

Astronomie et astrophysique pour physiciens CUSO 2015

Instruments and observational techniques - Adaptive Optics

F. Pepe

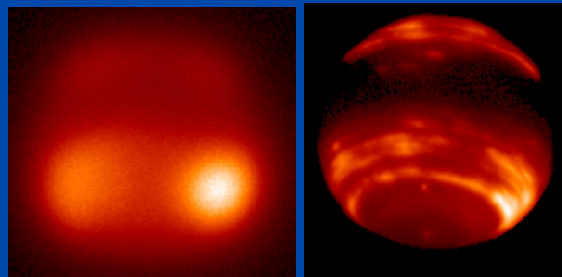
Observatoire de l'Université Genève

F. Courbin and P. Jablonka, EPFL

Adaptive Optics in the VLT and ELT era

basics of AO

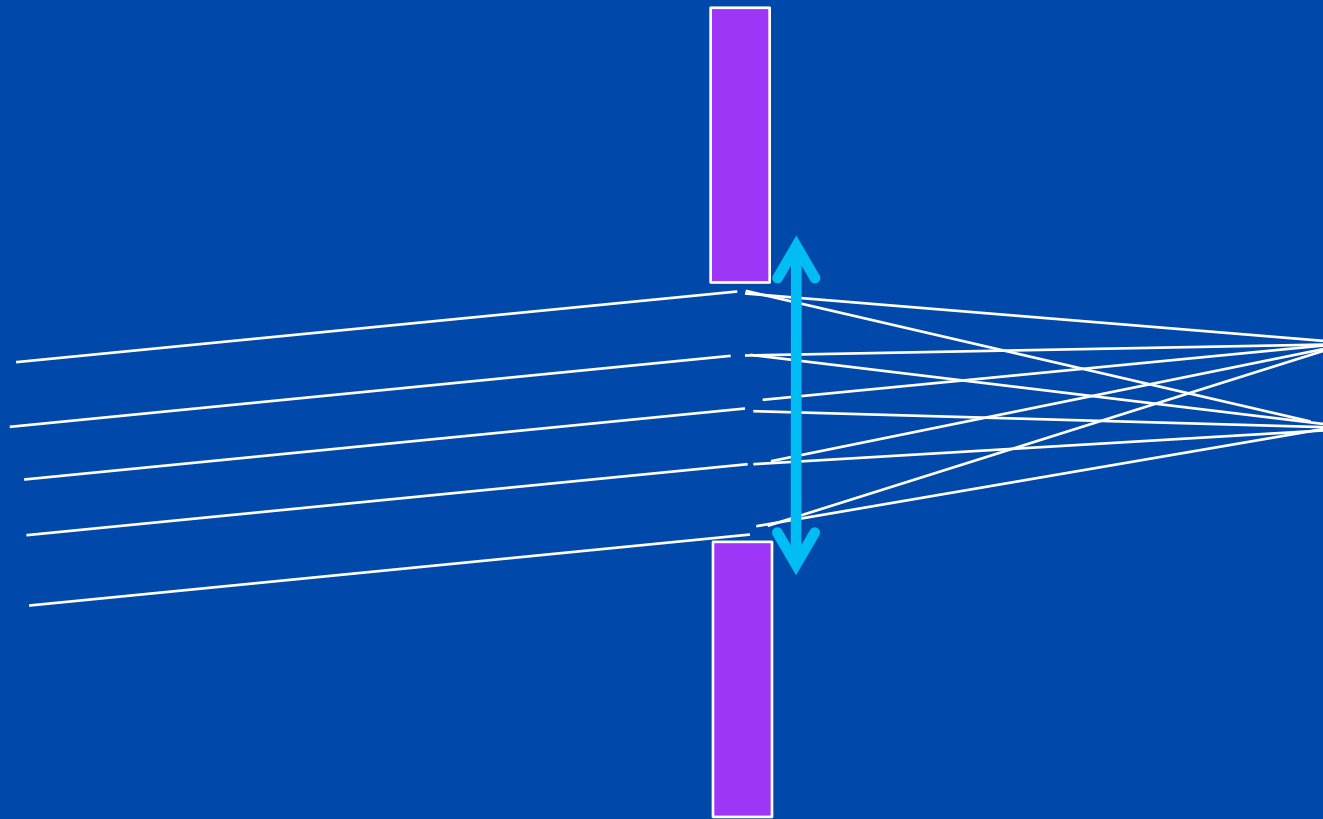
Neptune



Adapted from: **François Wildi**
Observatoire de Genève

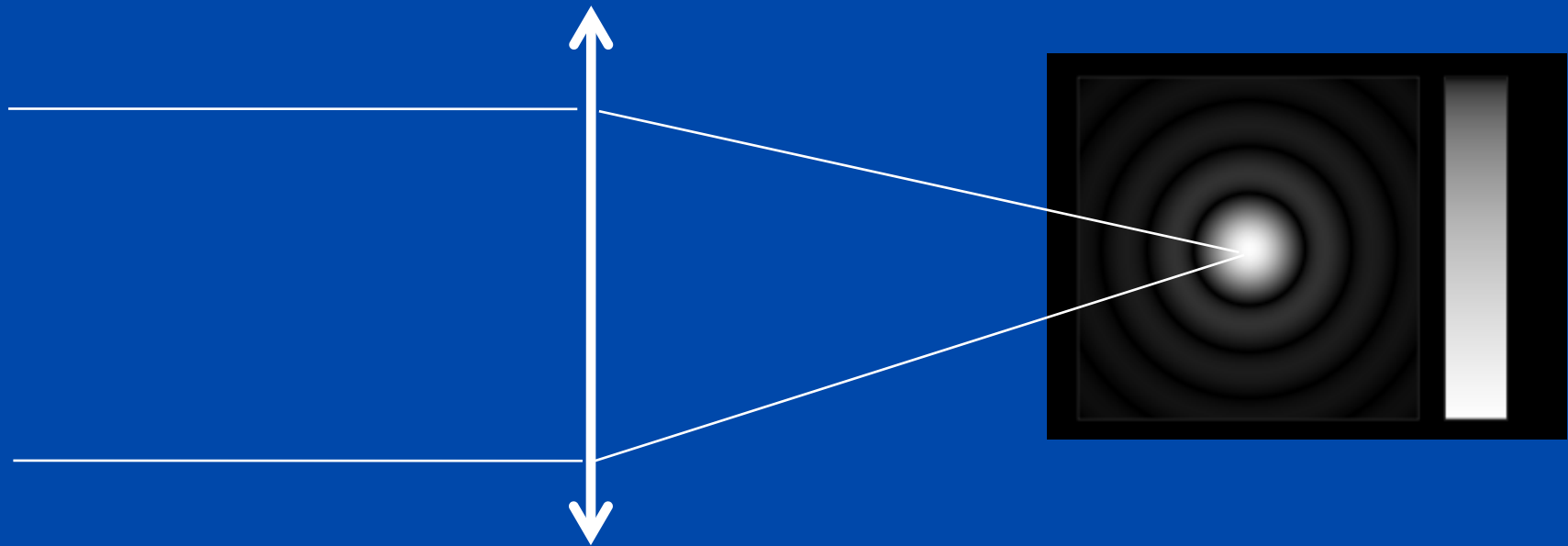
Credit for most slides : Claire Max (UC Santa Cruz)

Looking at the far field (step 2)



What is the 'ideal' PSF?

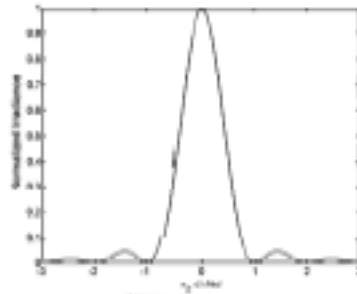
- The image of a point source through a round aperture and no aberrations is an Airy pattern



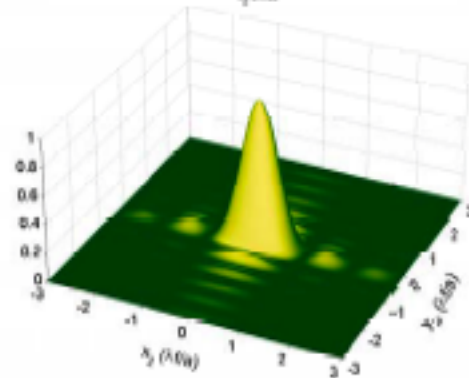
Rectangular Aperture

$$E_2(x_2, y_2) = \frac{E_0 a^2 d^2}{\lambda^2 f^2} \text{sinc}^2\left(\frac{x_2}{\lambda f/a}, \frac{y_2}{\lambda f/d}\right)$$

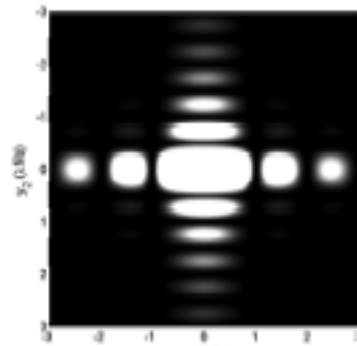
a.)



b.)



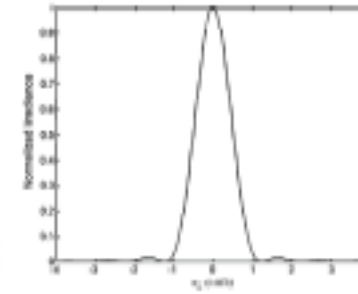
c.)



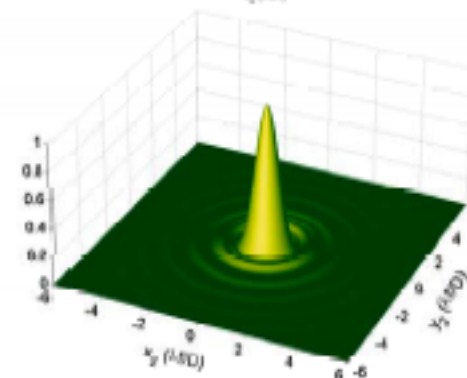
Circular Aperture

$$E_2(x_2, y_2) = E_0 \left(\frac{\pi D^2}{4 \lambda f}\right)^2 \text{somb}^2\left(\frac{r_2}{\lambda f/D}\right)$$

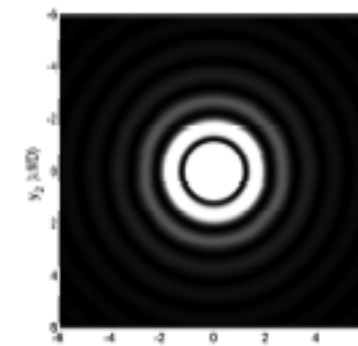
a.)



b.)



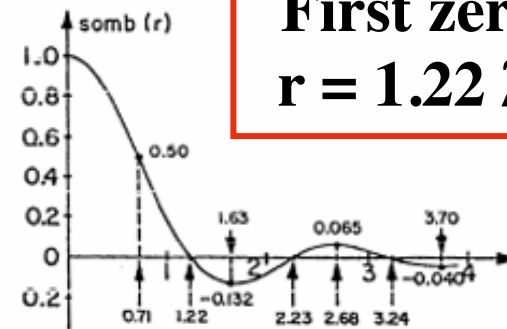
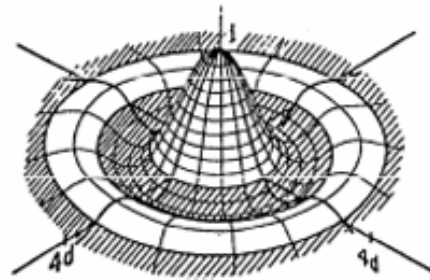
c.)



Details of diffraction from circular aperture and flat wavefront

1) Amplitude

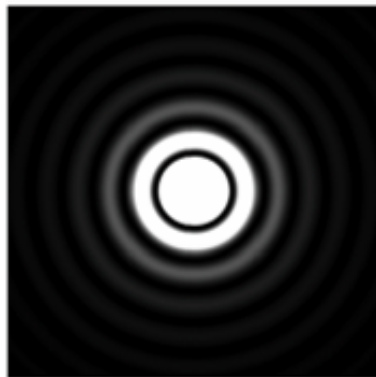
$$\text{somb}(r) = 2 J_1(\pi r) / (\pi r)$$



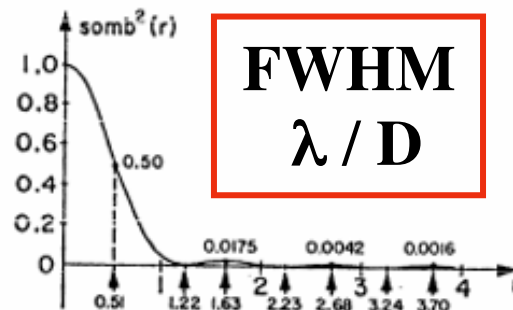
**First zero at
 $r = 1.22 \lambda / D$**

2) Intensity

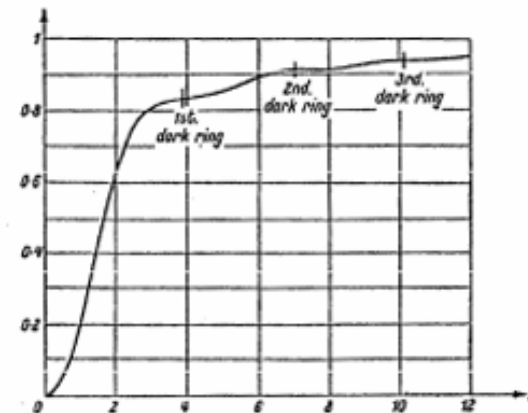
Airy Pattern



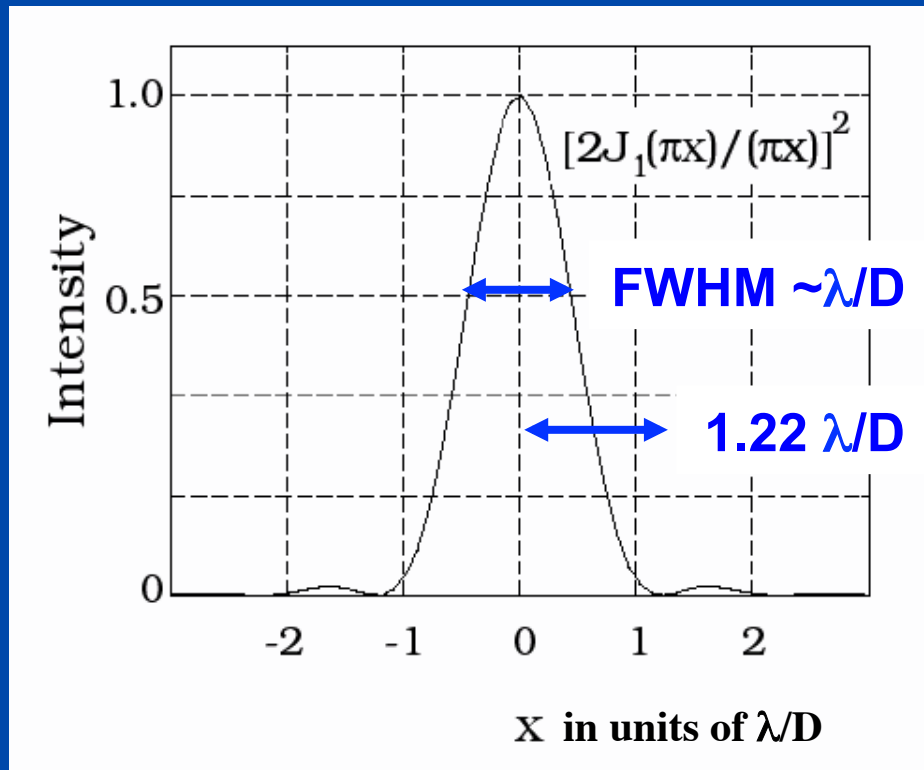
$\text{somb}^2(r)$



Fractional Encircled Energy



Imaging through a perfect telescope (circular pupil)



Point Spread Function (PSF):
intensity profile from point source

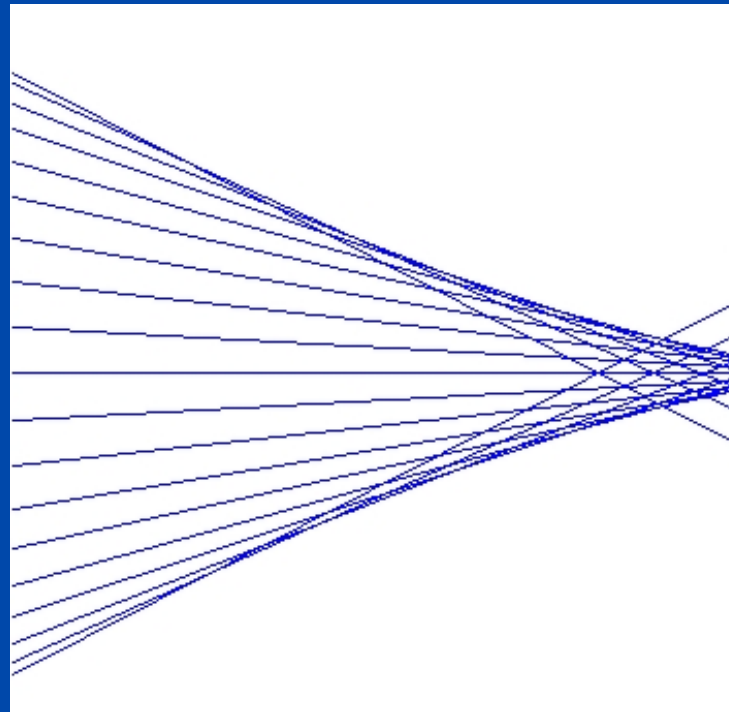
With **no turbulence**,
FWHM is diffraction limit
of telescope, $\theta \sim \lambda / D$

Example:

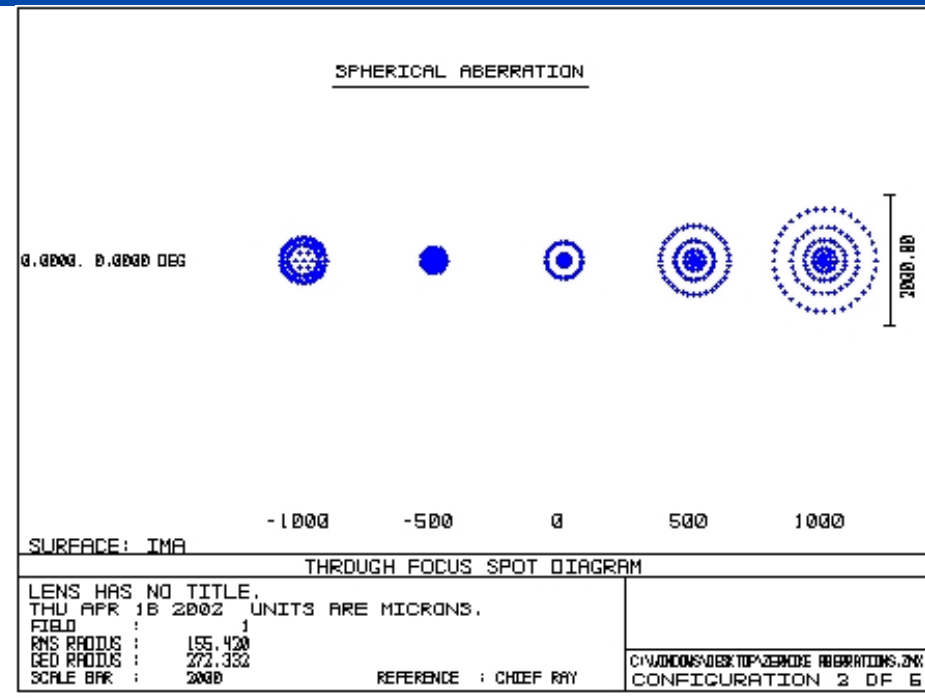
$$\lambda / D = 0.02 \text{ arc sec for } \lambda = 1 \mu\text{m}, D = 10 \text{ m}$$

With turbulence, image
size gets much larger
(**typically 0.5 - 2 arc sec**)

Spherical aberration



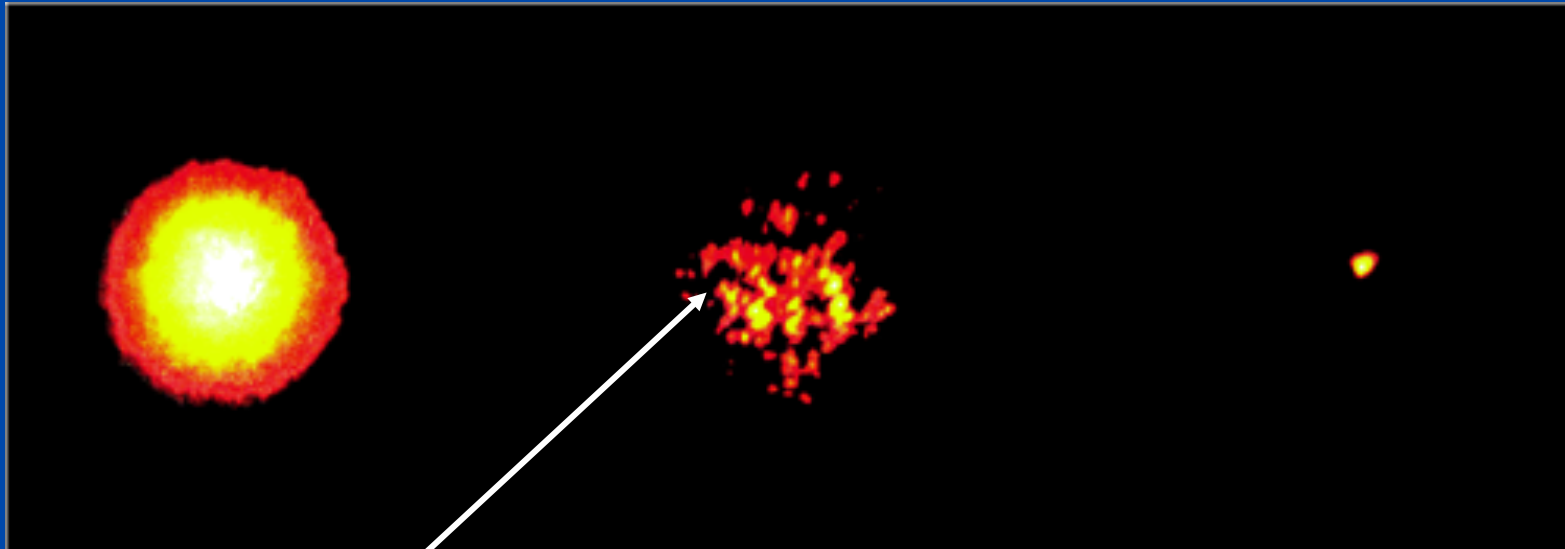
Rays from a spherically aberrated wavefront focus at different planes



Through-focus spot diagram for spherical aberration

Images of a bright star

1 m telescope



Speckles (each is at **diffraction limit** of telescope)

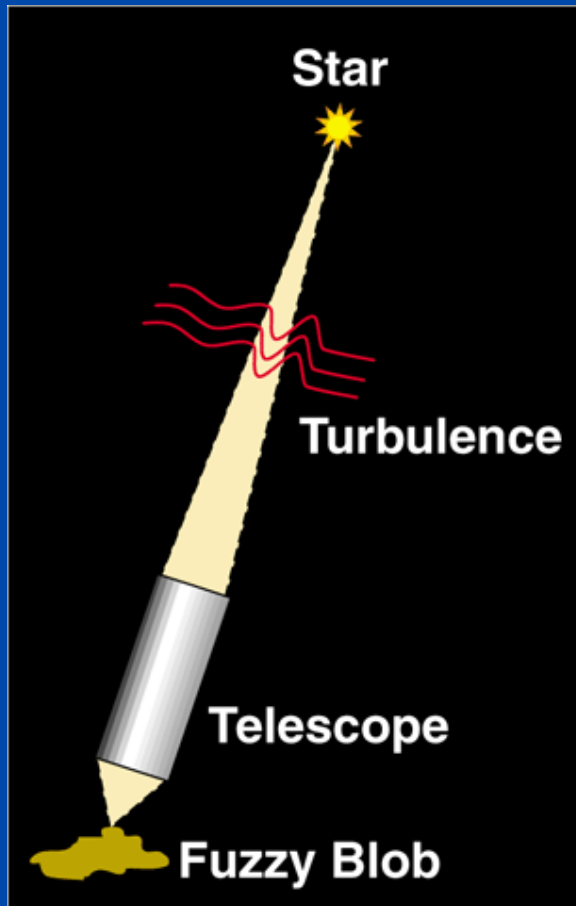
Goals of lecture

- To understand the main concepts behind adaptive optics systems
- To understand how important AO is for a VLT and how indispensable for an ELT
- To get an idea what is brewing in the AO field and what is store for the future

Content

- Intro to AO systems
- Basic optics, diffraction, Fourier optics, image structure
- High contrast AO (VLT SPHERE, E-ELT)
- Sky coverage, Laser guide stars
- Wide field AO, Multi-Conjugate Adaptive Optics (Gemini GLAO, VLT MAD, Gemini MCAO)
- Multi-Object Adaptive Optics (TMT IRMOS, E-ELT Eagle)

Why is adaptive optics needed?

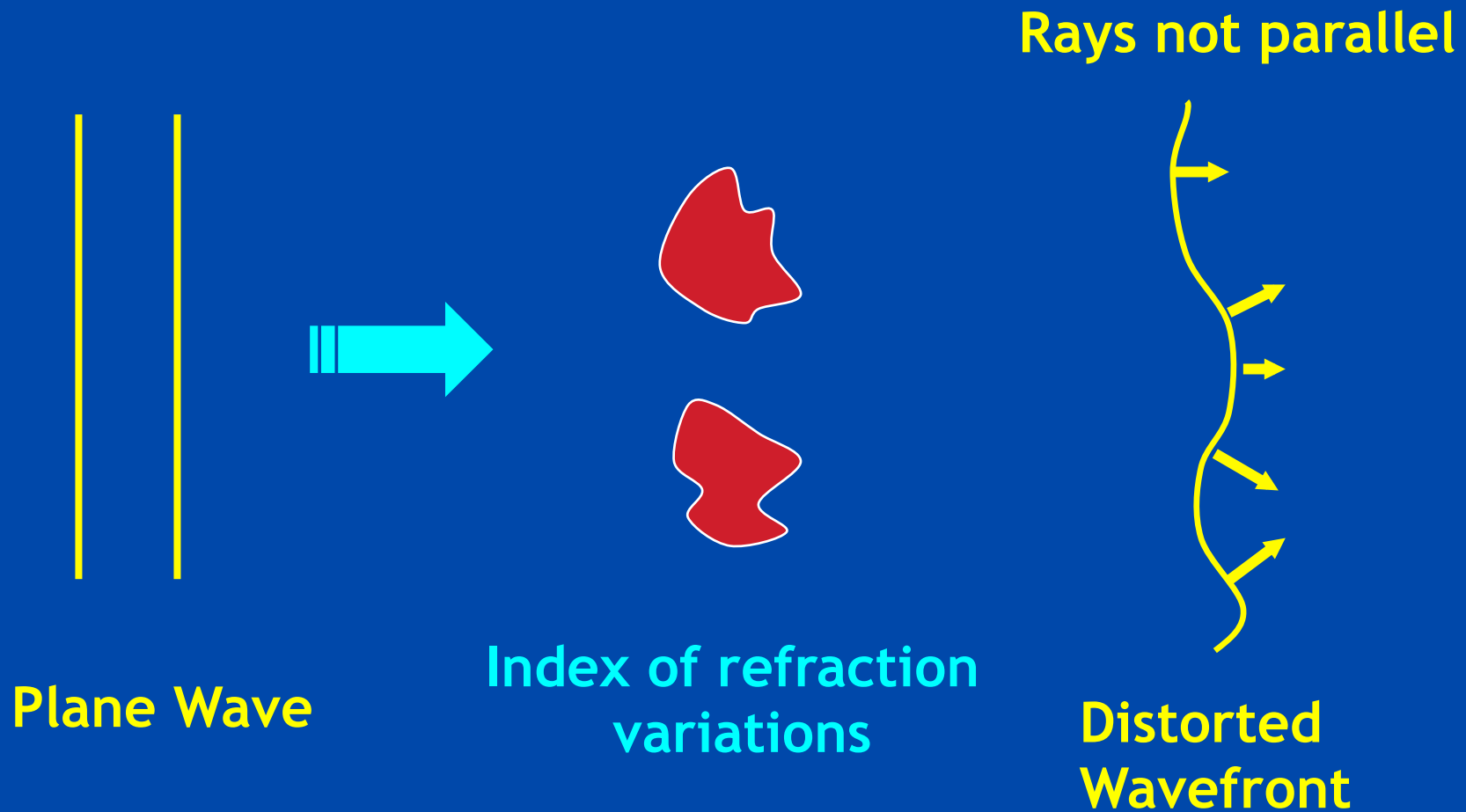


Turbulence in earth's atmosphere makes stars twinkle

More importantly, turbulence spreads out light; makes it a blob rather than a point. This blob is a lot larger than the Point Spread Function (PSF) that would be limited by the size of the telescope only

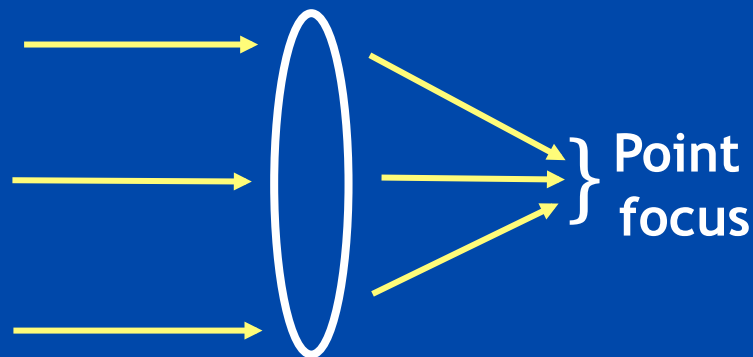
Even the largest ground-based astronomical telescopes have no better resolution than an 20cm telescope

Atmospheric perturbations cause distorted wavefronts

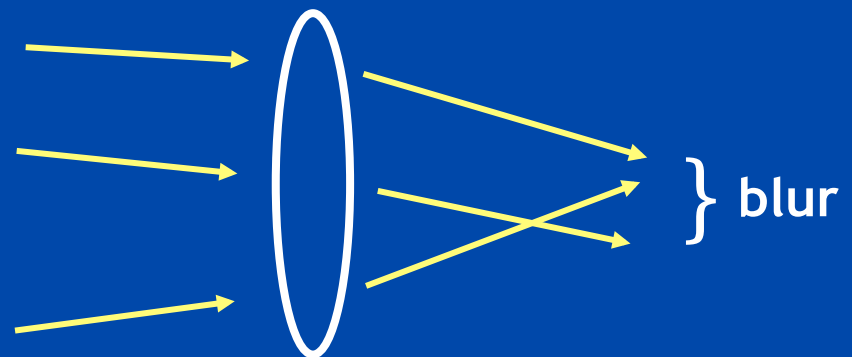


Optical consequences of turbulence

- Temperature fluctuations in small patches of air cause changes in index of refraction (like many little lenses)
- Light rays are refracted many times (by small amounts)
- When they reach telescope they are no longer parallel
- Hence rays can't be focused to a point:



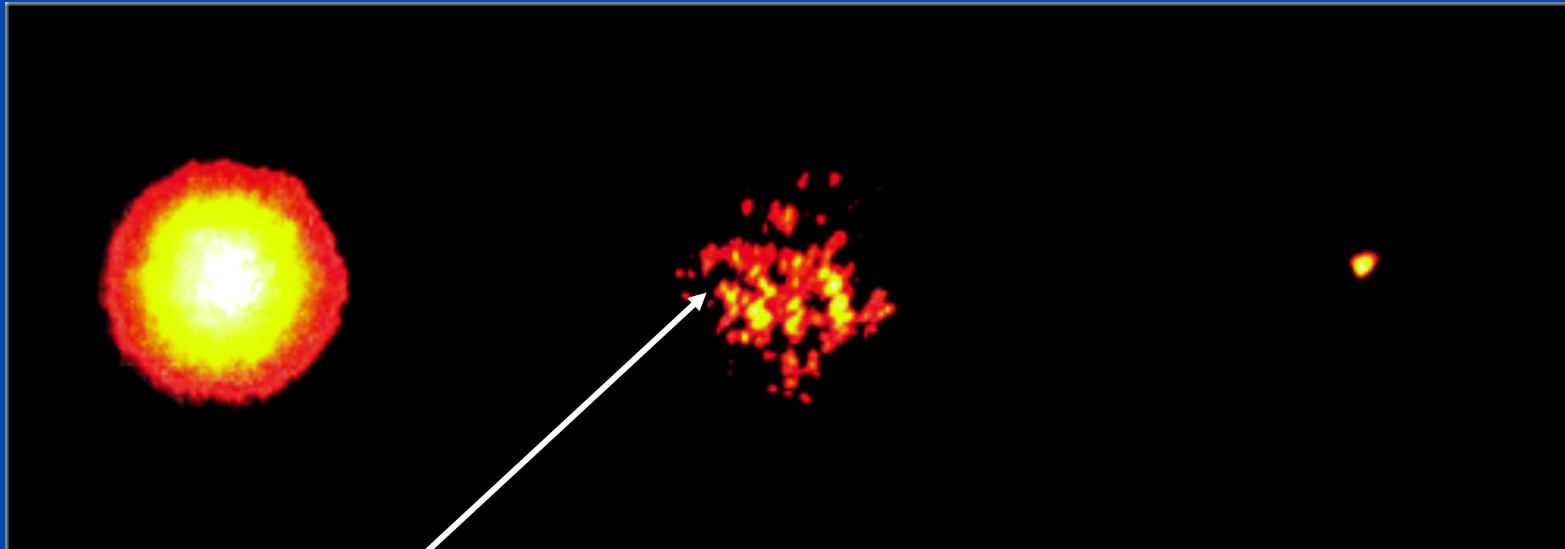
Parallel light rays



Light rays affected by turbulence

Images of a bright star

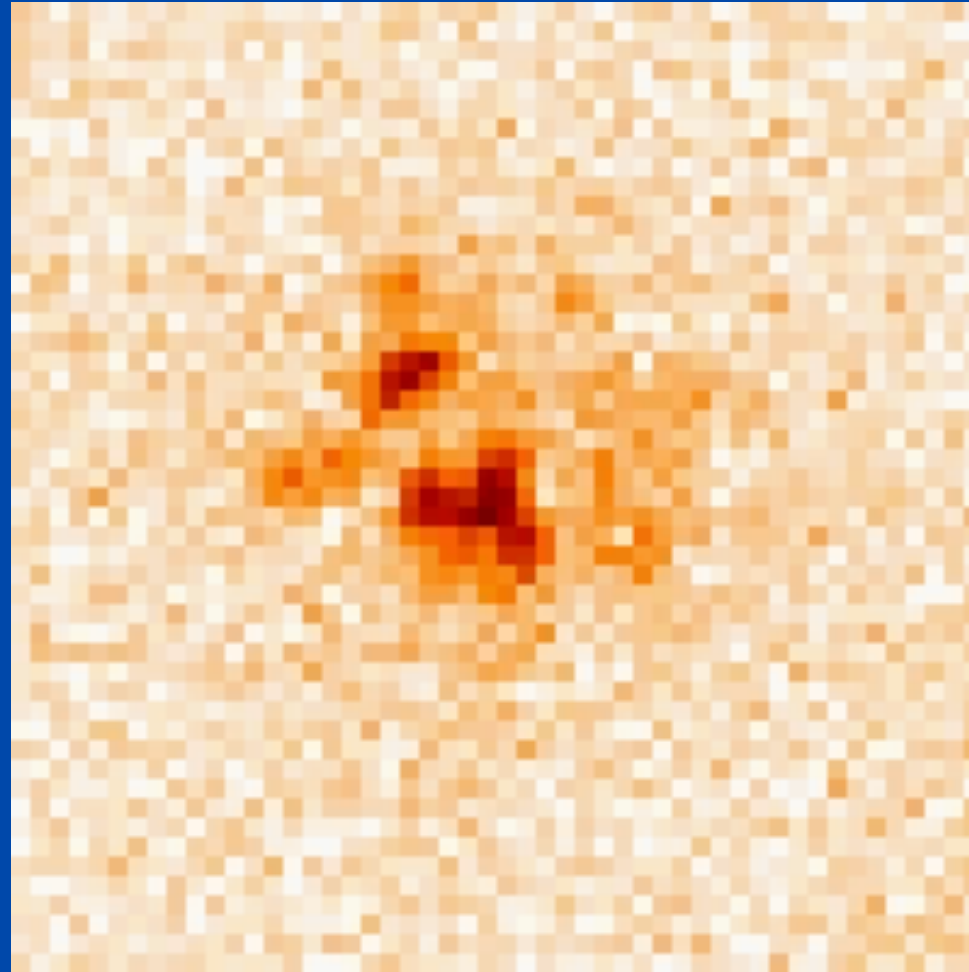
1 m telescope



Speckles (each is at **diffraction limit** of telescope)

Turbulence changes rapidly with time

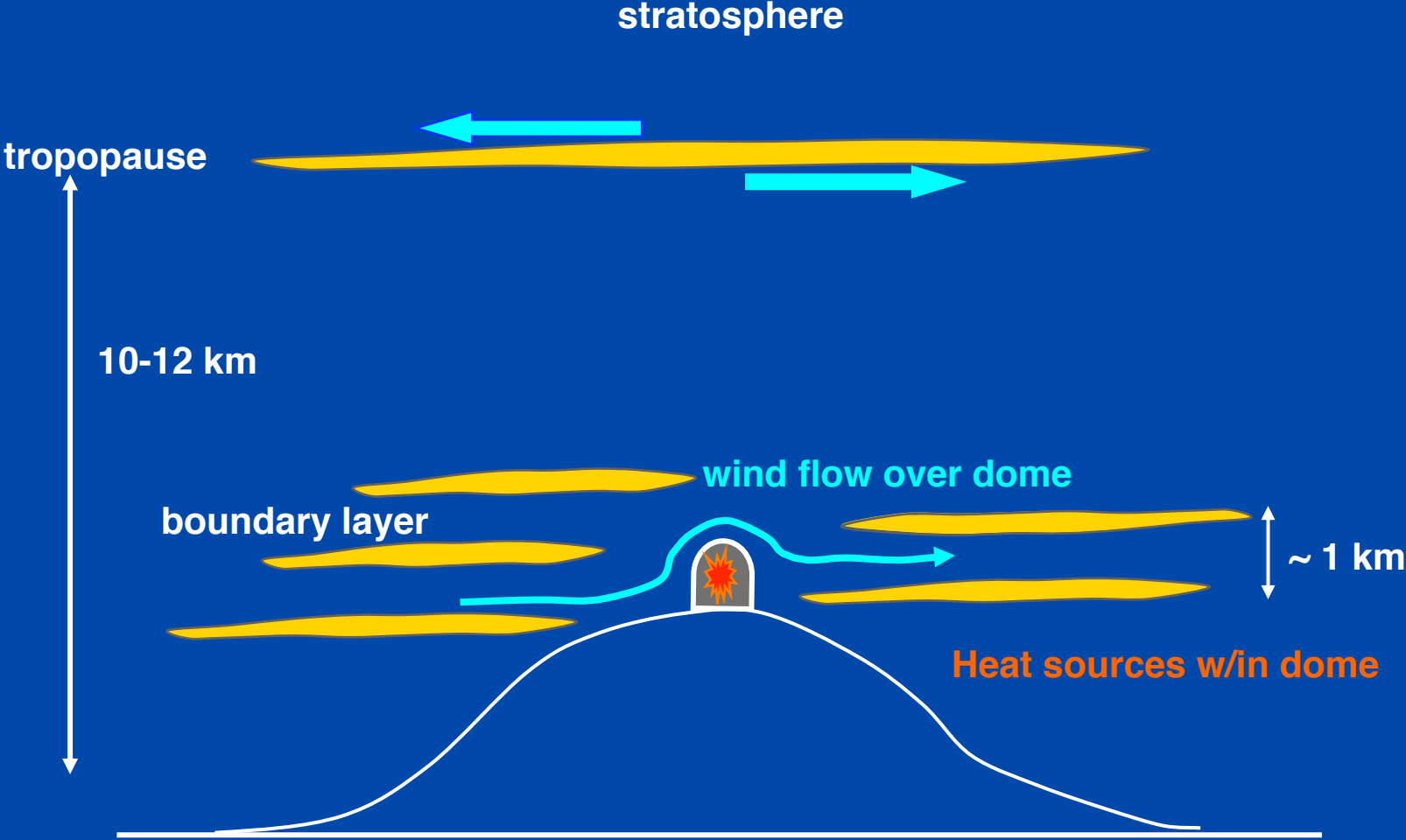
Image is spread out into **speckles**



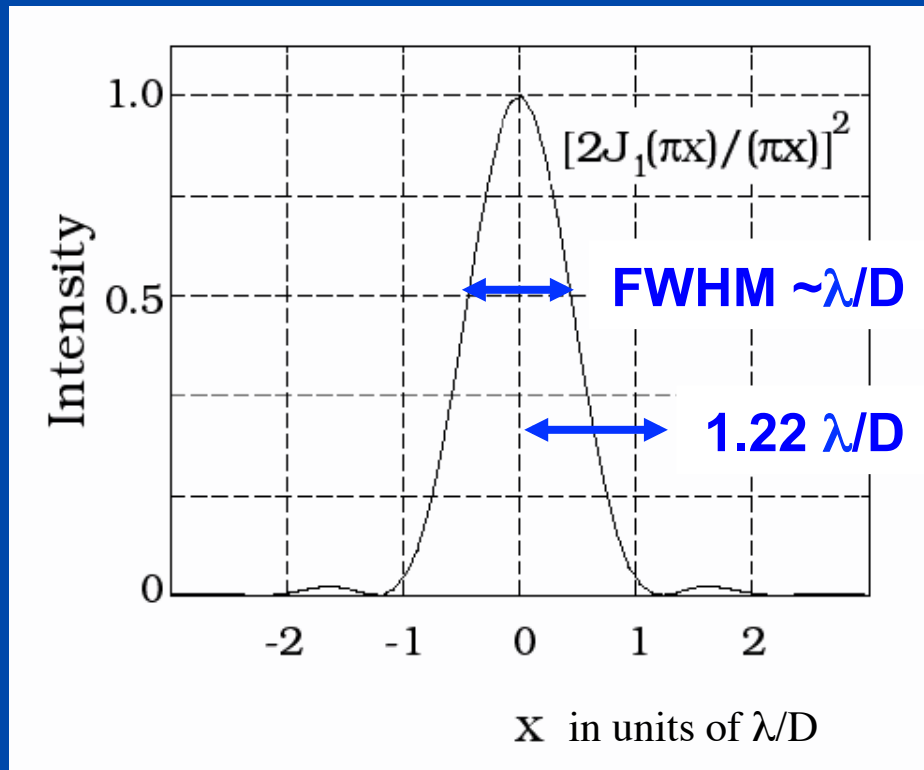
Centroid jumps around (image motion)

“Speckle images”: sequence of short snapshots of a star, taken at MMT Observatory using a commercial H-band camera

Turbulence arises in many places



Imaging through a perfect telescope (circular pupil)



Point Spread Function (PSF):
intensity profile from point source

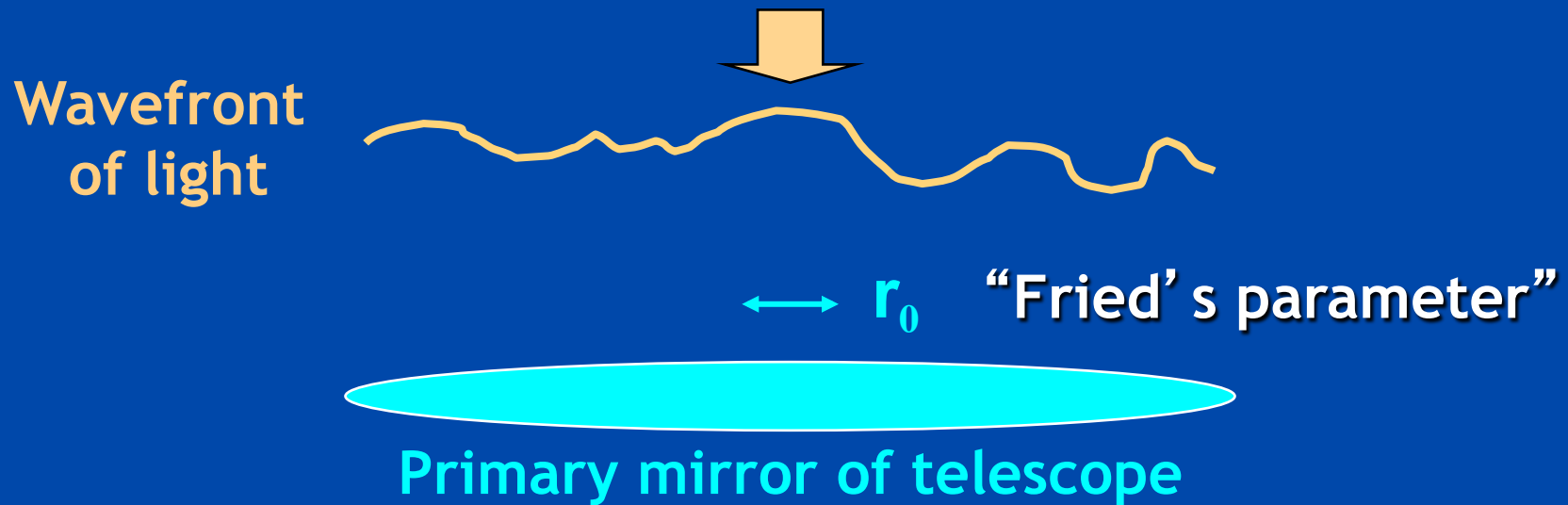
With **no turbulence**,
FWHM is diffraction limit
of telescope, $\theta \sim \lambda / D$

Example:

$$\lambda / D = 0.02 \text{ arc sec for } \lambda = 1 \mu\text{m}, D = 10 \text{ m}$$

With turbulence, image
size gets much larger
(typically 0.5 - 2 arc sec)

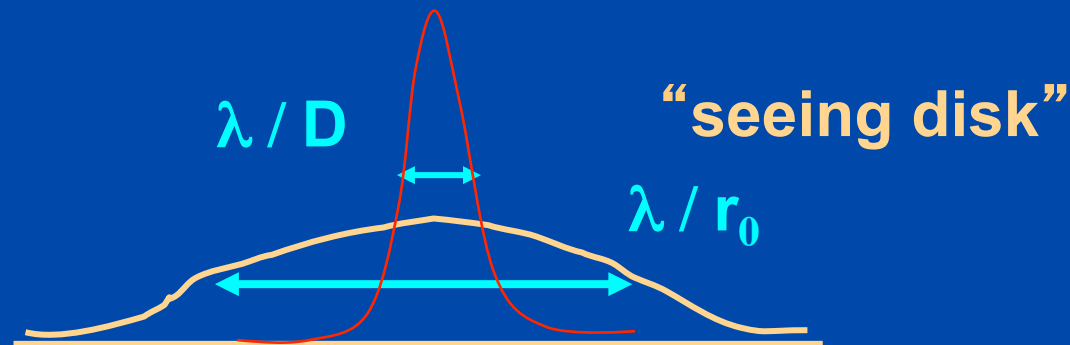
Turbulence strength is characterized by quantity r_0



- "Coherence Length" r_0 : distance over which optical phase distortion has mean square value of 1 rad^2 ($r_0 \sim 15 - 30 \text{ cm}$ at good observing sites)
- Easy to remember: $r_0 = 10 \text{ cm} \Leftrightarrow \text{FWHM} = 1 \text{ arc sec}$ at $\lambda = 0.5 \mu\text{m}$

Effect of turbulence on image size

- If telescope diameter $D \gg r_0$, image size of a point source is $\lambda / r_0 \gg \lambda / D$



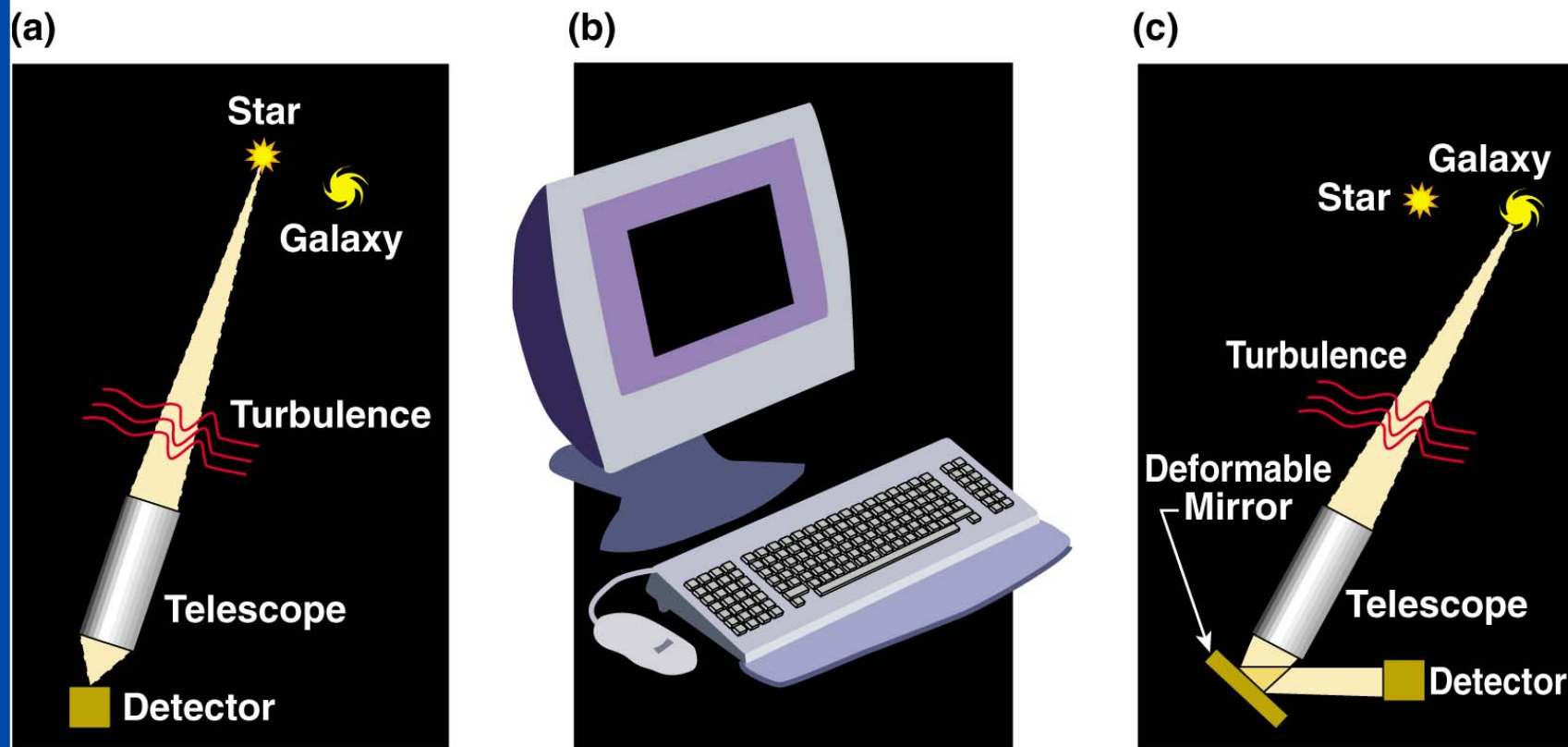
- r_0 is diameter of the circular pupil for which the diffraction limited image and the seeing limited image have the same angular resolution.
- $r_0 \approx 25\text{cm}$ at a good site. So any telescope larger than this has no better spatial resolution!

How does adaptive optics help?

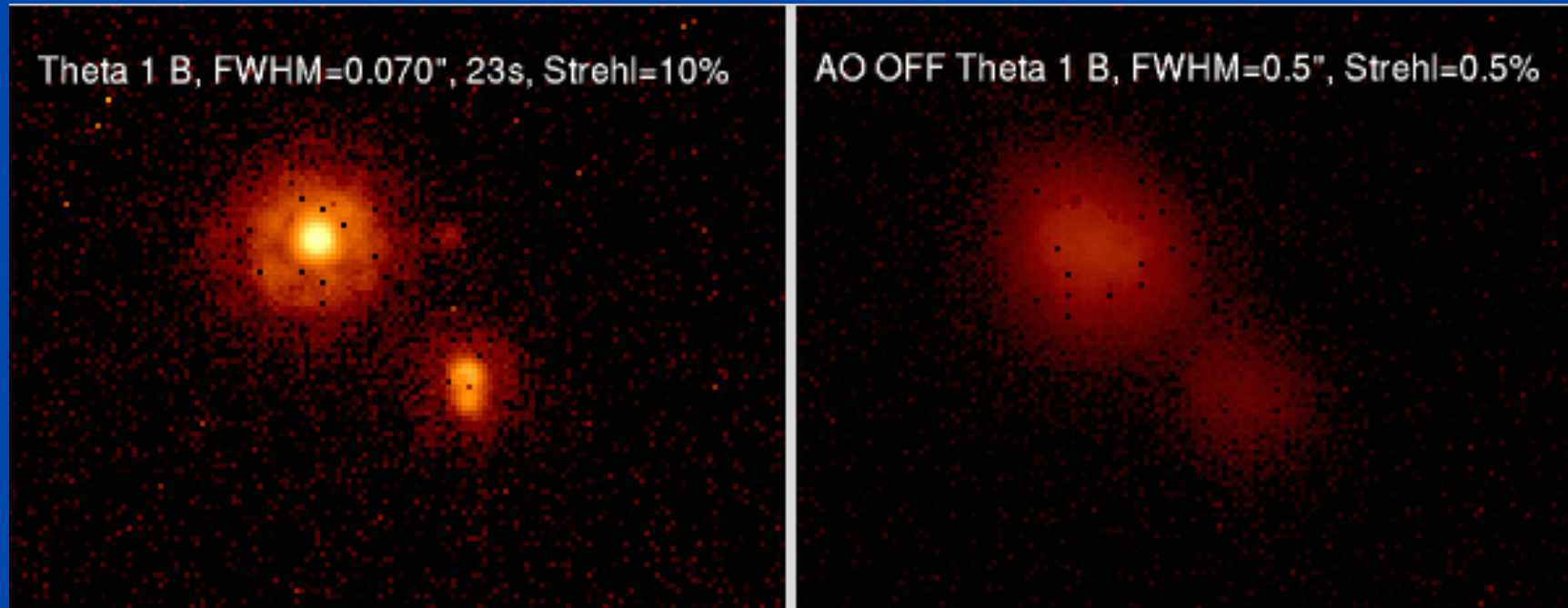
Measure details of blurring from "guide star" near the object you want to observe

Calculate (on a computer) the shape to apply to deformable mirror to correct blurring

Light from both guide star and astronomical object is reflected from deformable mirror; distortions are removed



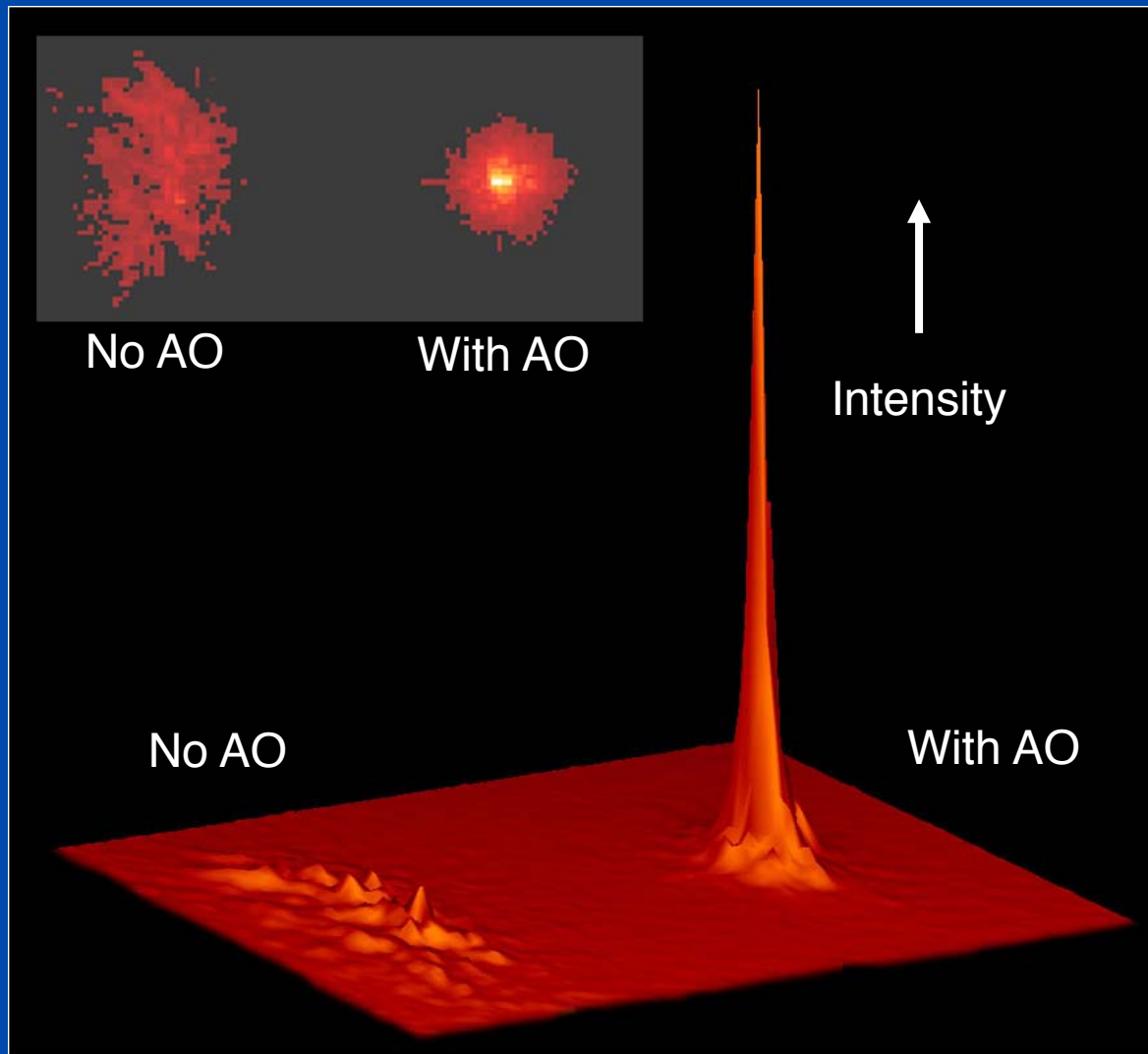
H-band images of a star system, from MMT AO



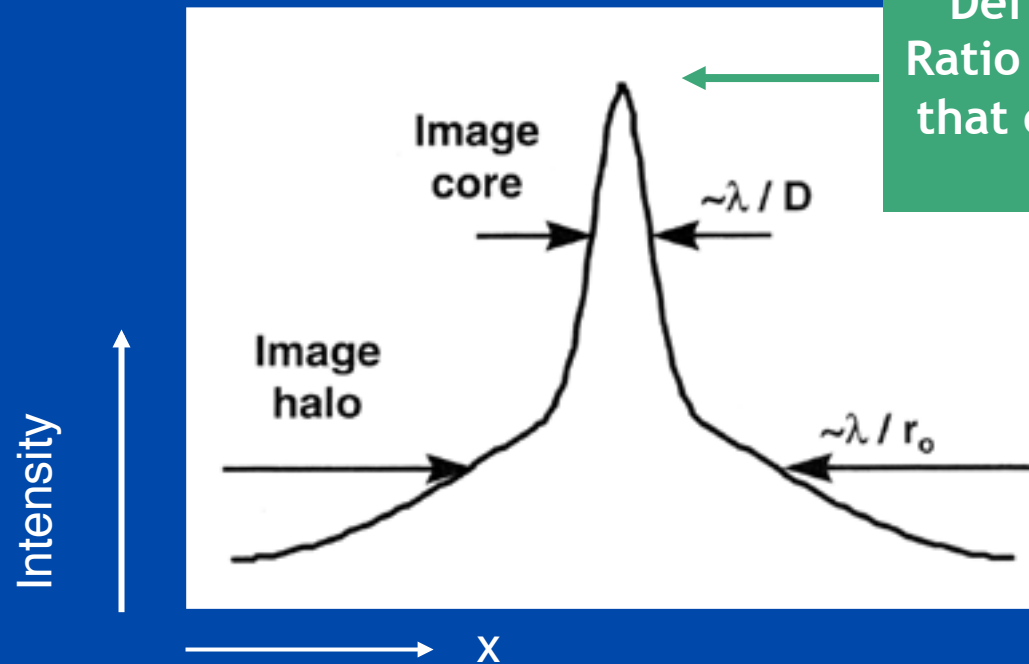
With adaptive optics

No adaptive optics

Adaptive optics increases peak intensity of a point source



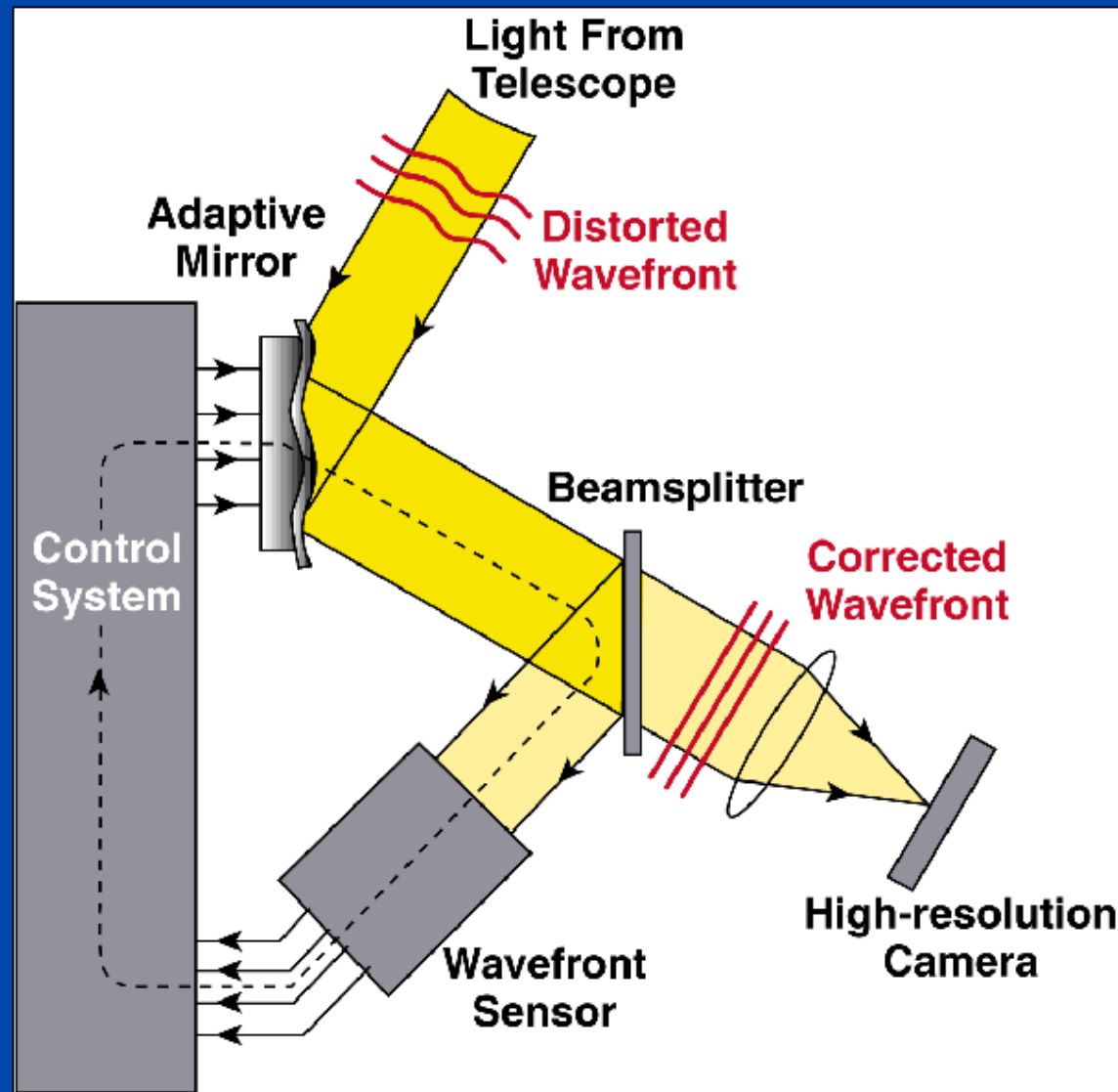
AO produces point spread functions with a “core” and “halo”



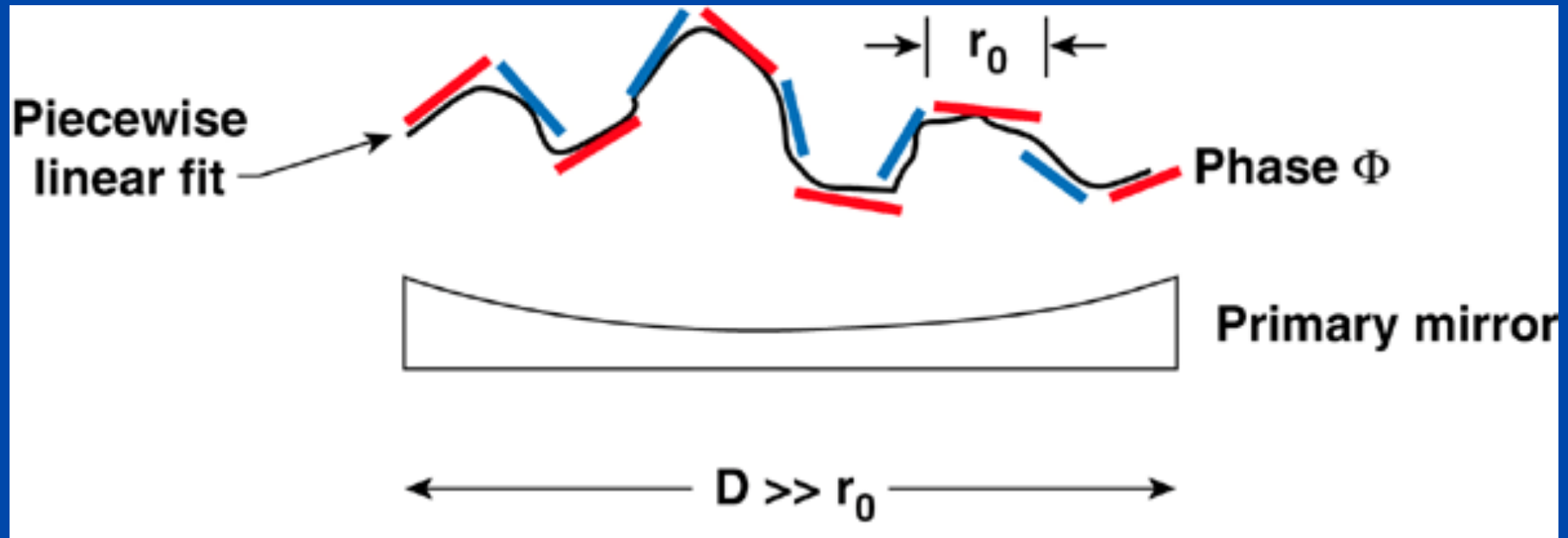
- When AO system performs well, more energy in core
- When AO system is stressed (poor seeing), halo contains larger fraction of energy (diameter $\sim r_0$)
- Ratio between core and halo varies during night

Schematic of adaptive optics system

Feedback loop:
next cycle
corrects the
(small) errors of
the last cycle

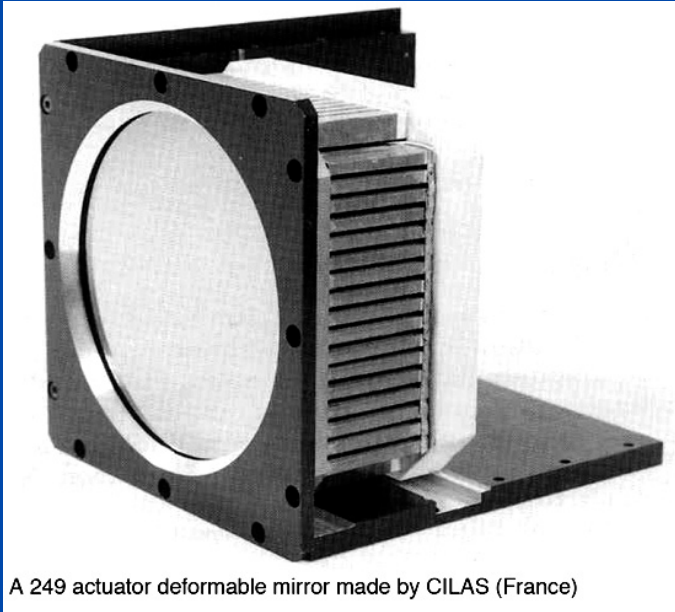


Real deformable mirrors have smooth surfaces

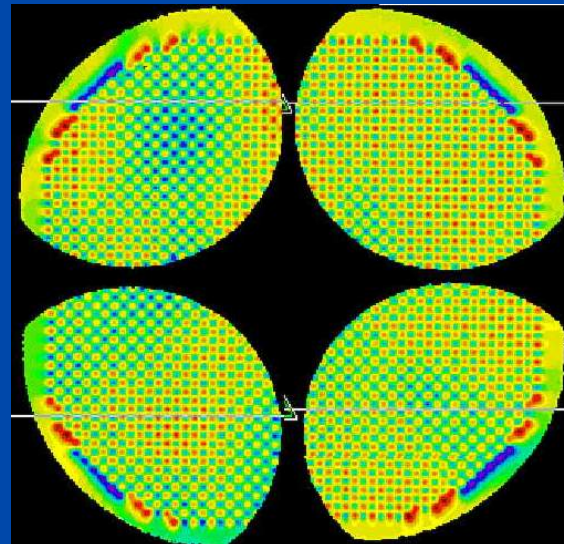
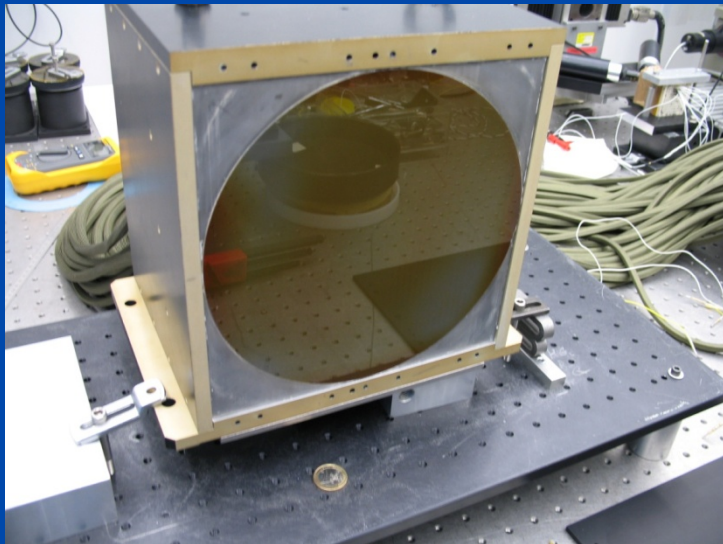


- In practice, a small deformable mirror with a thin bendable face sheet is used
- Placed after the main telescope mirror

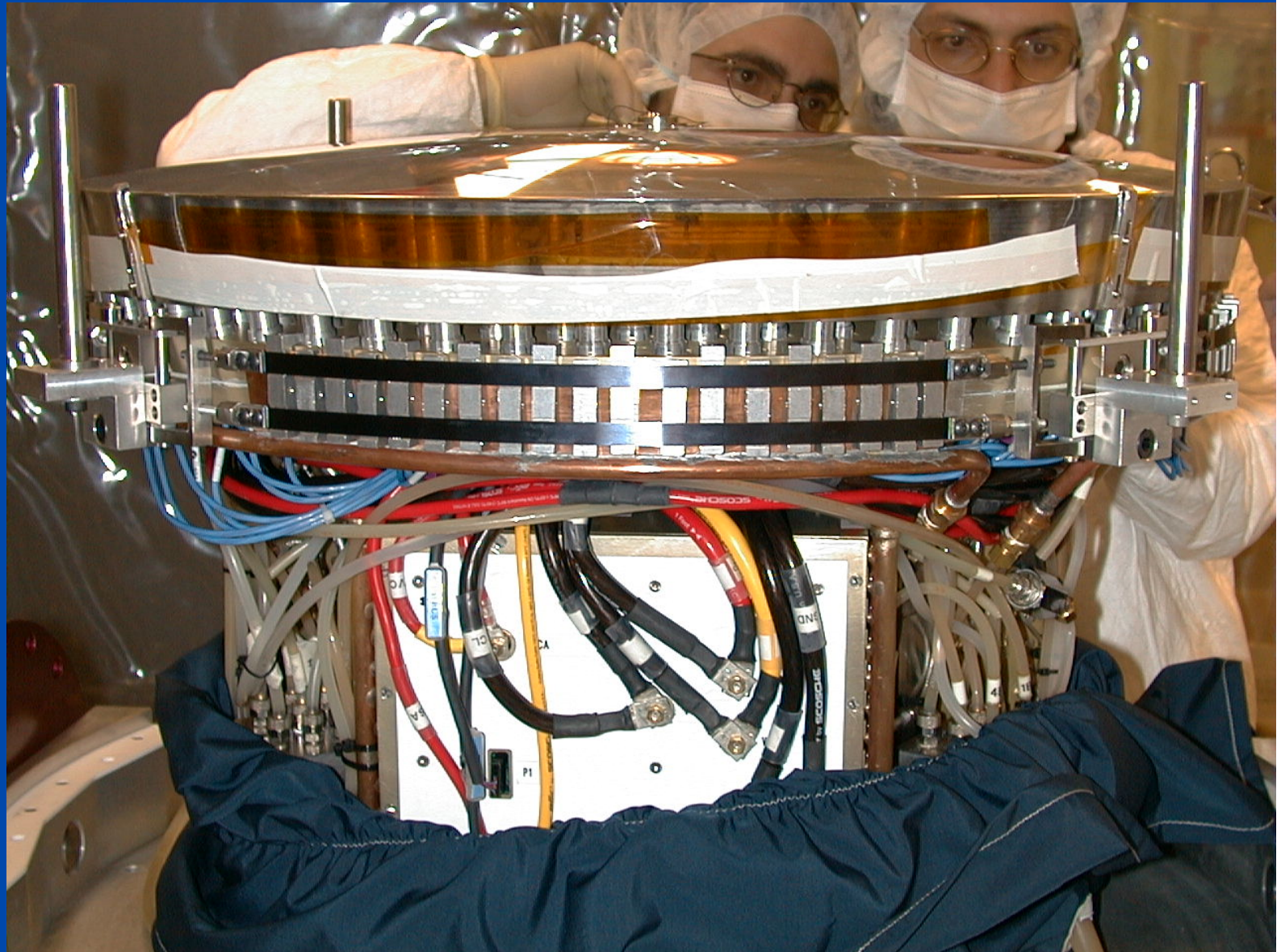
Classical PIEZO actuators



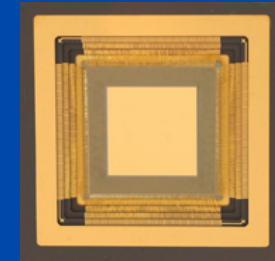
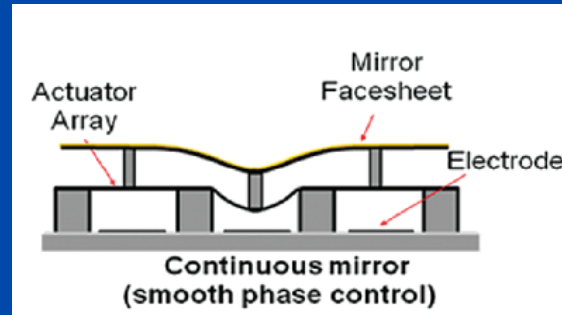
A 249 actuator deformable mirror made by CILAS (France)



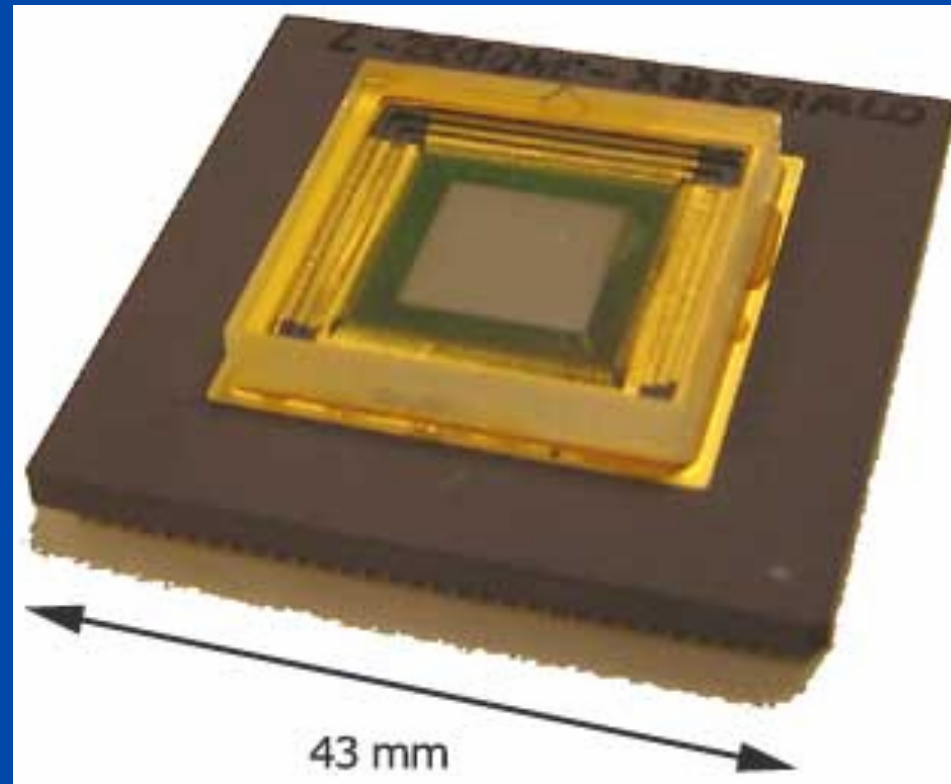
Large DM's are on every ELT technological roadmap



Existing MEMS mirror (sufficient for Hybrid-MOAO)

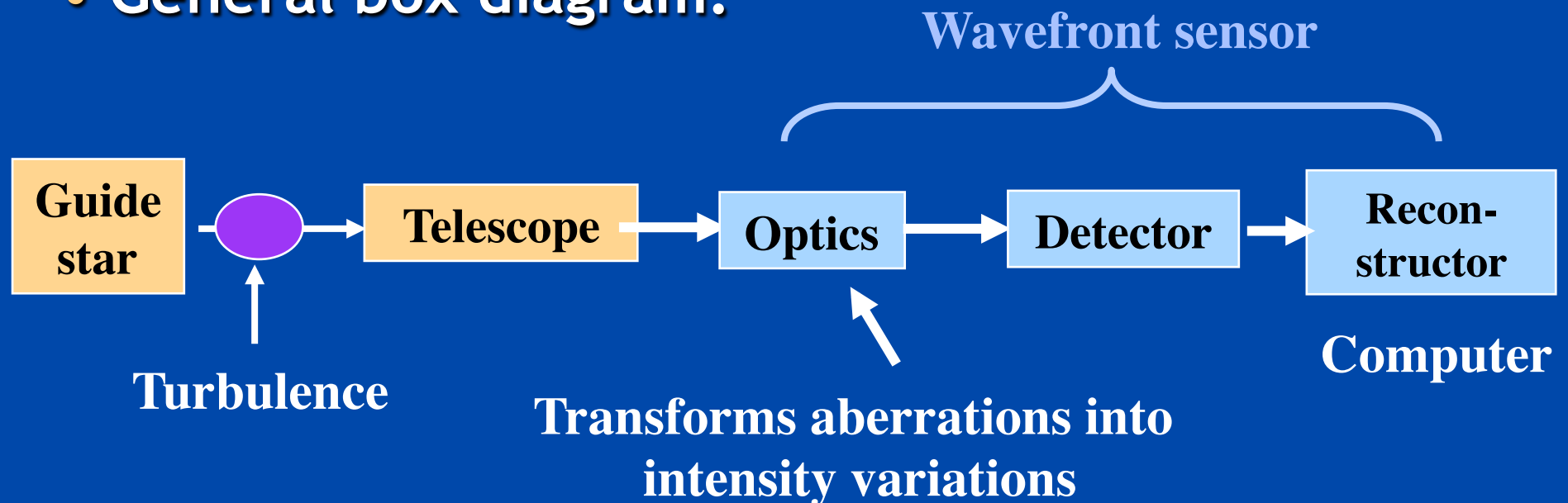


**Boston
Micromachines
32x32 actuator,
1.5 um MEMS
device.
(In Stock)**



Basics of wavefront sensing

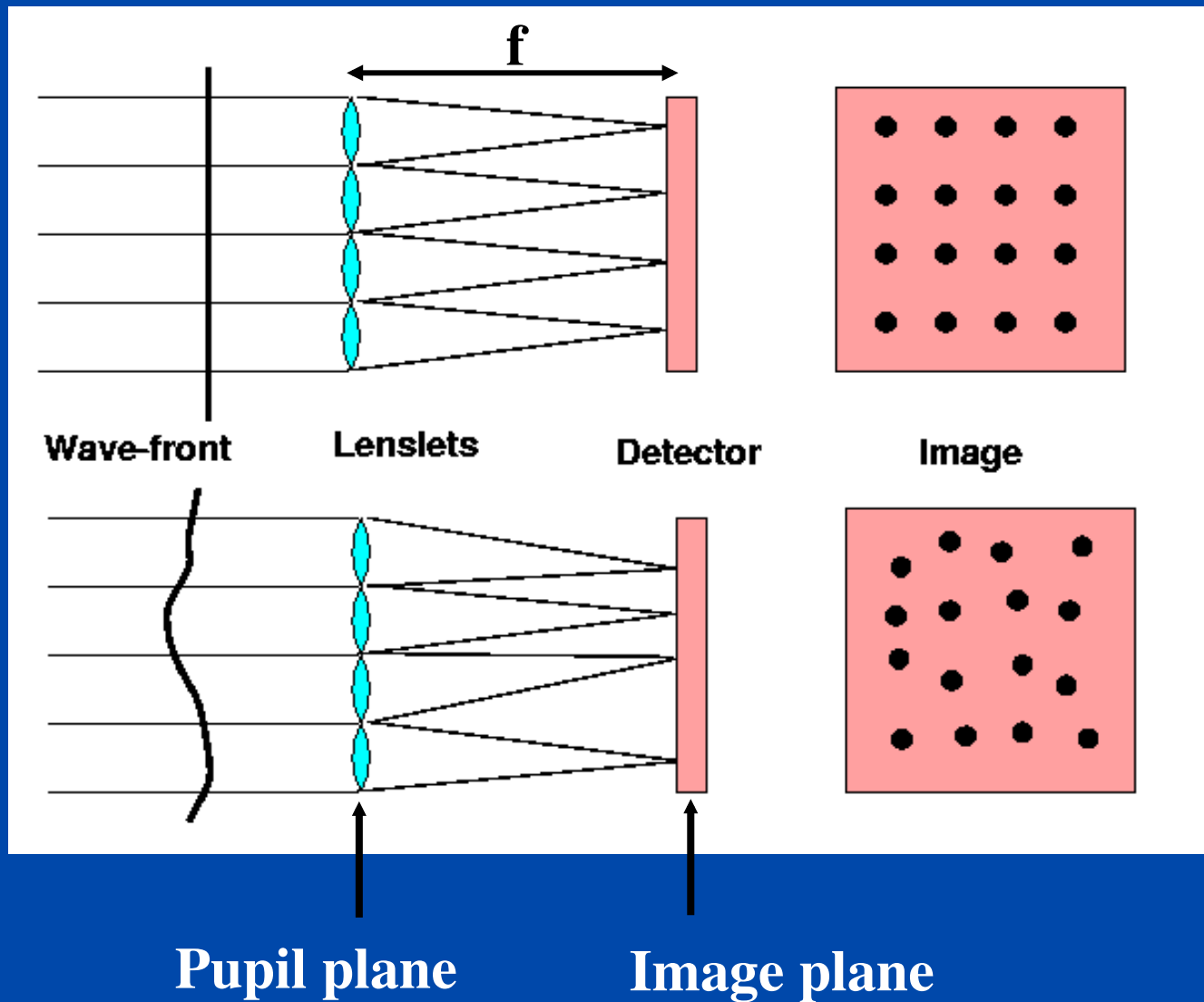
- Measure phase by measuring intensity variations
- Difference between various wavefront sensor schemes is the way in which phase differences are turned into intensity differences
- General box diagram:



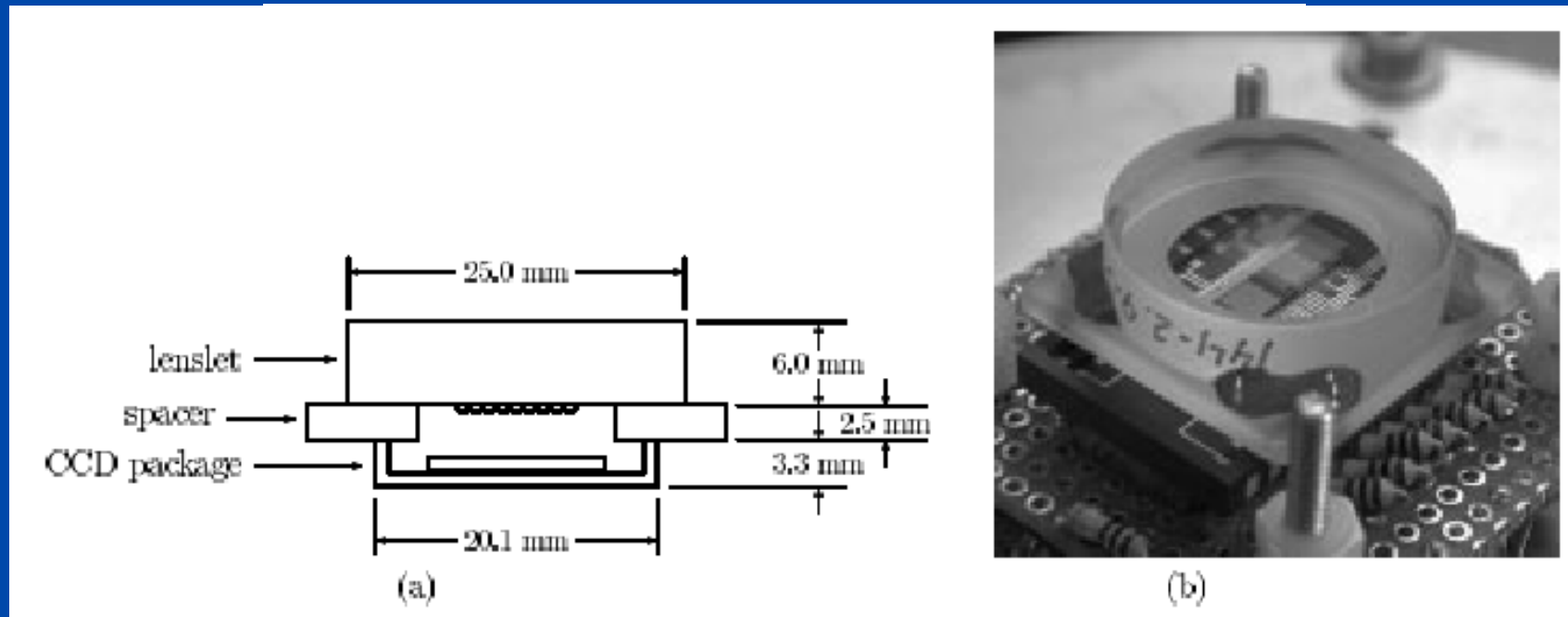
Types of wavefront sensors

- “Direct” in pupil plane: split pupil up into subapertures in some way, then use intensity in each subaperture to deduce phase of wavefront. **REAL TIME**
 - Slope sensing: Shack-Hartmann, pyramid sensing
 - Curvature sensing
- “Indirect” in focal plane: wavefront properties are deduced from whole-aperture intensity measurements made at or near the focal plane. Iterative methods - **take a lot of time.**
 - Image sharpening, multi-dither
 - Phase diversity

Shack-Hartmann wavefront sensor concept - measure subaperture tilts



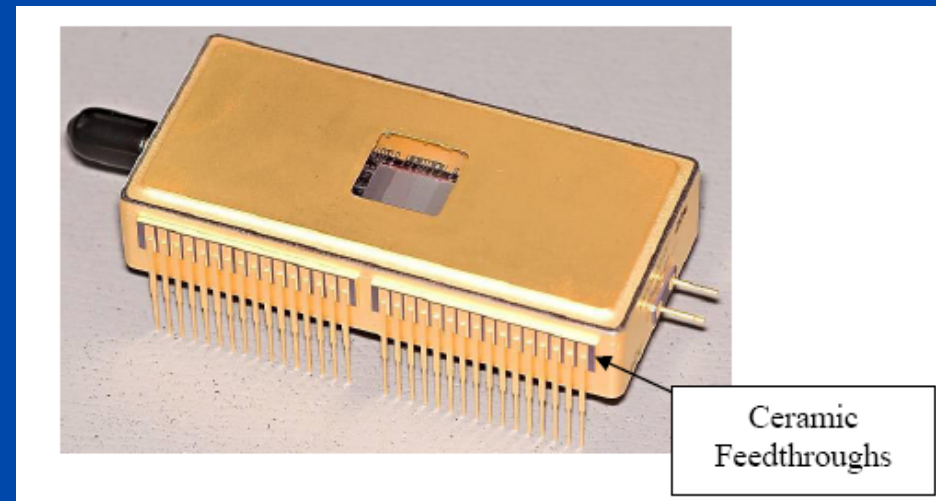
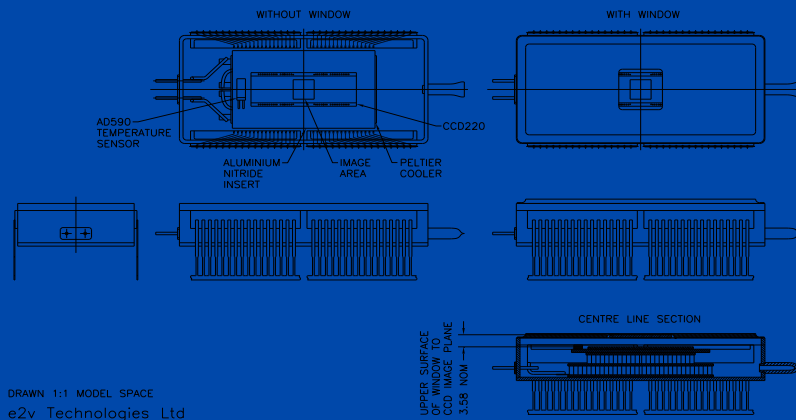
WFS implementation



- Compact
- Time-invariant

CCD rapide

- CCD design complete
- 64 pins
 - 256x256 pixels
 - 1200 trames/s
 - < 1e bruit
 - Refroidissement Peltier

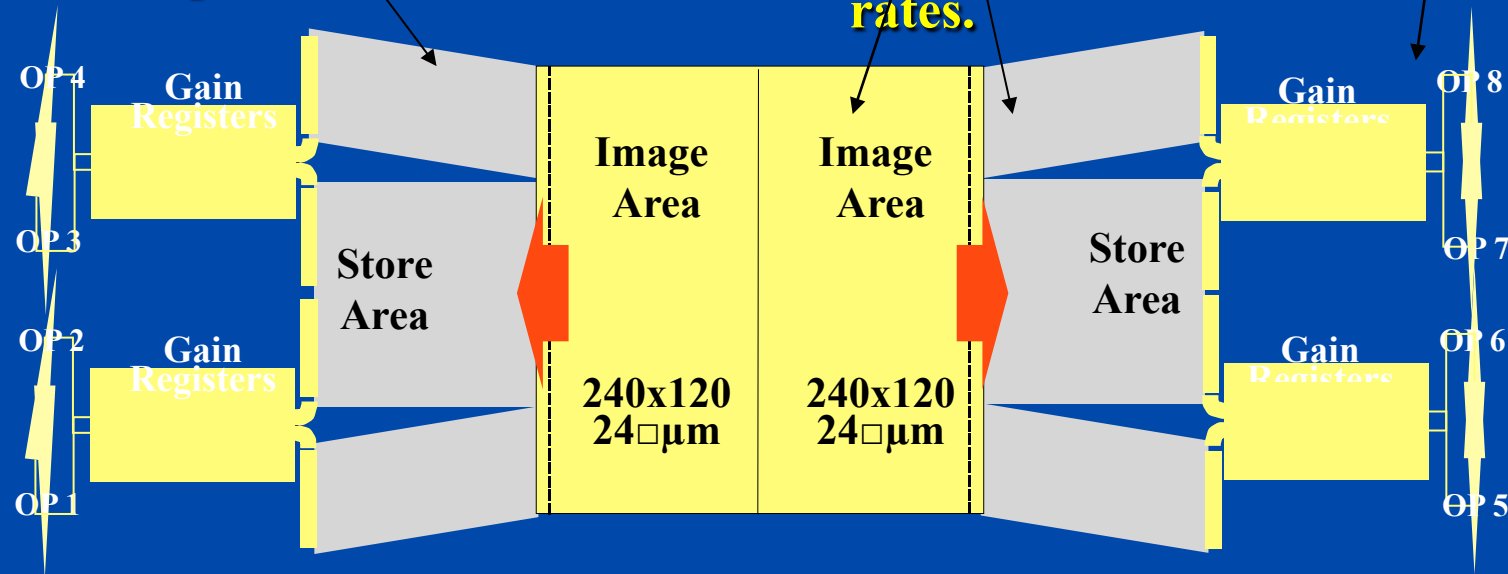


Split frame transfer 8-output back-illuminated e2v L3Vision CCD for WFS.

Store slanted
to allow room
for multiple
outputs.

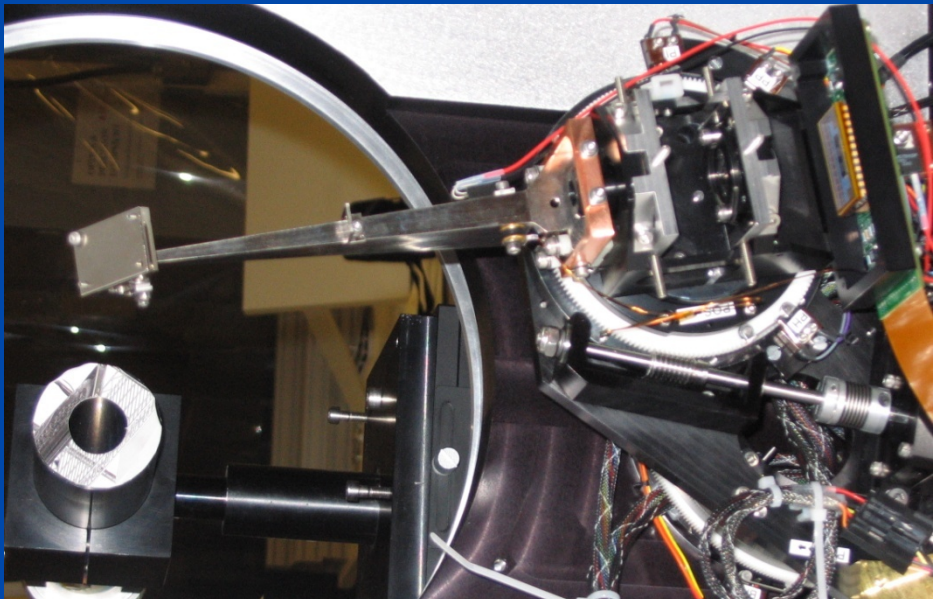
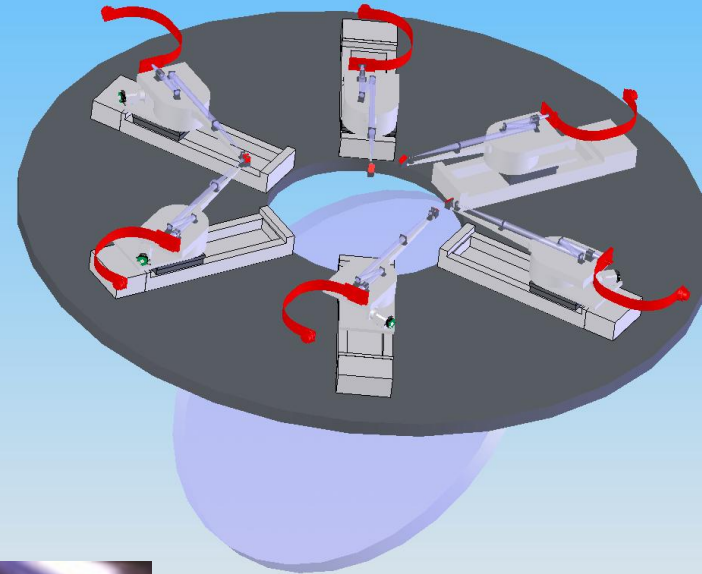
Metal Buttressed
2Φ 10 Mhz Clocks
for fast image to
store transfer
rates.

8 L3Vision Gain
Registers/Outputs.
Each 15Mpix./s.



3. NGS WFS

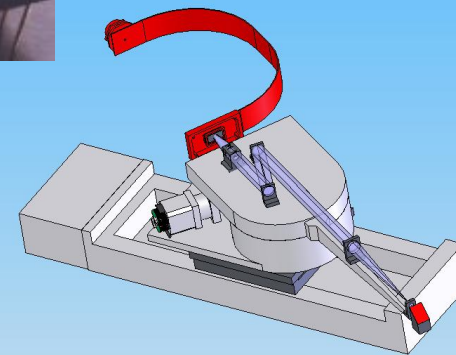
- Radial+Linear stages with encoders offer flexible design with min. vignetting
- 6 probe arms operating in “Meatlocker” just before focal plane
- 2x2 lenslets



Flamingos2 OI WFS



EEV CCD60



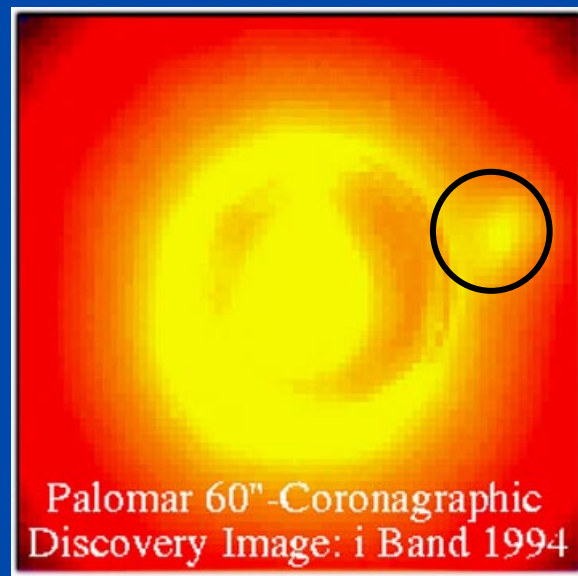
Astronomical observatories with AO on 6 - 10 m telescopes

- European Southern Observatory (Chile)
 - 4 telescopes (MACAO, NAOS, CRIRES, SPIFFI, MAD)
- Keck Observatory, (Hawaii)
 - 2 telescopes
- Gemini North Telescope (Hawaii), ALAIR + LGS
- Subaru Telescope, Hawaii
- MMT Telescope, Arizona

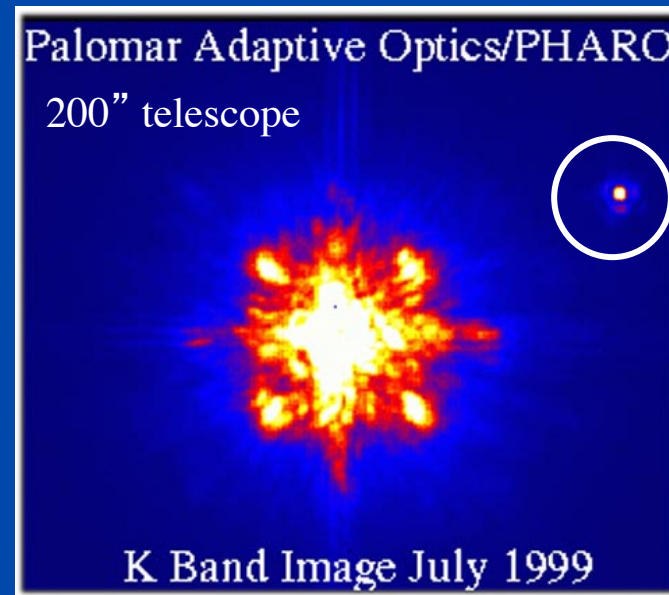
- Soon:
 - Gemini South Telescope, Chile (MCAO)
 - Large Binocular Telescope, Arizona

Adaptive optics makes it possible to find faint companions around bright stars

Two images from Palomar of a brown dwarf companion to GL 105



No AO

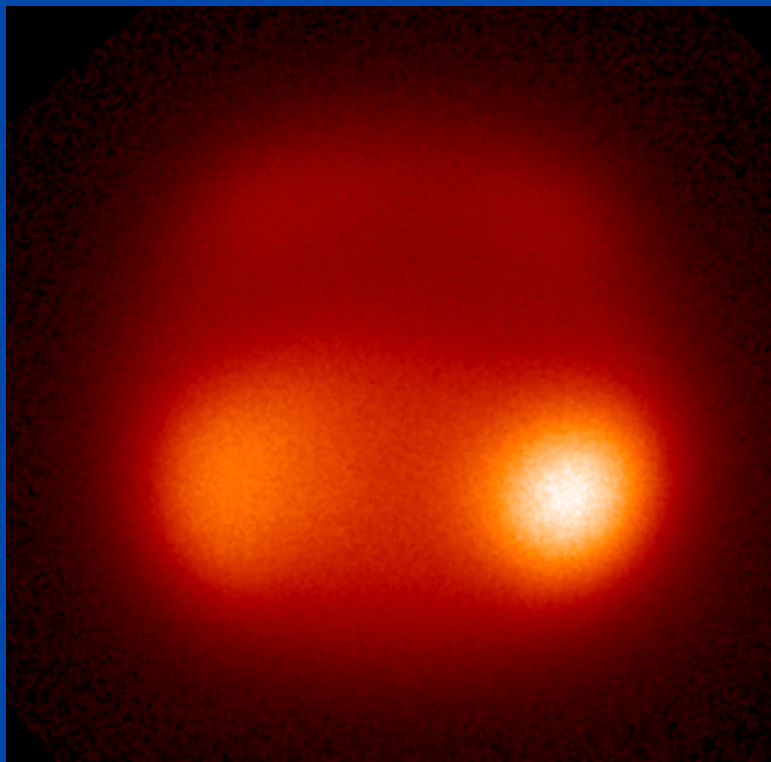


With AO

Credit: David Golimowski

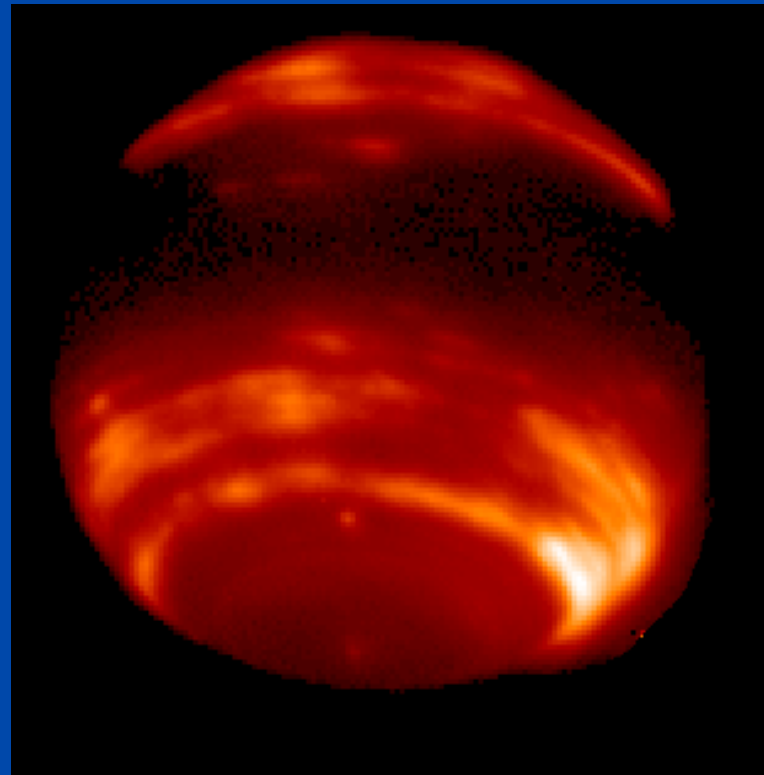
Neptune in infra-red light (1.65 microns)

Without adaptive optics



May 24, 1999

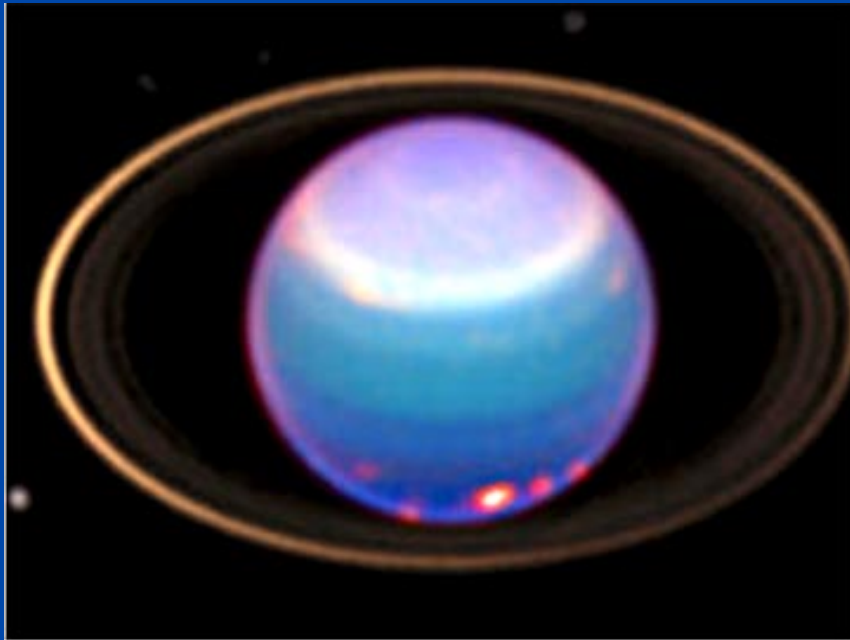
With adaptive optics



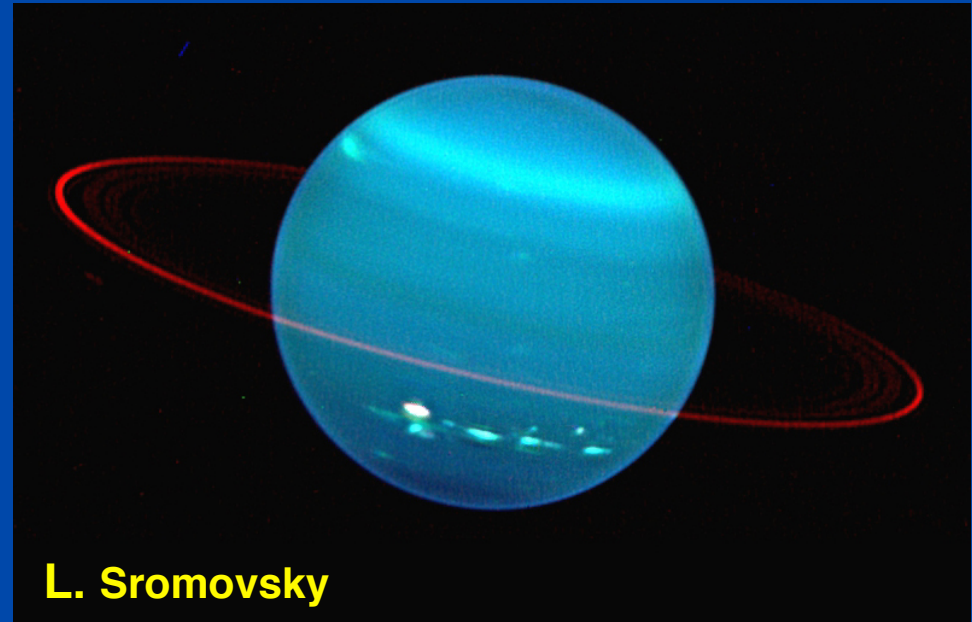
June 27, 1999

2.3 arc sec

Uranus with Hubble Space Telescope and Keck AO



HST, Visible



Keck AO, IR

Lesson: Keck in near IR has ~ same resolution as Hubble in visible

Some frontiers of astronomical adaptive optics

- **Current systems (natural and laser guide stars):**
 - How can we measure the Point Spread Function while we observe?
 - How accurate can we make our photometry? astrometry?
 - What methods will allow us to do high-precision spectroscopy?
- **Future systems:**
 - Can we push new AO systems to achieve very high contrast ratios, to detect planets around nearby stars?
 - How can we achieve a wider AO field of view?
 - How can we do AO for visible light (replace Hubble on the ground)?
 - How can we do laser guide star AO on future 30-m telescopes?

Frontiers in AO technology

- New kinds of deformable mirrors with > 5000 degrees of freedom
- Wavefront sensors that can deal with this many degrees of freedom
- (ultra) Fast computers
- Innovative control algorithms
- “Tomographic wavefront reconstruction” using multiple laser guide stars
- New approaches to doing visible-light AO