

# Circular Speed

Newton derived two useful theorems concerning shells of matter:

1) A body inside a spherical shell of matter experiences no net gravitational force from the shell.

2) A body lying outside a closed spherical shell experiences a gravitational force which is the same as if all the matter in the shell were concentrated at a point at its center.

A circular mass distribution can therefore be characterized in terms of a circular speed  $v_{\text{circ}}$ , which is the speed a test particle would have in a

Circular orbit at radius  $r$ .

With a spherically symmetric potential  $\Phi(\underline{r}) = \Phi(r)$ ,  
and using polar coordinates

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \end{pmatrix}$$

Then the Lagrangian is

$$\begin{aligned} \mathcal{L} &= T - V = \frac{1}{2}(\dot{x}^2 + \dot{y}^2) - \Phi(x, y) \\ &= \frac{1}{2}(\dot{r}^2 + (r\dot{\varphi})^2) - \Phi(r) \end{aligned}$$

The Euler-Lagrange equations of motion  
are:

$$\frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{q}} \right) - \frac{\partial \mathcal{L}}{\partial q} = 0, \quad q = r, \varphi$$

$$\Rightarrow \frac{d}{dt} \left( \frac{1}{2} \cdot 2\dot{r} \right) - \frac{1}{2} \cdot 2r \dot{\varphi}^2 + \frac{\partial \Phi}{\partial r} = 0$$

$$\Rightarrow \boxed{\ddot{r} - r\dot{\varphi}^2 + \frac{\partial \Phi}{\partial r} = 0}$$

$$\frac{d}{dt} \left( \frac{1}{2} r^2 \cdot 2\dot{\varphi} \right) - 0 = 0$$

$$\Rightarrow \boxed{\frac{d}{dt} (r^2 \dot{\varphi}) = 0}$$

If we assume circular motion, we have

$$dr = 0 \Rightarrow \dot{r} = \frac{dr}{dt} = 0$$

$$\text{Then from } \frac{d}{dt}(r^2\dot{\varphi}) = 0 = 2r \underbrace{\frac{dr}{dt}}_{=0} + r^2\ddot{\varphi}$$

$$\Rightarrow \ddot{\varphi} = 0$$

[ Alternatively, you can just demand that the rotation speed  $\dot{\varphi}$  is constant, and skip the entire Euler-Lagrange step ]

Then the expression for the circular speed can be obtained through

$$\underline{r}_c = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \end{pmatrix}$$

$$\underline{v}_c = \dot{\underline{r}}_c = r \begin{pmatrix} -\sin \varphi \\ \cos \varphi \end{pmatrix} \dot{\varphi}$$

$$\begin{aligned} \underline{a}_c = \dot{\underline{v}}_c &= r \begin{pmatrix} -\cos \varphi \\ -\sin \varphi \end{pmatrix} \dot{\varphi}^2 + r \begin{pmatrix} -\sin \varphi \\ \cos \varphi \end{pmatrix} \underbrace{\ddot{\varphi}}_{=0} \\ &= -\underline{r}_c \dot{\varphi}^2 = -\frac{\|(r\dot{\varphi})\|^2}{r} \underline{e}_r = -\frac{\|\underline{v}_c\|^2}{r} \underline{e}_r = -\frac{v_c^2}{r} \underline{e}_r \end{aligned}$$

Using Newton's first law:

$$\underline{F} = m \underline{a} = -m \underline{\nabla} \phi = -m \frac{\partial \phi}{\partial r} \quad \text{spherical symmetry}$$

$$\Rightarrow \underline{a} = -\frac{\partial \phi}{\partial r} = \frac{v_c^2}{r}$$

For the gravitational potential in spherical symmetry, we find an expression for the  $\frac{\partial \phi}{\partial r}$  via the Poisson equation:

$$\Delta \phi = 4\pi G \rho(r) = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \phi}{\partial r} \right) \quad \text{in sph. sym.}$$

$$\Rightarrow \partial \left( r^2 \frac{\partial \phi}{\partial r} \right) = -4\pi G \rho(r) r^2 \partial r$$

$$\Rightarrow r^2 \frac{\partial \phi}{\partial r} = -4\pi G \int \rho(r) r^2 dr =$$

$$= -G \int 4\pi \rho(r) r^2 dr = -G \int \rho(\underline{x}) dV =$$

$$= -G M(<r)$$

$$\Rightarrow \frac{\partial \phi}{\partial r} = \frac{-GM(<r)}{r^2}$$

This finally gives us:

$$\underline{a} = -\frac{\partial\phi}{\partial r} = \frac{v_c^2}{r} = + \frac{GM(r)}{r^2}$$

$$\Rightarrow v_c^2 = + \frac{GM(r)}{r}$$

