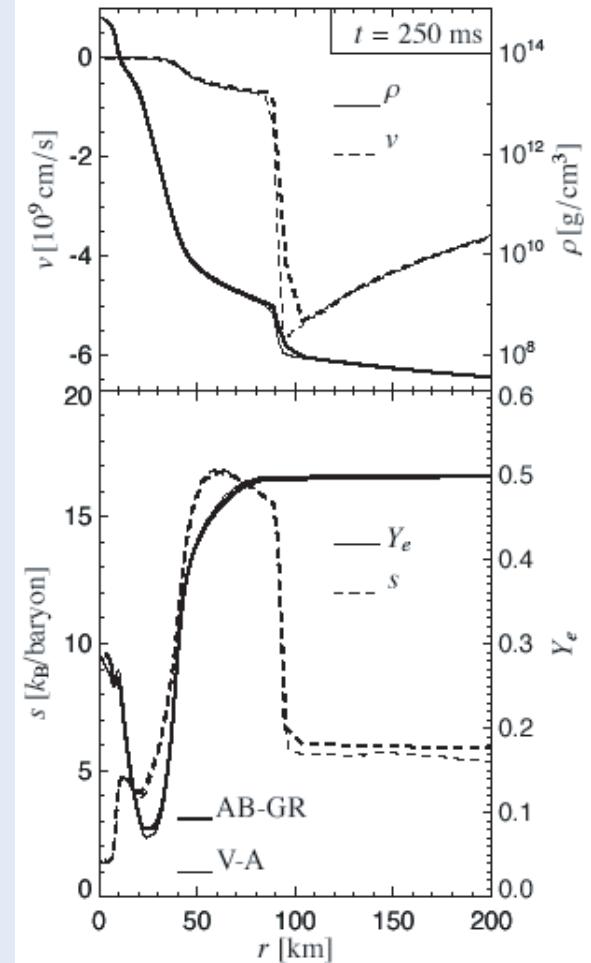


Comparison of spherically symmetric simulations:
Oak Ridge/Basel group and Garching group

Liebendörfer, Rampp, Janka, Mezzacappa, ApJ 620 (2005)



excellent agreement:



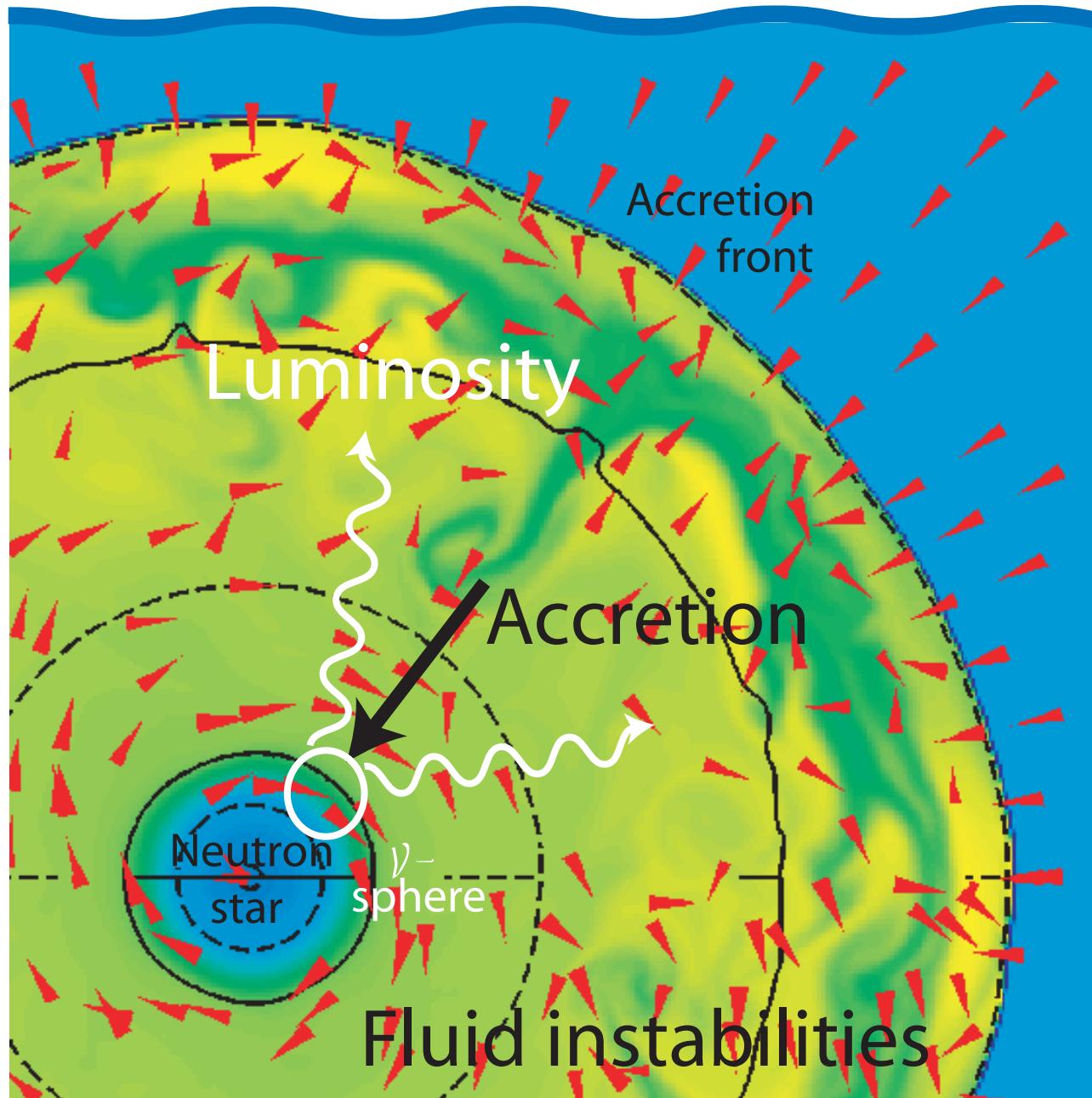
[datafiles.tar.gz](#) of simulation in ApJ electronic edition

(Marek et al., A&A 2006)

SN model minimum requirements

- shock-proof hydrodynamics
 - energy conservation for dissipation on small scales
 - radial GR effects (as in TOV equation)
 - transport of electron neutrino and antineutrino
 - hydrodynamic limit of neutrino gas (pdV term!)
 - comoving-frame diffusion limit
 - spectral decoupling in semi-transparent regime
 - non-local determination of flux factor
 - emission of μ/τ neutrinos and antineutrinos
 - equation of state
 - advection of composition at low density
 - nuclear statistical equilibrium at high density
 - dominant weak interactions in each phase
 - accurate detailed balance
 - implicit finite differencing to obtain equilibria
-
- Good approximations can be more accurate if the full problem is computationally very challenging
 - But, it is difficult to quantify their accuracy without a solution of the full problem

Multi-dimensional radiation-hydrodyn.



- accretion controls >50% of luminosity
 - up- or downflow absorb and emit neutrinos differently
 - luminosity controls the accretion rate
- => 3D nonlocal transport problem: full solution not feasable!

Buras et al. (2003-2005)

Livne et al. (2004)

Walder et al. (2004)

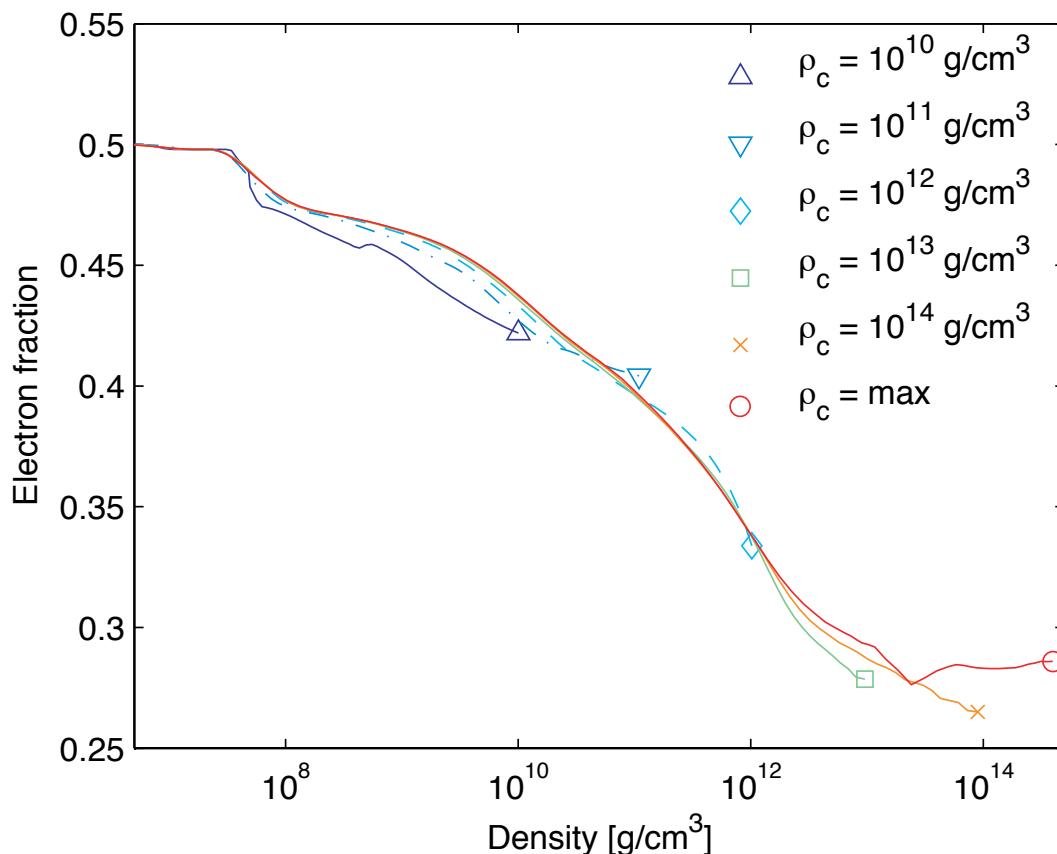
Cardall & Mezzacappa (2005)

Fryer & Warren (2004)

Myra & Swesty (2005)

Parameterised ν -physics before bounce

Electron fraction in spherical runs can be parameterised



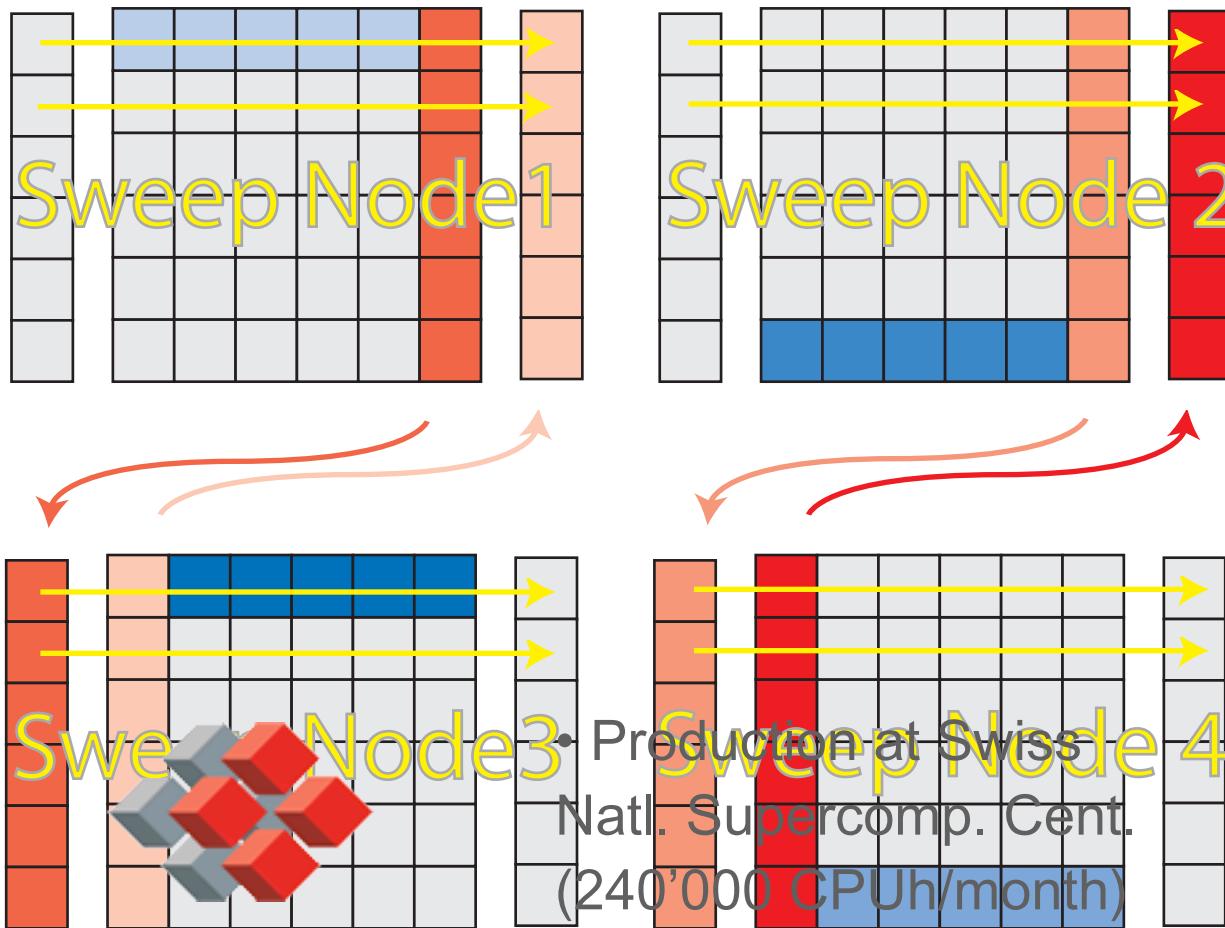
Entropy changes
and neutrino stress
can be derived:

$$\frac{\Delta s}{\Delta t} = - \frac{\Delta Y_e}{\Delta t} \frac{\mu_e - \mu_n + \mu_p - E_\nu^{esc}}{T} \quad (\sim 10 \text{ MeV})$$

- Simple to implement (compared to neutrino transport...)
- Computationally very efficient!
- Performs well for collapse and bounce
- Not applicable in postbounce phase!

Liebendörfer 2005

Parallelisation of 3D MHD code

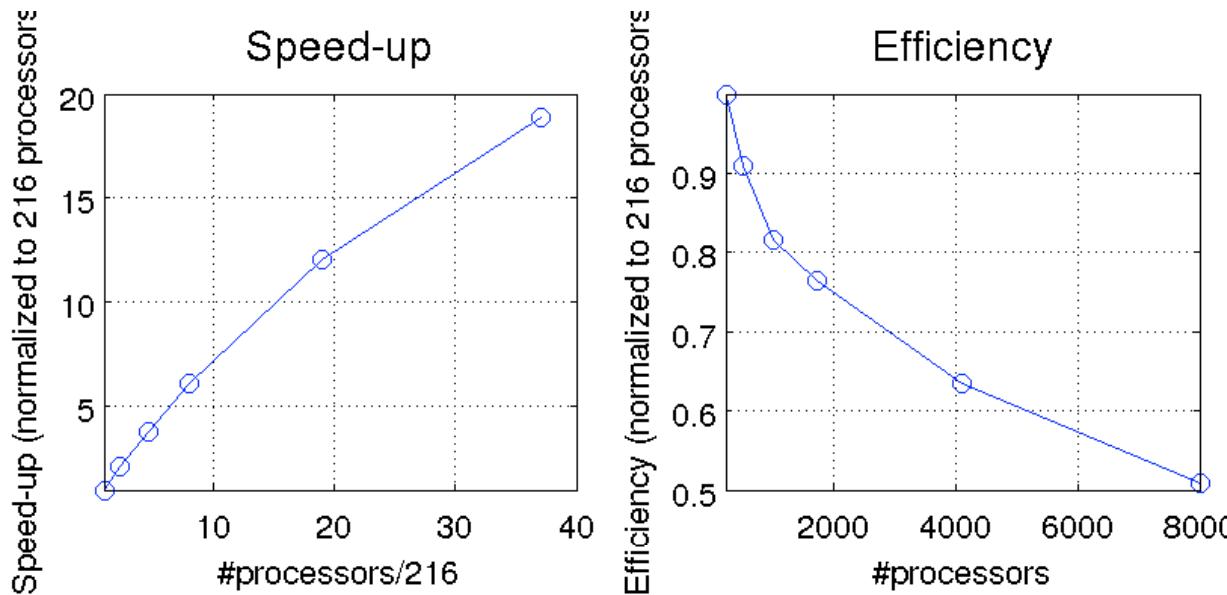


FISH code, Käppeli, Whitehouse,
 Pen, Liebendörfer, arXiv:0910.2854

Communications for **y-sweep**

- 3D cubic domain decomposition (MPI)
- Directional operator-splitting
- Physical x-, y-, z-sweeps by data rotation
- Data consecutively loaded and stored into and from cache
- OpenMP applicable to parallelise sweeps on one node

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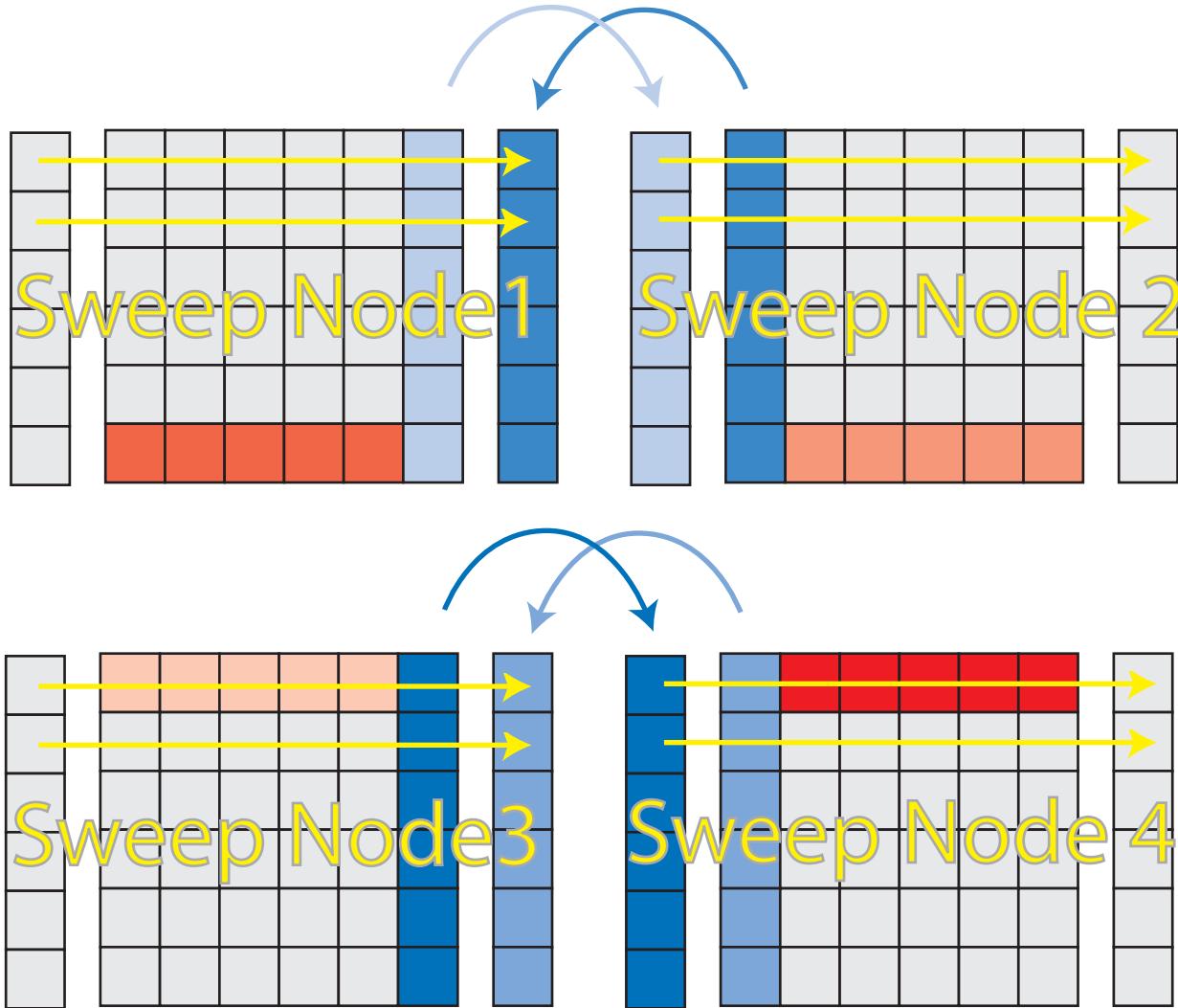


FISH code, Käppeli, Whitehouse,
Pen, Liebendörfer, arXiv:0910.2854

- Production at Swiss
Natl. Supercomp. Cent.
(240'000 CPUh/month)

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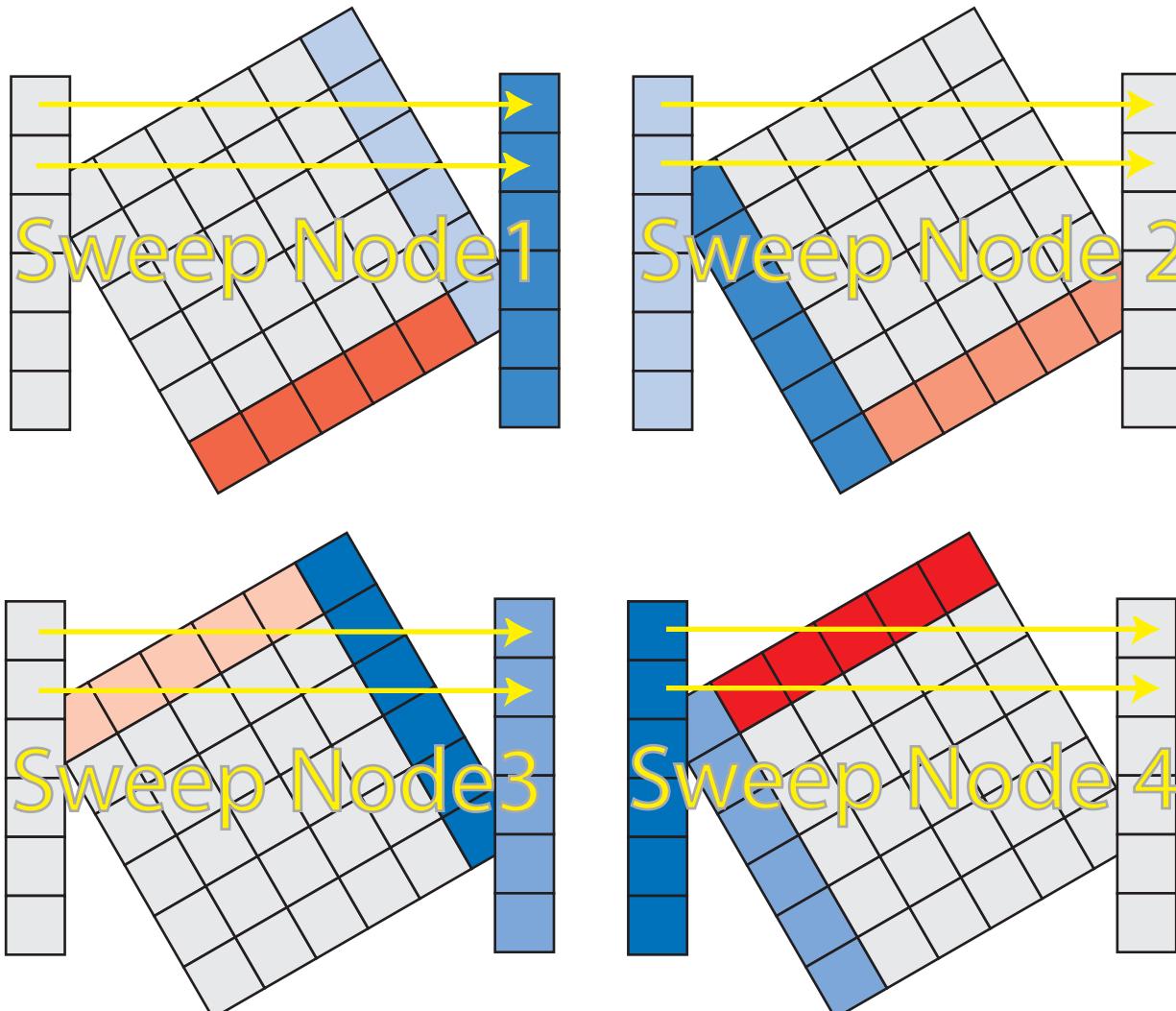
Parallelisation of 3D MHD code



(Pen et al. 2003, Käppeli et al. 200X)

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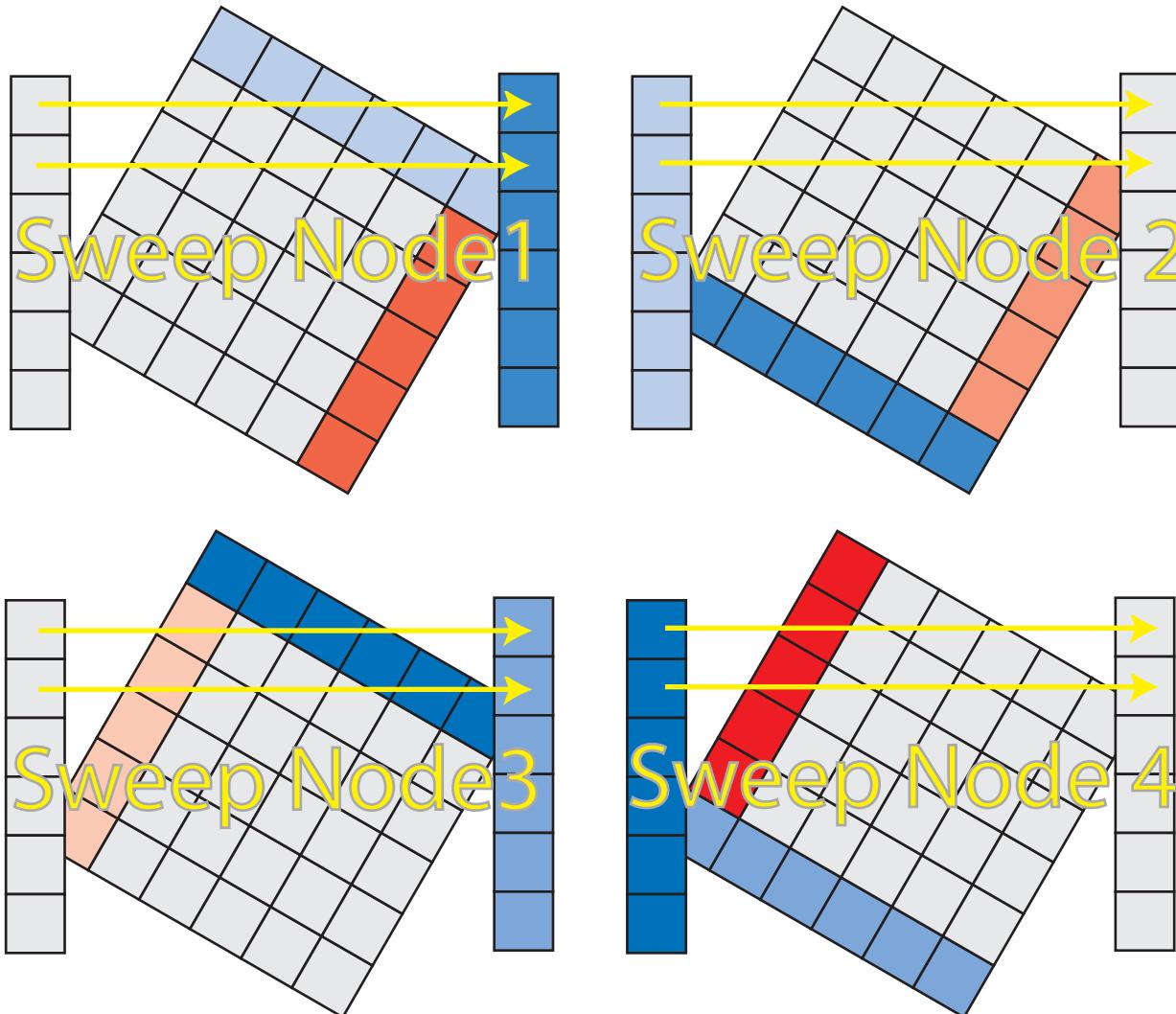


(Pen et al. 2003, Käppeli et al. 200X)

Communications for x-sweep?

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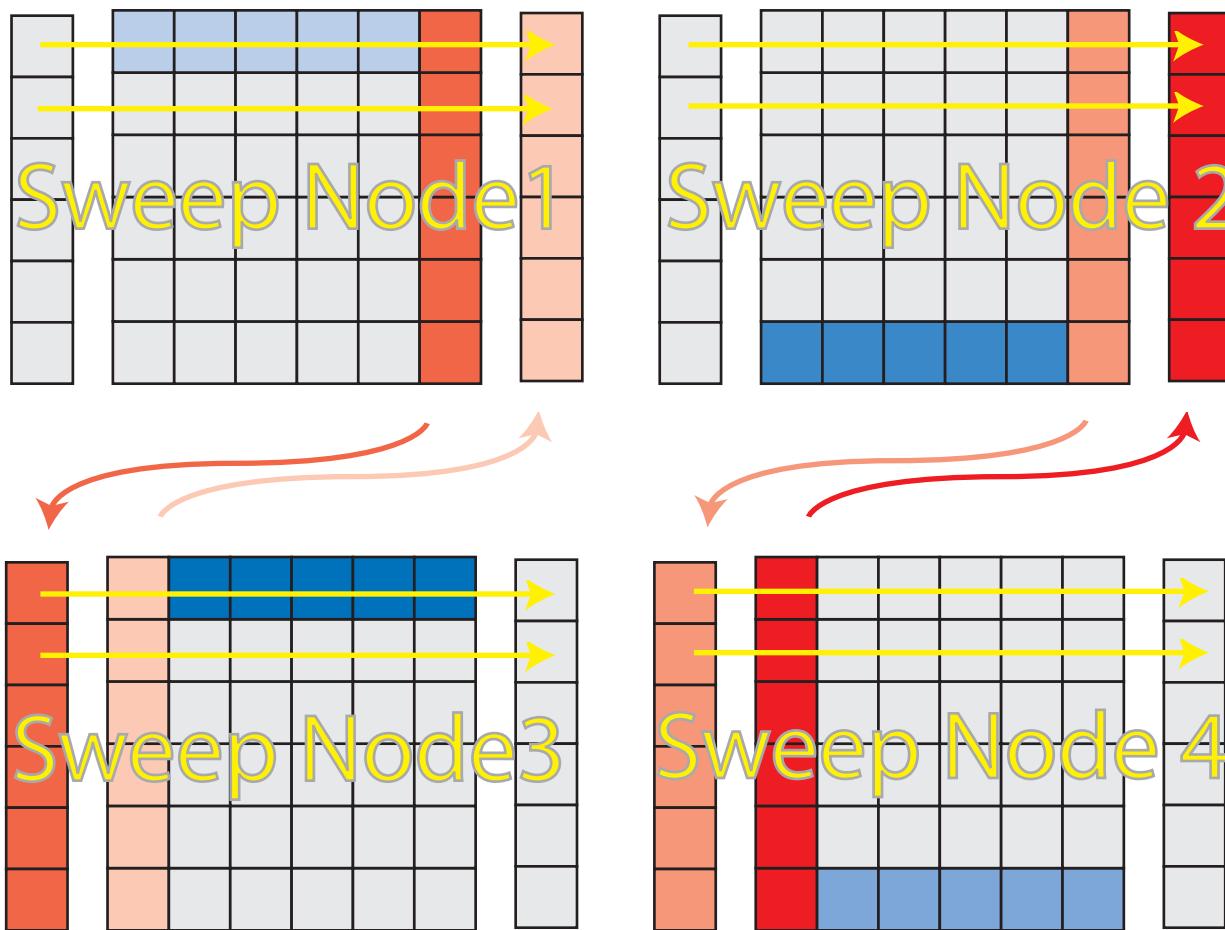
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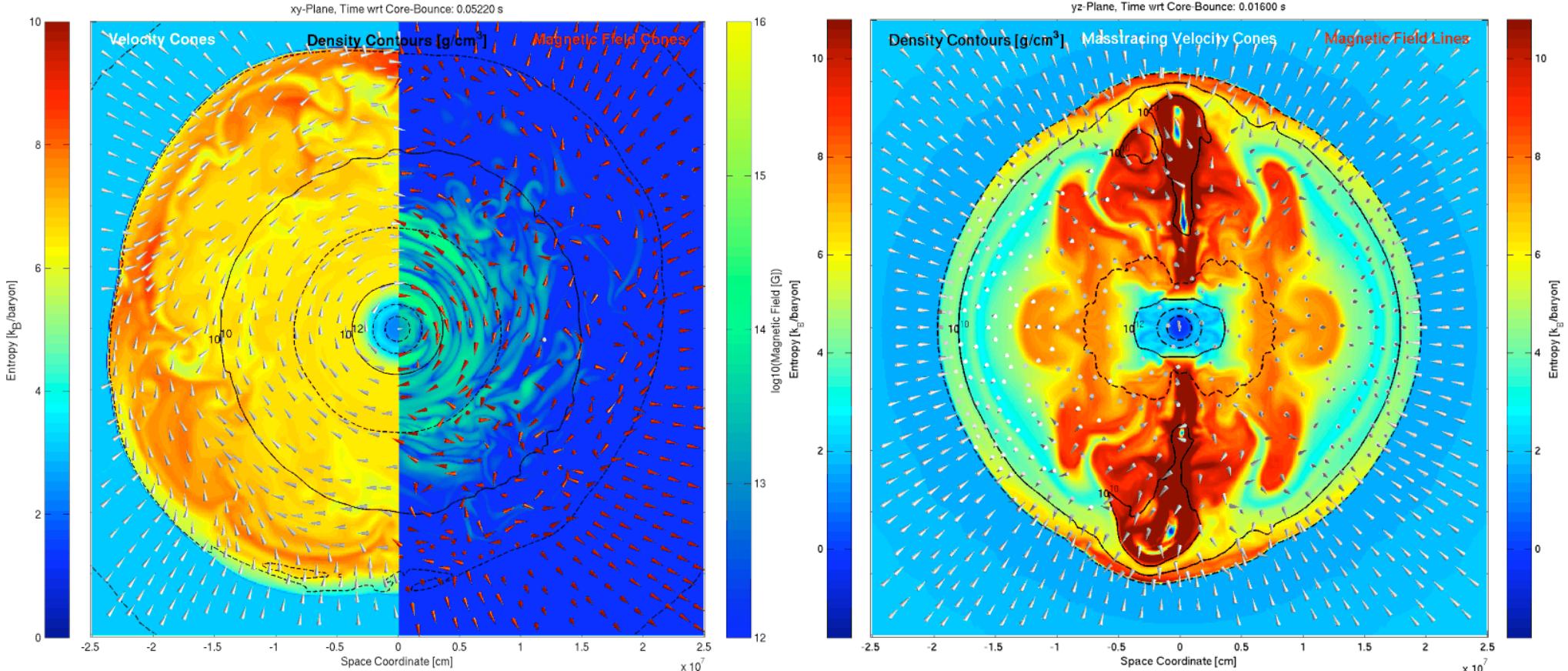
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- Data consecutively loaded and stored into and from cache
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(-->movie)

Experimental 3D magneto-rotational runs



Setup with weak toroidal field
 --> winding
 Liebendörfer et al. 2006

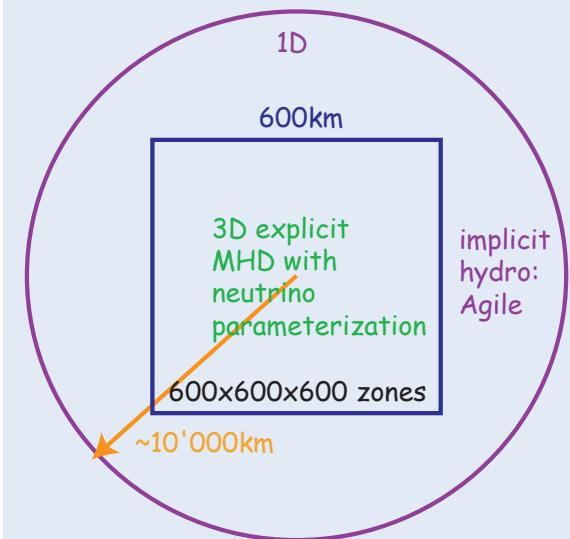
Setup with poloidal field as in Burrows et al. 2007,
 --> jet
 Käppeli, Scheidegger et al.

3D Magneto-Hydrodynamics

Elegant parallel hydrodynamics with
approximate neutrino transport



- Lattimer-Swesty EoS
- Effective GR potential
- constrained transport
- 2nd order TVD
- e-flavour neutrinos



(Liebendörfer, Pen, Thompson 2006)

Pitfalls of multi-D Boltzmann ν -transport



Boltzmann transport:

- One fluid element contains
 4ν types \times 20 energies \times 100 angles = 8000 variables
- At a resolution of 1000^3 zones
--> 64TB per time step

Hydrodynamics:

- One fluid element contains ~ 10 variables
- At a resolution of 1000^3 zones
--> 80GB per step

Pitfalls of multi-D Boltzmann v -transport

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 $4 v \text{ types} \times 20 \text{ energies} \times 100 \text{ angles} = 8000 \text{ variables}$
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 $\rightarrow 64\text{TB per time step}$

Compression of Fermi-gas:

$$\frac{dF}{dt} - \frac{1}{3E^2} \frac{\partial}{\partial E} (E^3 \rho F) \frac{d}{dt} \left(\frac{1}{\rho} \right) - \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{c\lambda}{3} \frac{\partial F}{\partial r} \right) = \left(\frac{dF}{dt} \right)_{\text{collision}}$$

de $p dV$ diffusion = interactions

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difficult energy-terms
 must not be neglected!

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de $p dV$ diffusion = interactions

Diffusion limit:

$$\frac{\lambda}{3} \frac{\partial F}{\partial r} \ll F, \quad \frac{H}{cJ} \sim 10^{-4}, \quad H = \int_{-1}^{+1} F(\mu) \mu d\mu$$

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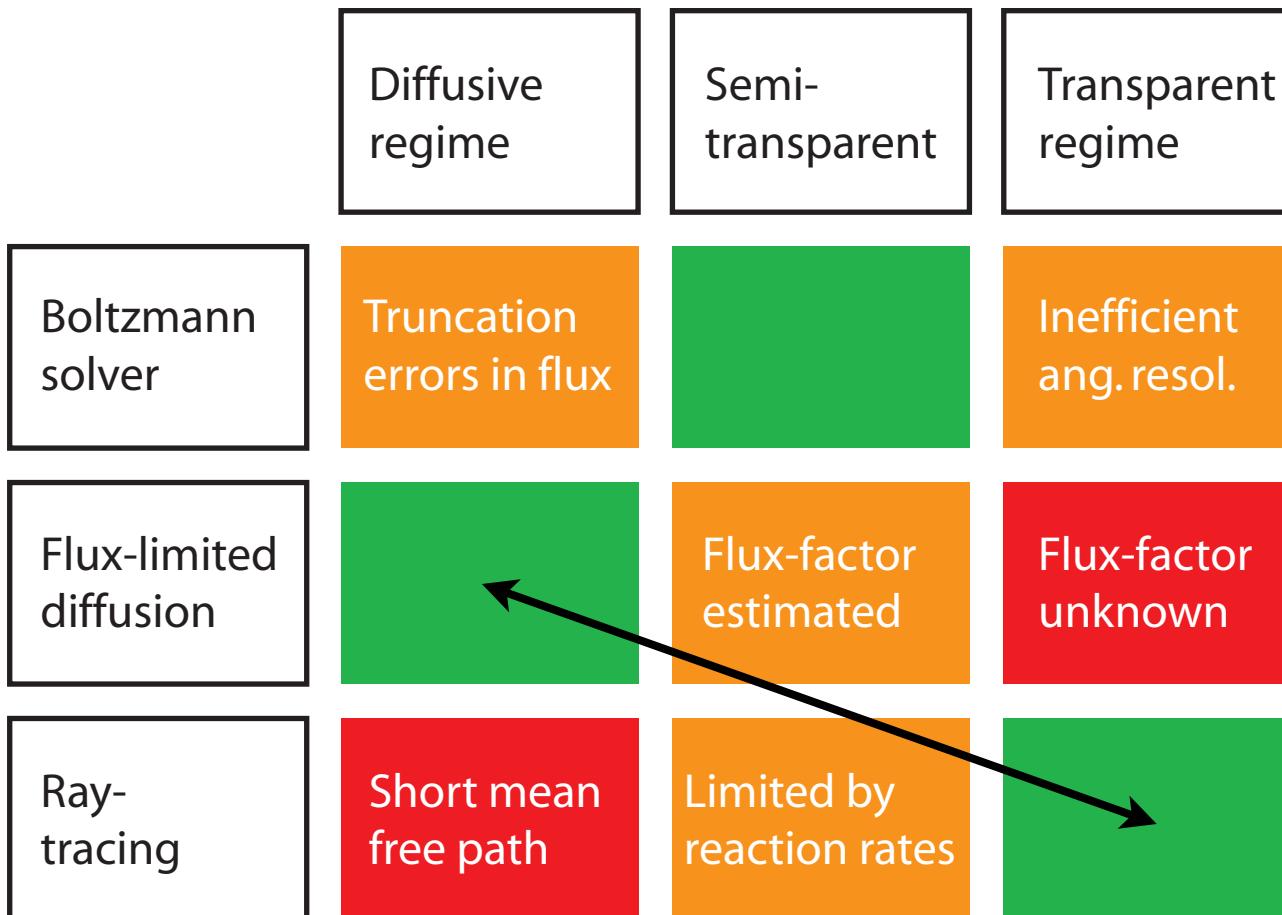
Inaccurate fluxes in
 diffusion-regime due to
 large cancellations in
 angle integral!

There is no perfect transport algorithm...

	Diffusive regime	Semi-transparent	Transparent regime
Boltzmann solver	Truncation errors in flux		Inefficient ang. resol.
Flux-limited diffusion		Flux-factor estimated	Flux-factor unknown
Ray-tracing	Short mean free path	Limited by reaction rates	

- Variable Eddington Factor method successful in 2D but very computationally expensive!
(Rampp & Janka, Buras et al. 2002-5)
- Grey diffusion in one regime and grey transparent elsewhere successful in 3D but not accurate enough!
(e.g. Fryer & Warren 2004)
- Multi-Group Flux-Limited diffusion difficulty of local flux limiters & multi-D
(e.g. Arnett 1966, Bruenn 1985,...)

There is no perfect transport algorithm...



New three-dimensional simulations based on the Isotropic Diffusion Source Approximation (IDSA)
 Liebendörfer, Whitehouse, Fischer (2009)

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Spectral neutrino transport after bounce



$$D(f) = j - \chi^* f$$

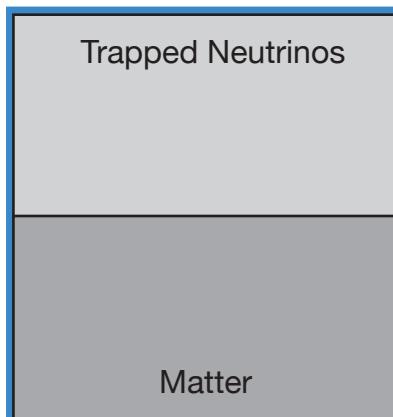
$$f = f(\text{trapped}) + f(\text{streaming}) = f_t + f_s$$

Different approx.
for trapped & streaming
neutrino components!

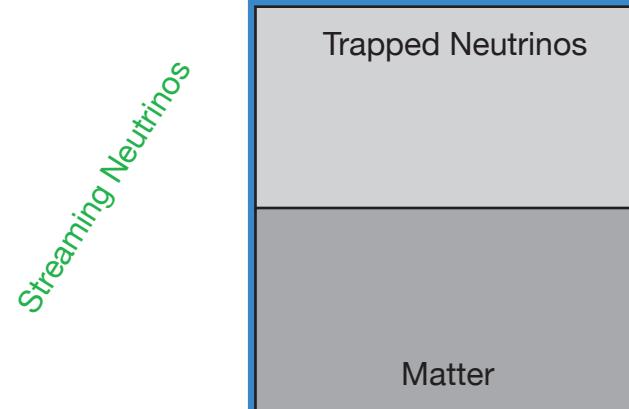
I sotropic
D iffusion
S ource
A pproximation

(Liebendörfer,
Whitehouse,
Fischer 2007)

Fluid element A



Fluid element B



Spectral neutrino transport after bounce

$$D(f) = j - \chi^* f$$

$$f = f(\text{trapped}) + f(\text{streaming}) = f_t + f_s$$

$$D(f_t) = j - \chi^* f_t - \Sigma \quad (1)$$

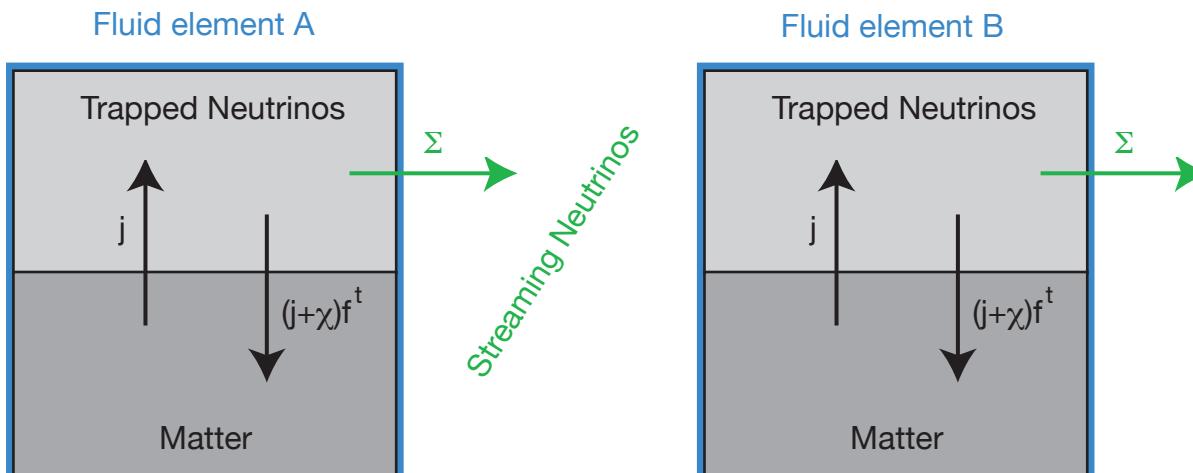
$$D(f_s) = -\chi^* f_s + \Sigma \quad (2)$$

Different approx.
for trapped & streaming
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Σ determined by diffusion limit of (1)

I isotropic
D iffusion
S ource
A pproximation

(Liebendörfer,
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Spectral neutrino transport after bounce

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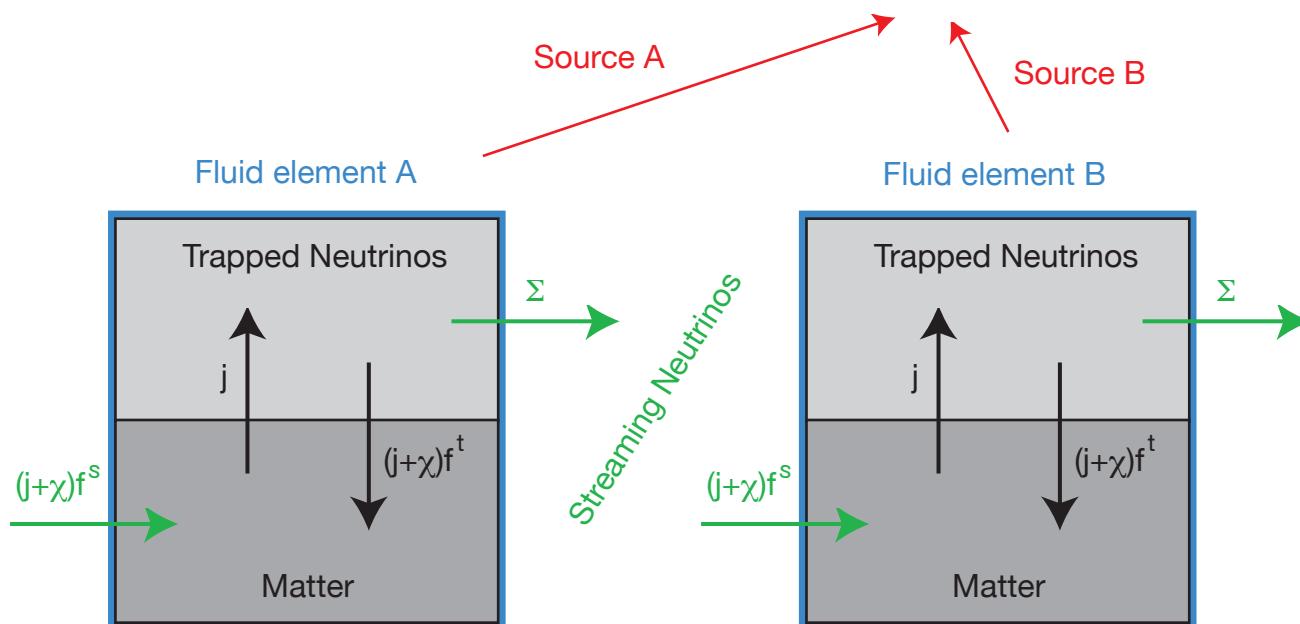
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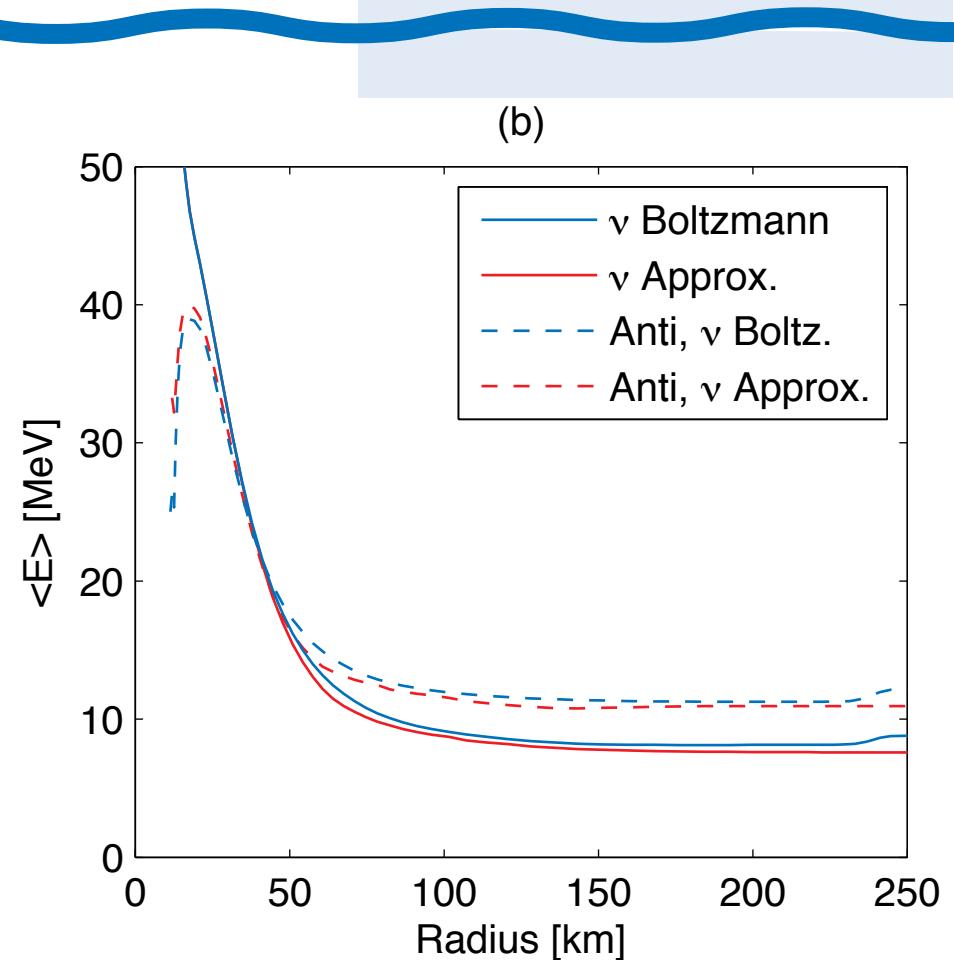
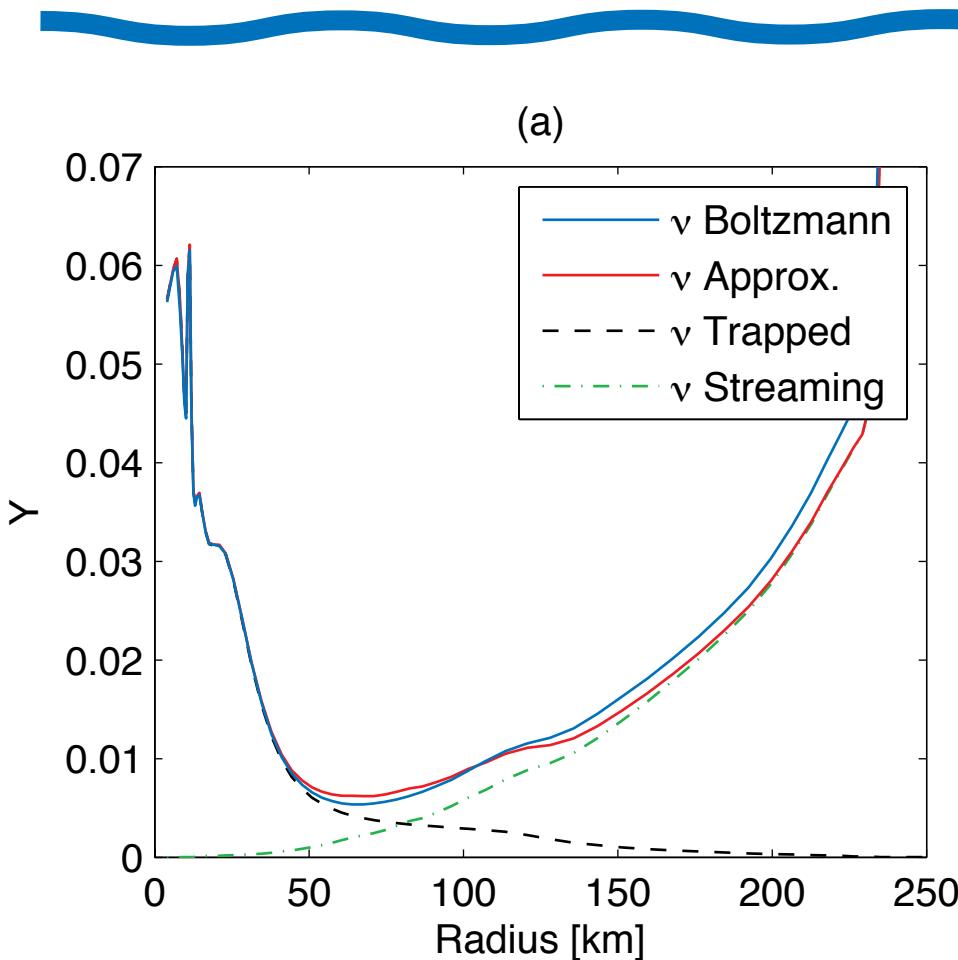
Stationary state approx. for (2) --> Poisson Eq.

I isotropic
D iffusion
S ource
A pproximation

(Liebendörfer,
Whitehouse,
Fischer 2007)



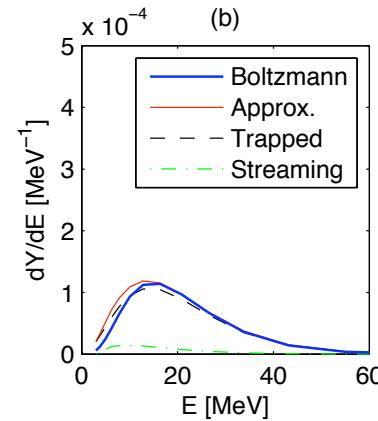
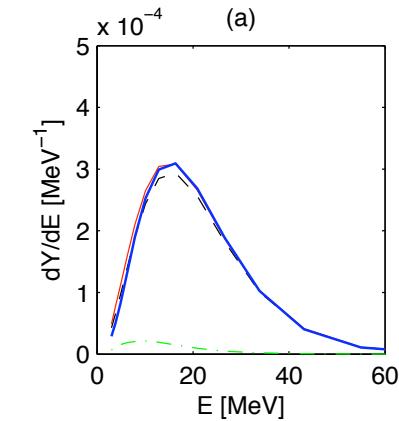
IDSA <--> Boltzmann



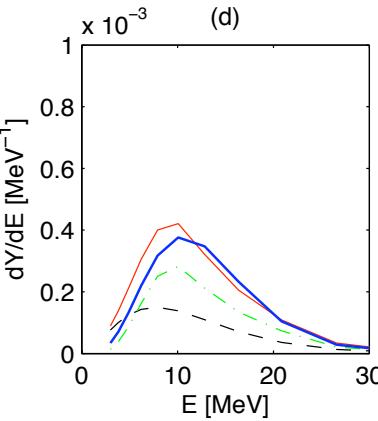
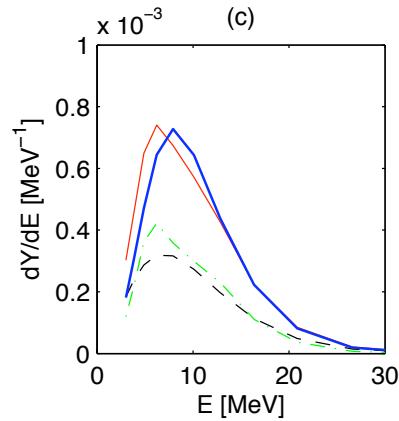
- trapped neutrinos at center
- transition to streaming neutrinos toward surface
- sum of both compared to Boltzmann simulation

Net neutrino abundance and mean energy

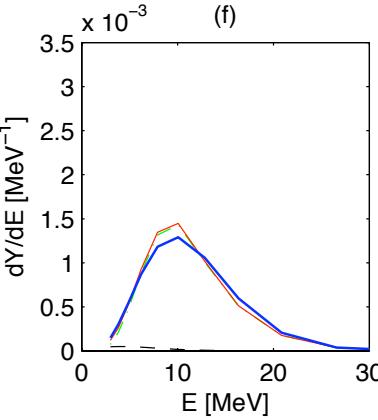
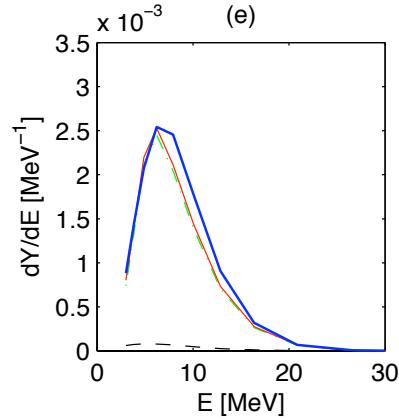
Comparison of IDSA Spectra



at 40 km radius
(trapped regime)



at 80 km radius
(semi-transparent)



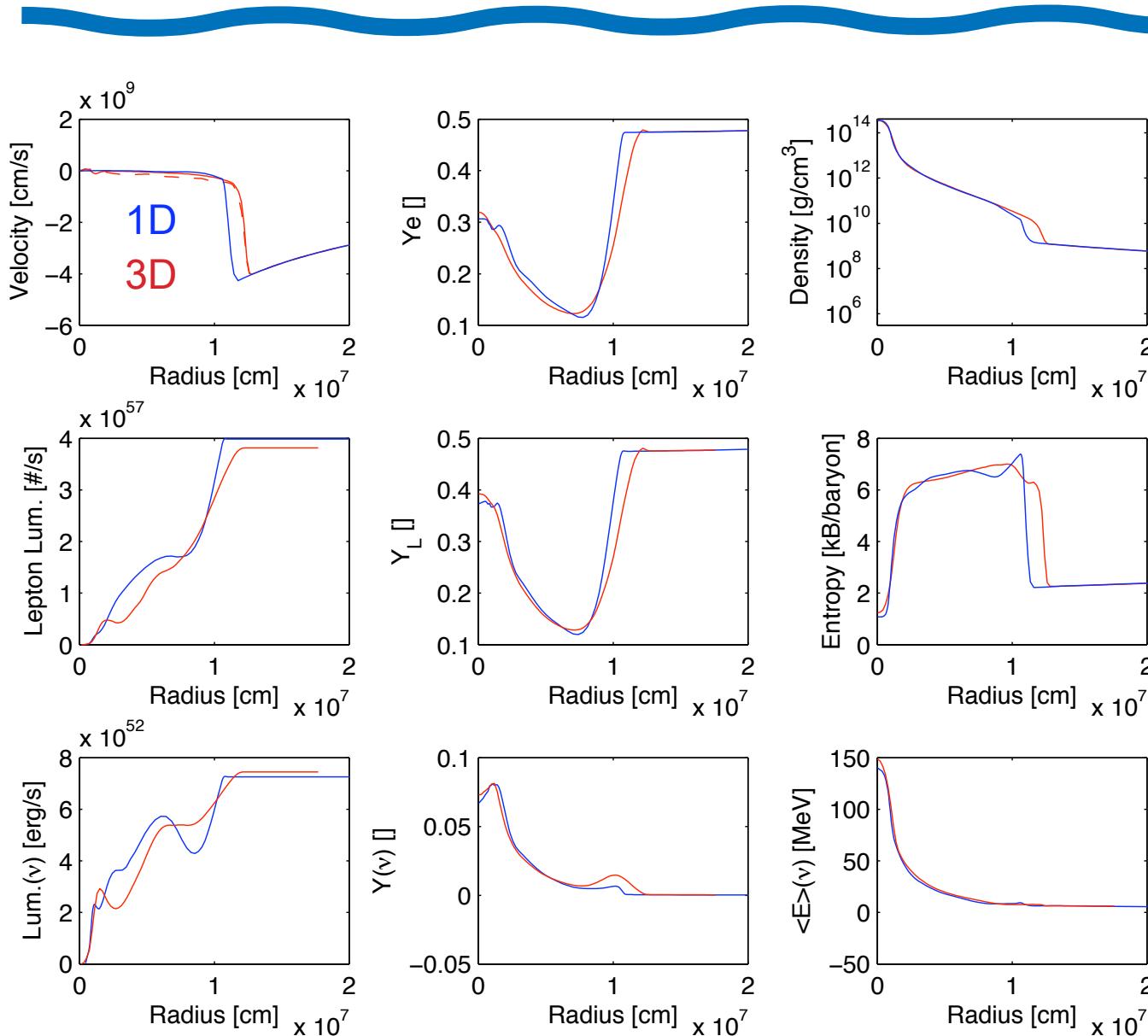
at 160 km radius
(free streaming)

Trapped neutrinos
dominate spectrum

Trapped *and*
streaming neutrinos
form spectrum

Streaming neutrinos
dominate spectrum

Checking the 3D Elephant code...



20 ms postbounce, same input physics

Physics <--> Model <--> Observation



Physics <--> Model <--> Observation



Spherical Symmetry:

- Excellent v-transport with detailed input physics
- 5 different codes give consistent results!

Bruenn et al. 2001, Liebendörfer et al. 2001-5, Rampp & Janka 2000-2,
Thompson et al. 2003, Sumiyoshi et al. 2005-7

- No explosions obtained for most progenitors, exploring neutrino interactions & nuclear physics

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Axisymmetry:

- ray-by-ray or MGFLD v-transport
- computationally very expensive

Buras et al. 2003/5, Walder et al. 2004, Bruenn et al. 2006,
Marek & Janka 2007, Ott et al. 2008

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Three-dimensional:

- v-transport approximations
- enable 3D flow pattern & magnetic fields

Fryer & Warren 2002/4, Scheck et al. 2003, Ott et al. 2007, Scheidegger et al. 2008, Iwakami et al. 2008

- Phenomenology --> predictive power, coming up...