

# One-Dimensional Euler Equations

## 1. Conservative Formulation

$$\underline{U}_t + \underline{F}(\underline{U})_x = \underline{0}$$

$$\underline{U} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} \rho \\ \rho u \\ E \end{bmatrix}$$

$$\underline{F} = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \end{bmatrix} = \begin{bmatrix} \rho u \\ \rho u^2 + p \\ u(E+p) \end{bmatrix}$$

$$E = \rho \left( \frac{1}{2} u^2 + e \right)$$

$$e = e(\rho, p) = \frac{p}{(\gamma-1)\rho} \quad \text{for ideal gases}$$

$$a = \sqrt{\frac{\gamma p}{\rho}} \quad \text{sound speed}$$

We can express the conservation law in quasi-linear form:

$$\underline{U}_t + \underline{A}(\underline{U}) \underline{U}_x = \underline{0}$$

where  $A_{ij} = \frac{\partial f_i}{\partial u_j}$

To compute  $A_{ij}$ : First express all quantities of  $\underline{F}$  via quantities of  $\underline{U} = (\rho, \rho u, E) = (u_1, u_2, u_3)$

$$\text{Using } E = \frac{1}{2} \rho u^2 + \rho e = \frac{1}{2} \rho u^2 + \rho \frac{p}{(\gamma-1)\rho} = \frac{1}{2} \rho u^2 + \frac{p}{\gamma-1}$$

$$\Rightarrow p = (\gamma-1) \left[ E - \frac{1}{2} \rho u^2 \right] = (\gamma-1) \left[ u_3 - \frac{1}{2} \frac{u_2^2}{u_1} \right]$$

Which gives us:

$$\begin{aligned} \underline{F} &= \begin{bmatrix} f_1 \\ f_2 \\ f_3 \end{bmatrix} = \begin{bmatrix} 3u \\ 3u^2 + p \\ u(\epsilon + p) \end{bmatrix} = \begin{bmatrix} u_2 \\ \frac{u_2^2}{u_1} + (r-1)\left[u_3 - \frac{1}{2}\frac{u_2^2}{u_1}\right] \\ \frac{u_2}{u_1}\left(u_3 + (r-1)\left[u_3 - \frac{1}{2}\frac{u_2^2}{u_1}\right]\right) \end{bmatrix} \\ &= \begin{bmatrix} u_2 \\ \frac{1}{2}(3-r)\frac{u_2^2}{u_1} + (r-1)u_3 \\ r\frac{u_2}{u_1}u_3 - \frac{1}{2}(r-1)\frac{u_2^3}{u_1^2} \end{bmatrix} \end{aligned}$$

Computing  $A_{ij} = \frac{\partial f_i}{\partial a_j}$ :

$$A = \begin{bmatrix} 0 & 1 & 0 \\ -\frac{1}{2}(3-r)\frac{u_2^2}{u_1^2} & 2\frac{u_2}{u_1} + (r-1)\frac{-u_2}{u_1} & (r-1) \\ -r\frac{u_2}{u_1^2}u_3 + (r-1)\frac{u_2^3}{u_1^3} & r\frac{u_3}{u_1} - \frac{3}{2}(r-1)\frac{u_2^2}{u_1^2} & r\frac{u_2}{u_1} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 & 0 \\ \frac{r-3}{2}\frac{u_2^2}{u_1^2} & (3-r)\frac{u_2}{u_1} & r-1 \\ -r\frac{u_2 u_3}{u_1^2} + (r-1)\frac{u_2^3}{u_1^3} & r\frac{u_3}{u_1} + \frac{3}{2}(1-r)\frac{u_2^2}{u_1^2} & r\frac{u_2}{u_1} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 & 0 \\ \frac{r-3}{2}u^2 & (3-r)u & r-1 \\ -r\frac{u\epsilon}{s} + (r-1)u^3 & r\frac{\epsilon}{s} + \frac{3}{2}(1-r)u^2 & ru \end{bmatrix}$$

The Eigenvalues of the Jacobian matrix are

$$\lambda_1 = u - a, \quad \lambda_2 = u, \quad \lambda_3 = u + a$$

The corresponding eigenvectors are

$$\underline{K}_1 = \begin{bmatrix} 1 \\ u - a \\ \frac{E+p}{s} - ua \end{bmatrix}, \quad \underline{K}_2 = \begin{bmatrix} 1 \\ u \\ \frac{1}{2}u^2 \end{bmatrix}, \quad \underline{K}_3 = \begin{bmatrix} 1 \\ u + a \\ \frac{E+p}{s} + ua \end{bmatrix}$$

(Proof is easy, but long calculation by hand)

## 2. Primitive Variable Formulation

Use  $\underline{w} = \begin{pmatrix} s \\ u \\ p \end{pmatrix}$

Getting equations from conservative to primitive variables:

$$\cdot = \frac{\partial}{\partial t} \begin{bmatrix} s \\ su \\ E \end{bmatrix} + \frac{\partial}{\partial x} \begin{bmatrix} su \\ su^2 + p \\ u(E+p) \end{bmatrix} = 0$$

The first equation,  $\boxed{\frac{\partial s}{\partial t} + \frac{\partial s}{\partial x} u + s \frac{\partial u}{\partial x} = 0}$  is fine in primitive variables too.

For the second:

$$s_t u + s u_t + s_x u^2 + 2s u u_x + p_x = 0$$

$$= u \underbrace{[s_t + s_x u + s u_x]}_{=0: \text{first equation}} + s [u_t + u u_x + \frac{1}{s} p_x] = 0$$

$$\Rightarrow \boxed{u_t + u u_x + \frac{1}{s} p_x = 0}$$

Third equation:

$$E_t + u_x(E+p) + u(E_x + p_x) = 0$$

$$E = \frac{1}{2} S u^2 + s e = \frac{1}{2} S u^2 + \frac{f}{\gamma-1}$$

$$E_x = \frac{1}{2} u^2 S_x + S u u_x + \frac{f_x}{\gamma-1}$$

$$E_t = \frac{1}{2} u^2 S_t + S u u_t + \frac{f_t}{\gamma-1}$$

$$\Rightarrow \frac{1}{2} u^2 S_t + S u u_t + \frac{f_t}{\gamma-1} + u_x \left( \frac{1}{2} S u^2 + \frac{f}{\gamma-1} + p \right) + u \left( \frac{1}{2} u^2 S_x + S u u_x + \frac{f_x}{\gamma-1} + p_x \right) = 0$$

$$= \frac{1}{2} u^2 S_t + S u u_t + \frac{f_t}{\gamma-1} + \frac{1}{2} S u^2 u_x + \frac{f}{\gamma-1} u_x + \frac{1}{2} u^3 S_x + S u^2 u_x + u \frac{f_x}{\gamma-1} + u p_x$$

$$= \frac{1}{2} u^2 \left[ S_t + S u_x + u S_x \right] + S u \left[ u_t + u u_x + \frac{1}{S} p_x \right] + \frac{1}{\gamma-1} \left[ p_t + \gamma p u_x + u p_x \right] = 0$$

$= S u \left[ \frac{f_x}{\gamma-1} + \frac{p_x}{S} \right] = S u \frac{p_x}{S} \left[ \frac{1}{\gamma-1} + \frac{1}{S} \right]$

with  $a^2 = \frac{df}{ds} \Rightarrow \boxed{p_t + S a^2 u_x + u p_x = 0}$

Which leaves us with the equations:

$$\boxed{\begin{aligned} S_t + u S_x + S u_x &= 0 \\ u_t + u u_x + \frac{1}{S} p_x &= 0 \\ p_t + S a^2 u_x + u p_x &= 0 \end{aligned}}$$

or  $\underline{w}_t + \underline{A}(\underline{w}) \underline{w}_x = 0$  with

$$\underline{w} = \begin{bmatrix} S \\ u \\ p \end{bmatrix} \quad \text{and} \quad \underline{A} = \begin{bmatrix} u & S & 0 \\ 0 & u & 1/S \\ 0 & S a^2 & u \end{bmatrix}$$

## Computing eigenvalues:

$$\det(\underline{A} - \lambda \underline{I}) = 0 = \begin{vmatrix} u - \lambda & s & 0 \\ 0 & u - \lambda & 1/s \\ 0 & sa^2 & u - \lambda \end{vmatrix}$$

$$= (u - \lambda)^3 + 0 + 0 - 0 - sa^2 \cdot \frac{1}{s} (u - \lambda) =$$

$$= (u - \lambda) [(u - \lambda)^2 - a^2]$$

$$\Rightarrow \lambda_1 = u$$

$$(u - \lambda_{2,3})^2 - a^2 = 0 \Rightarrow u - \lambda_{2,3} = \pm a$$

$$\Rightarrow \lambda_{2,3} = u \pm a$$

## Computing eigenvectors

$$\lambda = u$$

$$\begin{pmatrix} u & s & 0 \\ 0 & u & 1/s \\ 0 & sa^2 & u \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = u \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$ux + sy = ux \Rightarrow y = 0$$

$$uy + \frac{1}{s}z = uy \Rightarrow z = 0$$

$$\Rightarrow \text{valid for all } x \Rightarrow \underline{K}(\lambda = u) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda = u \pm a: \begin{pmatrix} u & s & 0 \\ 0 & u & 1/s \\ 0 & sa^2 & u \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = (u \pm a) \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$ux + sy = (u \pm a)x \quad \Rightarrow \quad sy = \pm ax$$

$$uy + \frac{1}{s}z = (u \pm a)y \quad \Rightarrow \quad \frac{1}{s}z = \pm ay$$

$$sa^2y + uz = (u \pm a)z \quad \Rightarrow \quad sa^2y = \pm az$$

Let  $x = 1$

$$\hookrightarrow y = \mp a/s, \quad z = \pm sa y = \pm sa(\mp a/s) = \mp a^2$$

$$\Rightarrow K(\lambda = u + a) = \begin{pmatrix} 1 \\ -a/s \\ a^2 \end{pmatrix}$$

$$\Rightarrow K(\lambda = u - a) = \begin{pmatrix} 1 \\ a/s \\ a^2 \end{pmatrix}$$

Similarly, the left eigenvectors are

$$\underline{L}^{(1)} = \beta_1 (0, 1, -1/sa)$$

$$\underline{L}^{(2)} = \beta_2 (1, 0, -1/a^2)$$

$$\underline{L}^{(3)} = \beta_3 (0, 1, 1/sa)$$

By choosing appropriate normalisation parameters, the left and right eigenvectors are bi-orthonormal:

$$\underline{L}^{(j)} \cdot \underline{K}^{(i)} = \begin{cases} 1 & i=j \\ 0 & \text{otherwise} \end{cases}$$

## Characteristic equations:

The eigenvalues  $\lambda_1, \lambda_2, \lambda_3$  define characteristic directions  $\frac{dx}{dt} = \lambda_i$ . For a set of partial differential equations, a characteristic equation says that in a direction,  $\underline{L}^{(i)} \cdot d\underline{w} = 0$

$$\begin{aligned} \Rightarrow \quad dp - sa \, du &= 0 \quad \text{along } dx/dt = \lambda_1 = u - a \\ dp - a^2 ds &= 0 \quad \text{along } dx/dt = \lambda_2 = u \\ dp + sa \, du &= 0 \quad \text{along } dx/dt = \lambda_3 = u + a \end{aligned}$$

These relations hold true along characteristic directions

## Entropy Formulation

Use entropy instead of pressure as primitive variable:  $\underline{w} = (S, u, s)^T$

$$\text{with } s = C_v \ln\left(\frac{p}{\rho^{\gamma}}\right) + C_0 \Leftrightarrow p = C_1 s^{\gamma} e^{s/C_v}$$

The entropy satisfies the following PDE:

$$S_t + u S_x = 0$$

$$\text{Proof: } s = C_v \ln\left(\frac{p}{\rho^{\gamma}}\right) + C_0 = C_v (\ln p - \gamma \ln \rho) + C_0$$

$$\begin{aligned} \text{Then } S_t &= C_v \left( \frac{1}{p} p_t - \frac{\gamma}{\rho} \rho_t \right) = \frac{C_v}{\rho} \left( p_t - \frac{\gamma p}{\rho} \rho_t \right) \\ &= \frac{C_v}{\rho} (p_t - a^2 \rho_t) \end{aligned}$$

$$\text{analogously: } S_x = \frac{C_v}{\rho} (p_x - a^2 \rho_x)$$

Using  $p_t + \gamma a^2 u_x + u p_x = 0$ :

$$\begin{aligned} S_t + u S_x &= \frac{C_v}{p} [p_t + u p_x - a^2 S_t - a^2 S_x u] \\ &= \frac{C_v}{p} [-\gamma a^2 u_x - u p_x + u p_x - a^2 S_t - a^2 S_x u] \\ &= \frac{C_v}{p} [-\gamma a^2 (S_t + S_x u + S u_x)] = 0 \end{aligned}$$

$$\Rightarrow \boxed{S_t + u S_x = \frac{ds}{dt} = 0}$$

$$\Rightarrow p = C_1 \gamma^{\gamma} e^{s/C_v} = C \gamma^{\gamma} \quad \text{in regions of smooth flow.}$$

The eigenvalues for the entropy formulation are again  $\lambda_1 = u - a$ ,  $\lambda_2 = u$ ,  $\lambda_3 = u + a$

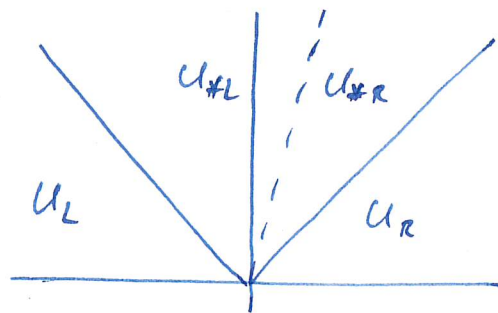
with eigenvectors

$$\underline{K}^{(1)} = \begin{bmatrix} 1 \\ -a/\gamma \\ 0 \end{bmatrix}, \quad \underline{K}^{(2)} = \begin{bmatrix} -\frac{\partial p}{\partial s} \\ 0 \\ a^2 \end{bmatrix}, \quad \underline{K}^{(3)} = \begin{bmatrix} 1 \\ a/\gamma \\ 0 \end{bmatrix}$$



### 3. Elementary Wave Solutions of the Riemann Problem

The solution of the Riemann problem is described as a set of elementary waves (rarefactions, contacts, shocks).



There are three waves associated with the three characteristic fields corresponding to the three Eigenvectors.

Reminder:  $\underline{K}^{(1)} = \begin{pmatrix} 1 \\ u - a \\ \frac{E+p}{S} - ua \end{pmatrix}$ ,  $\underline{K}^{(2)} = \begin{pmatrix} 1 \\ u \\ \frac{1}{2}u^2 \end{pmatrix}$ ,  $\underline{K}^{(3)} = \begin{pmatrix} 1 \\ u + a \\ \frac{E+p}{S} + ua \end{pmatrix}$

$\lambda_1 = u - a$ ,  $\lambda_2 = u$ ,  $\lambda_3 = u + a$

The  $\underline{K}^{(2)}$  characteristic field is linearly degenerate:

$$\nabla \lambda_2 \cdot \underline{K}^{(2)} = 0$$

$$\lambda_2 = u = \frac{u_2}{u_1}$$

$$\nabla \lambda_2 = \begin{pmatrix} \partial \lambda_2 / \partial u_1 \\ \partial \lambda_2 / \partial u_2 \\ \partial \lambda_2 / \partial u_3 \end{pmatrix} = \begin{pmatrix} -u_2 / u_1^2 \\ 1 / u_1 \\ 0 \end{pmatrix} = \begin{pmatrix} -S u / S^2 \\ 1 / S \\ 0 \end{pmatrix} = \begin{pmatrix} -u / S \\ 1 / S \\ 0 \end{pmatrix}$$

$$\nabla \lambda_2 \cdot \underline{K}^{(2)} = -u/S + u/S + 0 = 0 \quad \forall u, S, E$$

The  $\underline{K}^{(1)}$ ,  $\underline{K}^{(3)}$  characteristic fields are genuinely non-linear:

$$\nabla \lambda_{1,3} \cdot \underline{K}^{(1,3)} \neq 0$$

$$\lambda_{1,3} = u \pm a = \frac{u_2}{u_1} \pm a$$

$$\nabla \lambda_{1,3} = \begin{pmatrix} -u_2 / u_1^2 \\ 1 / u_1 \\ 0 \end{pmatrix} = \begin{pmatrix} -u / S \\ 1 / S \\ 0 \end{pmatrix}$$

$$\nabla \lambda_{1,3} \cdot \underline{K}^{(1,3)} = -\frac{u}{S} + \frac{u \pm a}{S} + 0 \neq 0 \quad \forall u, E$$

$= 0$  for  $S=0$  when

$\Rightarrow$  The wave associated with the  $\underline{k}^{(2)}$  characteristic will be a contact wave

$\Rightarrow$  The waves associated with the  $\underline{k}^{(1)}$ ,  $\underline{k}^{(3)}$  characteristic will either be shock or rarefaction wave.

Let's look at the waves individually:

i) Contact wave

Using generalised Riemann invariants  $\frac{du_1}{k_1} = \frac{du_2}{k_2} = \dots = \frac{du_n}{k_n}$

$$\underline{w} = (s, su, E)^T, \quad \underline{k} = (1, u, \frac{1}{2}u^2)$$

$$\Rightarrow \frac{ds}{1} = \frac{d(su)}{u} = \frac{dE}{\frac{1}{2}u^2}$$

From this:

$$\frac{ds}{1} = ds = \frac{1}{u} (dsu + sdu) = ds + sdu$$

$$\Rightarrow sdu = 0 \Rightarrow du = 0 \Rightarrow u = \text{const}$$

$$\frac{ds}{1} = ds = \frac{dE}{\frac{1}{2}u^2} = \frac{1}{\frac{1}{2}u^2} d\left(\frac{1}{2}su^2 + \frac{p}{\gamma-1}\right) =$$

$$= \frac{1}{\frac{1}{2}u^2} \left[ \frac{1}{2}u^2 ds + sdu + \frac{dp}{\gamma-1} \right]$$

$$= ds + \frac{2s}{u} du + \frac{2dp}{(\gamma-1)u^2}$$

$\underbrace{\quad}_{=0}$

$$\Rightarrow dp = 0 \Rightarrow p = \text{const}$$

$\Rightarrow$   $p$  and  $u$  are constant across the contact wave

## ii) Rarefaction Wave

Is associated with the  $\underline{k}^{(1)}$ ,  $\underline{k}^{(3)}$  eigenvectors.  
Consider the entropy formulation:

$$\underline{w} = (s, u, p)^T, \quad s = C_V \ln(p/\rho^{\gamma}) + C_0$$

and  $\lambda_1 = u - a$ ,  $\lambda_2 = u$ ,  $\lambda_3 = u + a$

$$\underline{k}^{(1)} = \begin{pmatrix} 1 \\ -a/\rho \\ 0 \end{pmatrix}, \quad \underline{k}^{(2)} = \begin{pmatrix} -\partial p / \partial s \\ 0 \\ a^2 \end{pmatrix}, \quad \underline{k}^{(3)} = \begin{pmatrix} 1 \\ a/\rho \\ 0 \end{pmatrix}$$

For the left rarefaction wave:  $\lambda_1$ ,  $\underline{k}^{(1)}$

Generalised Riemann Invariants:

$$\frac{ds}{1} = \frac{du}{-a/\rho} = \frac{ds}{0}$$

$$\rightarrow ds \text{ must } \rightarrow 0 \Rightarrow s = \text{const}$$

$$du = -a/\rho ds \Rightarrow u + \int \frac{a}{\rho} ds = \text{const}$$

Since  $s = \text{const} = C_V \ln(p/\rho^{\gamma}) + C_0$ :

$$\ln(p) - \ln(\rho^{\gamma}) = \text{const}$$

$$p = C \rho^{\gamma}$$

$$\Rightarrow a = \sqrt{\frac{dp}{ds}} = \sqrt{C \gamma \rho^{\gamma-1}}$$

$$\Rightarrow \int \frac{a}{\rho} ds = \int \sqrt{C \gamma} \rho^{\frac{\gamma-1}{2}-1} ds = \int \sqrt{C \gamma} \rho^{\frac{\gamma-3}{2}} ds$$

$$= \frac{2}{\gamma-1} \sqrt{C \gamma} \rho^{\frac{\gamma-1}{2}} = \frac{2a}{\gamma-1}$$

$$\Rightarrow \left[ \begin{array}{l} u + \frac{2a}{\gamma-1} = \text{const} \\ s = \text{const} \end{array} \right]$$

Similarly for the right wave:

$$\left[ \begin{array}{l} u - \frac{2a}{\gamma-1} = \text{const} \\ s = \text{const} \end{array} \right]$$

### iii) Shock Waves

In the context of 1D Euler equations, shock waves are discontinuous waves associated with the genuinely non-linear fields 1 and 3.

All three quantities  $S$ ,  $u$  and  $p$  change across a shock wave.

Consider the  $K^{(3)}$  characteristic field and assume the corresponding wave is a right-facing shock wave travelling at a constant speed  $S_3$ .

We denote the state ahead of the shock by  $\underline{w}_R = (S_R, u_R, p_R)^T$  and the state behind the shock by  $\underline{w}_* = (S_*, u_*, p_*)^T$ .

	$\rightarrow S_3$	
$S_*$	$S_R$	$S_*$
$u_*$	$u_R$	$\hat{u}_*$
$p_*$	$p_R$	$p_*$

It is convenient to transform the problem to a new frame of reference, comoving with the shock:

Now use Rankine-Hugoniot:

$$\underline{F}_R - \underline{F}_* = S(\underline{U}_R - \underline{U}_*)$$

with  $\underline{U} = (S, \rho u, E)^T$ ,  $E = (\rho u, \rho u^2 + p, u(E+p))$

1st equ:

$$\rho_R u_R - \rho_* u_* = S \rho_R - S \rho_*$$

$$\Rightarrow \rho_R (u_R - S) = \rho_* (u_* - S)$$

$$\Rightarrow \boxed{\rho_R \hat{u}_R = \rho_* \hat{u}_*}$$

2nd equ:

$$\rho_R u_R^2 + p_R - \rho_* u_*^2 - p_* = S \rho_R u_R - S \rho_* u_*$$

$$\rho_R (u_R^2 - u_R S) + p_R - \rho_* (u_*^2 - u_* S) - p_* = 0$$

Use 1st equ:

$$\rho_R (u_R - S) - \rho_* (u_* - S) = 0$$

$$\Rightarrow S \rho_R (u_R - S) - \rho_* (u_* - S) = 0$$

$$= \rho_R (u_R S - S^2) - \rho_* (u_* S - S^2) = 0$$

Subtract this from the second equation:

$$\rho_R (u_R^2 - 2u_R S + S^2) + p_R - \rho_* (u_*^2 - 2u_* S + S^2) - p_* = 0$$

$$\Rightarrow \boxed{\rho_R \hat{u}_R^2 + p_R = \rho_* \hat{u}_*^2 + p_*}$$

Third equation:

For both R and \* indices, we have:

$$\begin{aligned}
 u(E+p) - SE &= E(u-s) + up = \\
 &= \hat{u} E + up = \hat{u} \left( \frac{1}{2} S u^2 + Se \right) + up = \\
 &= \hat{u} \left( \frac{1}{2} S u^2 + Se - S u S + \frac{1}{2} S S^2 + S u S - \frac{1}{2} S S^2 \right) + up - S_p + S_p \\
 &= \hat{u} \left( \frac{1}{2} S (u^2 - 2uS + S^2) + Se \right) + (u-s)p + \hat{u} (S u S - \frac{1}{2} S S^2) + S_p \\
 &= \hat{u} \left( \frac{1}{2} S \hat{u}^2 + Se \right) + \hat{u} p + S (S u \hat{u} - \frac{1}{2} S S \hat{u} + p) \\
 &= \hat{u} (\hat{E} + p) + S (S \hat{u} (u-s) + p + \frac{1}{2} S \hat{u} S) \\
 &= \hat{u} (\hat{E} + p) + S (S \hat{u}^2 + p) + \frac{1}{2} S^2 S \hat{u}
 \end{aligned}$$

From the first two equations we know:

$$S_R \hat{u}_R = S_* \hat{u}_*$$

$$S_R \hat{u}_R^2 + p_R = S_* \hat{u}_*^2 + p_*$$

Now use that on Rankine Hugoniot:

$$u_R (E_R + p_R) - u_* (E_* + p_*) = S E_R - S E_*$$

$$\Rightarrow u_R (E_R + p_R) - S E_R = u_* (E_* + p_*) - S E_*$$

$$\Rightarrow \hat{u}_R (\hat{E}_R + p_R) + S (S \hat{u}_R^2 + p_R) + \frac{1}{2} S^2 S_R u_R =$$

$$= \hat{u}_* (\hat{E}_* + p_*) + S (S \hat{u}_*^2 + p_*) + \frac{1}{2} S^2 S_* u_*$$

equal on both sides
equal on both sides

$$\Rightarrow \boxed{\hat{u}_R (\hat{E}_R + p_R) = \hat{u}_* (\hat{E}_* + p_*)}$$

The third equation can be re-written:

$$\begin{aligned} \hat{u}(\hat{E} + p) &= \hat{u}\left(\left(\frac{1}{2}S\hat{u}^2 + e\right) + p\right) = \\ &= \hat{u}S\left(\frac{1}{2}\hat{u}^2 + (e + p/S)\right) \\ &= \hat{u}S\left(\frac{1}{2}\hat{u}^2 + h\right) \end{aligned}$$

with  $h = e + p/S$  the specific enthalpy. The equation is then

$$\hat{u}_R S_R \left(\frac{1}{2}\hat{u}_R^2 + h_R\right) = \hat{u}_* S_* \left(\frac{1}{2}\hat{u}_*^2 + h_*\right)$$

with  $\hat{u}_R S_R = \hat{u}_* S_*$ :

$$\Rightarrow \frac{1}{2}\hat{u}_R^2 + h_R = \frac{1}{2}\hat{u}_*^2 + h_*$$

To find an expression for  $\hat{u}_*^2, \hat{u}_R^2$ , use the first two equations:

$$\begin{aligned} S_* \hat{u}_*^2 &= S_R \hat{u}_R^2 + p_R - p_* \\ &= \frac{(S_R \hat{u}_R)^2}{S_R} + p_R - p_* = \frac{S_*^2 \hat{u}_*^2}{S_R} + p_R - p_* \end{aligned}$$

$$S_* \hat{u}_*^2 \left(1 - \frac{S_*}{S_R}\right) = S_* \hat{u}_*^2 \left(\frac{S_R - S_*}{S_R}\right) = p_R - p_*$$

$$\Rightarrow \hat{u}_*^2 = \frac{S_R}{S_*} \frac{p_R - p_*}{S_R - S_*}$$

analogously:  $\hat{u}_R^2 = \frac{S_*}{S_R} \frac{p_R - p_*}{S_R - S_*}$

This gives us:  $\frac{1}{2}\hat{u}_R^2 + h_R = \frac{1}{2}\hat{u}_*^2 + h_*$

$$\begin{aligned} \rightarrow h_R - h_* &= \frac{1}{2}(\hat{u}_*^2 - \hat{u}_R^2) = \frac{1}{2} \frac{p_R - p_*}{S_R - S_*} \left(\frac{S_R}{S_*} - \frac{S_*}{S_R}\right) \\ &= \frac{1}{2} \frac{\Delta p}{\Delta S} \left(\frac{S_R^2 - S_*^2}{S_* S_R}\right) = \frac{1}{2} (p_* - p_R) \left(\frac{S_R + S_*}{S_* S_R}\right) \end{aligned}$$

We can use that result to get an expression for the specific internal energy:

$$h = e + p/s$$

$$h_* - h_R = \frac{1}{2} (p_* - p_R) \frac{s_* + s_R}{s_* s_R} = e_* + p_*/s_* - e_R - p_R/s_R$$

$$\Rightarrow e_* - e_R = \frac{1}{2} (p_* - p_R) \frac{s_* + s_R}{s_* s_R} + \frac{p_R}{s_R} - \frac{p_*}{s_*}$$

$$= \frac{1}{2} \frac{1}{s_* s_R} (p_* s_* + p_* s_R - p_R s_* - p_R s_R + 2p_R s_* - 2p_* s_R)$$

$$= \frac{1}{2} \frac{1}{s_* s_R} (p_* s_* - p_* s_R + p_R s_* - p_R s_R)$$

$$= \frac{1}{2} \frac{1}{s_* s_R} (p_* (s_* - s_R) + p_R (s_* - s_R))$$

$$= \frac{1}{2} \frac{1}{s_* s_R} (p_* + p_R) (s_* - s_R)$$

$$= \frac{1}{2} (p_* + p_R) \frac{s_* - s_R}{s_* s_R}$$

For ideal gases, we can now use  $e = \frac{p}{(\gamma-1)s}$

$$\text{Then } e_* - e_R = \frac{1}{\gamma-1} \left( \frac{p_*}{s_*} \right) - \frac{1}{\gamma-1} \left( \frac{p_R}{s_R} \right)$$

$$= \frac{1}{\gamma-1} \left( \frac{p_* s_R - p_R s_*}{s_* s_R} \right)$$

$$= \frac{1}{2} (p_* + p_R) \frac{s_* - s_R}{s_* s_R}$$

$$\Rightarrow \frac{\gamma-1}{2} (p_* + p_R) (s_* - s_R) = p_* s_R - p_R s_*$$



$$P^* S_R - P_R S^* = \frac{\gamma-1}{2} (P^* S^* - P^* S_R + P_R S^* - P_R S_R)$$

$$\begin{aligned} \Rightarrow \frac{\gamma-1}{2} (P^* S^* - P_R S_R) &= \frac{\gamma-1}{2} \left( \frac{2}{\gamma-1} P^* S_R - \frac{2}{\gamma-1} P_R S^* + \right. \\ &\quad \left. P^* S_R - P_R S^* \right) \\ &= \frac{\gamma-1}{2} \left( \frac{2+\gamma-1}{\gamma-1} P^* S_R - \frac{2+\gamma-1}{\gamma-1} P_R S^* \right) \\ &= \frac{\gamma-1}{2} \left( \frac{\gamma+1}{\gamma-1} P^* S_R - \frac{\gamma+1}{\gamma-1} P_R S^* \right) \end{aligned}$$

$$\Rightarrow P^* S^* + \frac{\gamma+1}{\gamma-1} P_R S^* = P_R S_R + \frac{\gamma+1}{\gamma-1} P^* S_R$$

$$S^* \left( P^* + \frac{\gamma+1}{\gamma-1} P_R \right) = S_R \left( P_R + \frac{\gamma+1}{\gamma-1} P^* \right)$$

$$\begin{aligned} \Rightarrow \frac{S^*}{S_R} &= \frac{P_R + \frac{\gamma+1}{\gamma-1} P^*}{P^* + \frac{\gamma+1}{\gamma-1} P_R} = \frac{1 + \frac{\gamma+1}{\gamma-1} \frac{P^*}{P_R}}{\frac{P^*}{P_R} + \frac{\gamma+1}{\gamma-1}} \\ &= \frac{\frac{\gamma-1}{\gamma+1} + \frac{P^*}{P_R}}{\frac{\gamma-1}{\gamma+1} \frac{P^*}{P_R} + 1} \end{aligned}$$

Or for  $\frac{P^*}{P_R}$ :

$$P^* S^* + \frac{\gamma+1}{\gamma-1} P_R S^* = P_R S_R + \frac{\gamma+1}{\gamma-1} P^* S_R$$

$$\Rightarrow P^* \left( S^* - \frac{\gamma+1}{\gamma-1} S_R \right) = P_R \left( S_R - \frac{\gamma+1}{\gamma-1} S^* \right)$$

$$\Rightarrow \frac{P^*}{P_R} = \frac{S_R - \frac{\gamma+1}{\gamma-1} S^*}{S^* - \frac{\gamma+1}{\gamma-1} S_R} = \frac{1 - \frac{\gamma+1}{\gamma-1} \frac{S^*}{S_R}}{\frac{S^*}{S_R} - \frac{\gamma+1}{\gamma-1}}$$

This establishes a useful relation between the density and pressure ratios.

The shock speed  $S_3$  can be related to the pressure and density ratios. To demonstrate this, we introduce the Mach numbers:

$$M_R = \frac{U_R}{a_R} \quad M_S = \frac{S_3}{a_R}$$

$$\text{with } U_R^2 = \frac{S_*}{S_R} \left[ \frac{p_R - p_*}{S_R - S_*} \right] = a_R^2 (M_R - M_S)^2 =$$

$$= \frac{\gamma p_R}{S_R} (M_R - M_S)^2$$

$$= \frac{S_*}{S_R} \frac{p_R}{S_R} \left[ \frac{1 - p_*/p_R}{1 - S_*/S_R} \right]$$

$$\text{Let } \Delta M \equiv (M_R - M_S)$$

$$\Rightarrow \frac{S_*}{S_R} = \gamma (M_R - M_S)^2 \left[ \frac{1 - S_*/S_R}{1 - p_*/p_R} \right] =$$

$$= \gamma \Delta M^2 \frac{1 - S_*/S_R}{1 - \frac{\gamma+1}{\gamma-1} \frac{S_*}{S_R}} =$$

$$\frac{S_*}{S_R} - \frac{\gamma+1}{\gamma-1}$$

$$= \gamma \Delta M^2 \frac{(1 - S_*/S_R) \left( \frac{S_*}{S_R} - \frac{\gamma+1}{\gamma-1} \right)}{\frac{S_*}{S_R} - \frac{\gamma+1}{\gamma-1} - 1 + \frac{\gamma+1}{\gamma-1} \frac{S_*}{S_R}}$$

$$= \gamma \Delta M^2 \frac{(1 - S_*/S_R) \left( \frac{S_*}{S_R} - \frac{\gamma+1}{\gamma-1} \right)}{\frac{2\gamma}{\gamma-1} \left( \frac{S_*}{S_R} - 1 \right)}$$

$$= \Delta M^2 \frac{\frac{\gamma+1}{\gamma-1} - \frac{S_*}{S_R}}{2/(\gamma-1)}$$

$$\frac{S^*}{S_R} \left( 1 + \frac{\Gamma^{-1}}{2} \Delta M^2 \right) = \frac{\Delta M^2 \frac{\Gamma+1}{\Gamma-1}}{2/\Gamma-1} = \frac{\Delta M^2 (\Gamma+1)}{2}$$

$$\frac{S^*}{S_R} = \frac{\Delta M^2 (\Gamma+1)}{2 \left( 1 + \frac{\Gamma^{-1}}{2} \Delta M^2 \right)} = \frac{(\Gamma+1)(M_R - M_S)^2}{(\Gamma-1)(M_R - M_S)^2 + 2}$$

And for  $\frac{P^*}{P_R}$ :

$$\frac{P^*}{P_R} = \frac{1 - \frac{\Gamma+1}{\Gamma-1} \frac{S^*}{S_R}}{\frac{S^*}{S_R} - \frac{\Gamma+1}{\Gamma-1}} = \frac{1 - \frac{\Gamma+1}{\Gamma+1} \frac{(\Gamma+2) \Delta M^2}{(\Gamma-1) \Delta M^2 + 2}}{\frac{(\Gamma-1) \Delta M^2}{(\Gamma-1) \Delta M^2 + 2} - \frac{\Gamma+1}{\Gamma-1}}$$

$$= \frac{(\Gamma-1)[(\Gamma-1) \Delta M^2 + 2] - (\Gamma+1)^2 \Delta M^2}{(\Gamma-1)[(\Gamma-1) \Delta M^2 + 2]}$$

$$= \frac{(\Gamma-1)(\Gamma+2) \Delta M^2 - (\Gamma+1)[(\Gamma-1) \Delta M^2 + 2]}{(\Gamma-1)[(\Gamma-1) \Delta M^2 + 2]}$$

$$= \frac{[\Gamma^2 - 2\Gamma + 1 - \Gamma^2 - 2\Gamma - 1] \Delta M^2 + 2(\Gamma-1)}{(\Gamma-1)[(\Gamma-1) \Delta M^2 + 2]}$$

$$= \frac{-4\Gamma \Delta M^2 + 2(\Gamma-1)}{(\Gamma-1)[(\Gamma-1) \Delta M^2 + 2]}$$

$$= \frac{-4\Gamma \Delta M^2 + 2(\Gamma-1)}{-2(\Gamma+1)} = \frac{2\Gamma (M_R - M_S)^2 - (\Gamma-1)}{\Gamma+1}$$

These formulae allow us to relate the shock speed  $S_3$  to the pressure and density ratios:

$$\frac{p^*}{p_R} = \frac{2\gamma (M_R - M_S)^2 - (\gamma - 1)}{(\gamma + 1)}$$

$$\Rightarrow (M_R - M_S) = \sqrt{\frac{\gamma + 1}{2\gamma} \frac{p^*}{p_R} + \frac{\gamma - 1}{2\gamma}} \quad \leftarrow \begin{array}{l} M_S > M_R: \\ \text{Condition for shock} \\ \text{to form} \end{array}$$

with  $M_R = \frac{u_R}{a_R}$ ;  $M_S = \frac{S_3}{a_R}$ :

$$S_3 = u_R + a_R \sqrt{\frac{\gamma + 1}{2\gamma} \frac{p^*}{p_R} + \frac{\gamma - 1}{2\gamma}}$$

Furthermore, using  $\hat{u}_* s_* = \hat{u}_R s_R$ :

$$\hat{u}_* = \hat{u}_R \frac{s_R}{s_*} = (u_R - S_3) \frac{s_R}{s_*} = (u_* - S_3)$$

$$\Rightarrow u_* = (u_R - S_3) \frac{s_R}{s_*} + S_3 = \underline{\underline{\left(1 - \frac{s_R}{s_*}\right) S_3 + u_R \frac{s_R}{s_*}}}$$

giving us an expression for the particle velocity  $u_*$  after the shock wave.

The derivation for the left-facing  $S_1$  shockwaves are completely analogous.